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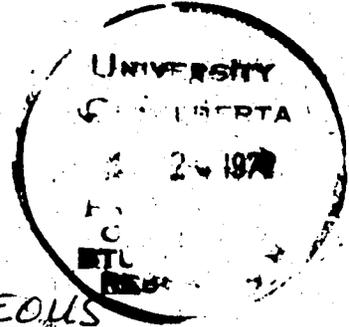


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ANALYSIS OF HEAT AND WATER TRANSPORT IN  
UNSATURATED-SATURATED POROUS MEDIA

by

MARIOS A. SOPHOCLEOUS

(C)

A THESIS

SUBMITTED TO THE FACULTY OF GRADUATE STUDIES AND RESEARCH  
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DEPARTMENT OF GEOLOGY

EDMONTON, ALBERTA

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THE UNIVERSITY OF ALBERTA  
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## ABSTRACT

It is possible to model mathematically the simultaneous transport of heat and water in liquid and vapor phases in unsaturated-saturated porous media. The theoretical development of the model is an adaptation and extension of the Philip and de Vries' non-isothermal model based on the more general pressure head approach. A methodology for subsurface coupled heat and water transport suitable for field applications is proposed. This methodology involves calculation of ratios of transport parameters in combination with a detailed heat flux equation, the introduction of a new approach for the calculation of liquid thermal diffusion coefficients and the extension of the Philip and de Vries-type theory to saturated regions.

A general and versatile one-dimensional computer simulation program for modeling coupled non-isothermal transport is developed based on a unified unsaturated-saturated approach. Temperature, pressure head and water content, as well as all relevant transport coefficients and fluxes of head and fluid components are predicted by the model. This model is successfully verified with field and complementary laboratory data collected for this purpose. A variety of field and laboratory methods and instrumentation was used to collect this array of data. The

4

equipment for thermal conductivity measurements was redesigned to meet the requirements of this study. An error analysis is used to identify the data causing the greatest amount of error.

The influence of coupling on diurnal subsurface moisture and heat transfer can be evaluated by comparing the transient non-isothermal numerical solutions to the heat and water transport problem under varying top boundary conditions. The results confirm that coupling does not appreciably influence the temperature field but does affect the evaporation and subsurface moisture fluxes. Thus, depending on the direction of the temperature and pressure head gradients, the evaporation and subsurface water fluxes may have been overestimated or underestimated significantly using an isothermal model. The analysis of transport coefficients indicated that thermally induced moisture movement becomes dominant at very low water contents. It is suggested that for long term simulations under extended drying conditions, the coupled non-isothermal model should be preferred in studying the long range seasonal influences on water transport. The non-isothermal theory can be applied to calculate evaporation from dry land surfaces. Simulation results show a very interesting cyclical evaporation pattern.

The theoretical and field analysis pointed out difficulties and deficiencies of non-isothermal models, such

as the calculation of flow enhancement factors and liquid thermal diffusion coefficients, the field performance of thermocouple psychrometers and others. Areas of hydrogeological interest such models, such as the subsurface waste heat disposal, thermal influences on the migration of radionuclides and other environmental and hydrological problems are pointed out.

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## LIST OF SYMBOLS<sup>1</sup>

Upper case Roman letters

A, D, E, F, G, H, H', L, M and U represent various matrices and vectors in the finite difference formulation.

$A_i, B_i, C_i, \bar{A}_i, \bar{B}_i, \bar{C}_i, A'_i, B'_i, C'_i, \bar{A}'_i, \bar{B}'_i, \bar{C}'_i, X_i,$  and  $Y_i$  are abbreviations associated with equations (4-4).

C	volumetric heat capacity of a moist porous medium (cal cm <sup>-3</sup> C <sup>-1</sup> )
$C_{mm}$	volumetric heat capacity of mineral matter (cal cm <sup>-3</sup> C <sup>-1</sup> )
$C_o$	volumetric heat capacity of organic matter (cal cm <sup>-3</sup> C <sup>-1</sup> )
$C_w$	volumetric heat capacity of water (cal cm <sup>-3</sup> C <sup>-1</sup> ) ;
$C_w$	specific water capacity (cm <sup>-1</sup> )
%C	percentage of clay
D	diffusion coefficient in moist soil of a gas insoluble in water (cm <sup>2</sup> sec <sup>-1</sup> )
D	damping depth (cm)
D	diameter of piezometer (cm)
$D_a$	molecular diffusion coefficient of water vapor in air (cm <sup>2</sup> sec <sup>-1</sup> )
$D_L$	coefficient for heat transport by pressure head gradients (cal cm <sup>-2</sup> sec <sup>-1</sup> )
$D_o$	diffusion coefficient in air of a gas insoluble in water (cm <sup>2</sup> sec <sup>-1</sup> )
$D_s$	diffusion coefficient in dry soil of a gas insoluble in water (cm <sup>2</sup> sec <sup>-1</sup> )
$D_\theta$	isothermal water diffusivity

<sup>1</sup> Additional symbols associated with the computer simulation program are included in Appendix E.

	( $\text{cm}^2 \text{ sec}^{-1}$ )
$D_{0l}$ , $D_{0v}$	liquid and vapor components of $D_0$ , respectively ( $\text{cm}^2 \text{ sec}^{-1}$ )
$D_T$	thermal water diffusivity ( $\text{cm}^2 \text{ sec}^{-1} \text{ C}^{-1}$ )
$D_{Tl}$ , $D_{Tv}$	liquid and vapor components of $D_T$ , respectively ( $\text{cm}^2 \text{ sec}^{-1} \text{ C}^{-1}$ )
$D_v$	diffusion coefficient of water vapor in a porous medium ( $\text{cm}^2 \text{ sec}^{-1}$ )
$E$	voltage input ( V )
$E_a$	absolute error
$EV$ or $E$	evaporation flux or rate ( $\text{cm sec}^{-1}$ )
$F$	generalized storage coefficient - $C_w$ in the unsaturated domain, $S_s$ in the saturated zone ( $\text{cm}^{-1}$ )
$F$	a measured quantity in error analysis
GHP	guarded hot plate
$H$	total heat content of a unit of volume of moist porous medium ( $\text{cal cm}^{-3}$ )
$I$	rate of irrigation application ( $\text{cm sec}^{-1}$ )
$I$	electric current ( A )
$J$	time step index
$J'$	mechanical equivalent of heat ( cal )
$K$ or $K_{\psi l}$	liquid hydraulic conductivity ( $\text{cm sec}^{-1}$ )
$K_{\psi}$	total water hydraulic conductivity ( $\text{cm sec}^{-1}$ )
$K_{\psi v}$	vapor component of $K_{\psi}$ ( $\text{cm sec}^{-1}$ )
$K_r$	relative hydraulic conductivity ( dimensionless )
$K_{sat}$	saturated hydraulic conductivity ( $\text{cm sec}^{-1}$ )

L	intake length of piezometer ( cm )
L	total length of subsurface profile studied ( cm )
L'	latent heat of vaporization of water ( cal gm <sup>-1</sup> )
L <sub>wq</sub> , L <sub>qw</sub> , L <sub>ww</sub> , L <sub>qq</sub>	phenomenological coefficients
M	molecular weight of water vapor ( gm mole <sup>-1</sup> )
N	total number of items
%OM	percentage of organic matter
P	total gas pressure ( cm H <sub>2</sub> O or atm )
P <sub>o</sub>	standard atmospheric pressure ( atm )
Q	heat input to the thermal conductivity probe per unit length ( cal cm <sup>-1</sup> sec <sup>-1</sup> or w cm <sup>-1</sup> )
R	universal gas constant ( erg mole <sup>-1</sup> K <sup>-1</sup> )
R	radius of piezometer ( cm )
R	rate of effective precipitation ( cm sec <sup>-1</sup> )
R, R'	resistance and resistance per cm of the heating element, respectively ( Ω , Ω cm <sup>-1</sup> )
S	shape factor ( cm )
S	slope of the temperature curve in thermal conductivity measurements ( C )
S <sub>e</sub>	effective saturation ( dimensionless )
S <sub>r</sub>	residual saturation ( dimensionless )
S <sub>s</sub>	specific storage ( cm <sup>-1</sup> )
S <sub>w</sub>	water saturation ( dimensionless )
%S	percentage of sand
T	temperature or absolute temperature ( C or K )

$T'$	basic time lag ( sec )
$T_o, T_{ref}$	arbitrary reference temperature ( C )
$V$	microscopic vector fluid velocity ( $cm\ sec^{-1}$ )
$W$	heat of wetting ( $cal\ gm^{-1}$ )
Lower case Roman letters	
$a$	volumetric air content ( dimensionless )
$b, b'$	column vectors of known quantities in finite difference formulation
$c$	specific heat capacity of the porous medium ( $cal\ gm^{-1}\ C^{-1}$ )
$c_l$	specific heat of liquid water ( $cal\ gm^{-1}\ C^{-1}$ )
$c_v$	specific heat of water vapor ( $cal\ gm^{-1}\ C^{-1}$ )
$c_{mm}$ or $c_s$	specific heat of mineral matter ( $cal\ gm^{-1}\ C^{-1}$ )
$c_o$	specific heat of organic matter ( $cal\ gm^{-1}\ C^{-1}$ )
$f$	pore geometry factor
$g$	acceleration of gravity ( $cm\ sec^{-2}$ )
$h$	soil relative humidity ( dimensionless )
$i$	unit vector in the positive z direction
$k$	intrinsic permeability ( $cm^2$ )
$p$	point fluid pressure ( $dyne\ cm^{-2}$ )
$p_v$	water vapor pressure ( $cm\ H_2O$ )
$p_v^s$	saturated water vapor pressure ( $cm\ H_2O$ )
$q_w$	total water flux density ( $gm\ cm^{-2}\ sec^{-1}$ )
$q_l, q_v$	liquid and vapor components of $q_w$

	respectively ( gm cm <sup>-2</sup> sec <sup>-1</sup> )
$q_h$	total heat flux ( cal cm <sup>-2</sup> sec <sup>-1</sup> )
$q_{cd}, q_{cv}$	conductive and convective components of $q_h$ , respectively ( cal cm <sup>-2</sup> sec <sup>-1</sup> )
$r^{-1}$	mean curvature of the water-air interface ( cm <sup>-1</sup> )
$r$	$\Delta t / \Delta z^2$
$t$	time ( sec )
$x$	column vector of unknown variables in finite difference formulation
$x_t$	input data
$x_{mm}$	volumetric mineral matter fraction
$x_o$	volumetric organic matter fraction
$y$	distance from the water table to the water level in the piezometer ( cm )
$z$	depth
$w$	bottom boundary water flux ( cm sec <sup>-1</sup> )
Greek letters	
$\alpha$	tortuosity ( dimensionless )
$\alpha$	thermal diffusivity ( cm <sup>2</sup> sec <sup>-1</sup> )
$\alpha'$	organic matter fraction by weight
$\gamma$	temperature coefficient of surface tension ( C <sup>-1</sup> )
$\Delta$	difference operator
$\Delta x_i$	error operator on input $x_i$
$\epsilon$	small positive number
$\zeta$	ratio of average temperature gradient in air-filled pores to the overall temperature gradient ( dimensionless )
$\eta$	exponent in equation ( 3-8 )
$\theta$	volumetric water content

	( dimensionless )
$\theta_l, \theta_v$	volumetric liquid and vapor components of $\theta$ , respectively
$\theta_x$	volumetric moisture content at which liquid continuity first occurs in the porous medium
$\lambda$	apparent thermal conductivity ( cal cm <sup>-1</sup> sec <sup>-1</sup> C <sup>-1</sup> )
$\lambda'$	pore size distribution index
$\lambda^*$	thermal conductivity not including convection of fluids ( cal cm <sup>-1</sup> sec <sup>-1</sup> C <sup>-1</sup> )
$\mu$	water viscosity ( gm cm <sup>-1</sup> sec <sup>-1</sup> or poise )
$\nu$	mass flow factor ( dimensionless )
$\xi$	liquid-assisted vapor enhancement factor ( dimensionless )
$\pi$	3.14 ( constant )
$\rho$ or $\rho_l$	liquid water density ( gm cm <sup>-3</sup> )
$\rho_b$	bulk density ( gm cm <sup>-3</sup> )
$\rho_{mm}$ or $\rho_s$	particle density ( gm cm <sup>-3</sup> )
$\rho_o$	organic matter density ( gm cm <sup>-3</sup> )
$\rho_v$	water vapor density ( gm cm <sup>-3</sup> )
$\rho(\lambda)$	spectral radius
$\sigma$	water-air interfacial tension ( dyne cm <sup>-1</sup> )
$\Sigma$	summation sign
$\phi$	porosity
$\phi_v$	viscous dissipation function ( sec <sup>-2</sup> )
$\Phi$	hydraulic potential ( cm H <sub>2</sub> O )
$\Psi$	hydraulic head ( cm H <sub>2</sub> O )
$\Psi_b$	air entry or bubbling pressure ( cm H <sub>2</sub> O )

$\omega$	radial frequency ( rad sec <sup>-1</sup> )
$\omega$	relaxation factor
Other notation	
$\nabla$	gradient operator
$D/Dt$	substantial time derivative
$i, j$	space and time indices when subscripts and superscripts, respectively
$O( )$	order of ( )
$\sim$	approximately equal to
$-$	mean value when superscript
$=$	tensor quantity when superscript
$   $	absolute value

## CHAPTER 1

### STATEMENT OF THE PROBLEM

In recent years, there has been considerable and varied research interest in problems relating to the simultaneous transfer of heat and mass in flow systems. Although this progress is visible in a broad range of scientific disciplines (Whitaker, 1977; Rossen and Hayakawa, 1977; de Vries, 1975; Guymon and Luthin, 1974; Klute, 1973, Harlan, 1973; Nielsen et al., 1972; Keey, 1972; Fulford, 1969 ), there is little evidence that this work is making an impact on hydrogeological research (Stallman, 1964, 1967 ). However there are a number of practical problems that would be of interest to the hydrogeologist concerned with thermal influences on the subsurface flow regime, for example, the migration of radionuclides away from subsurface waste management sites in dry desert regions; hydrothermal convection in porous media; subsurface waste heat disposal; evaporation from land surfaces; seasonal fluctuations of the water table in cold environments; natural and artificial recharge problems; systems for land treatment of waste water involving a surface soil saturation followed by evaporative drying; underground storage of cryogenic fluids and heat storage in aquifers; laying of pipelines in cold regions and other frost problems; and generally the subsurface hydrology

of arid, semiarid, as well as cold regions.

Although problems involving the simultaneous water and heat transport have been studied extensively, many aspects are not yet well understood. The fact that different transfer mechanisms operate simultaneously, and often in opposite directions, poses serious difficulties in the development of a suitable mathematical framework and analytical methodologies.

Let us now examine some of the reasons why the problem of the simultaneous movement of water and heat is so complex. Transfer of liquid occurs mainly as a result of gravity, external pressure forces, capillary forces, sorption forces and electrical forces (de Vries, 1965; Nerpin and Globus, 1969). Transfer of vapor is governed by several mechanisms, for example, vapor diffusion under the influence of vapor concentration differences and flow under the influence of external pressure, gravity and friction at the liquid-vapor interfaces. Heat is transported by conduction, radiation and convection (including sensible heat transfer by liquid and vapor movement, as well as latent heat transfer by vapor movement). The complicated internal geometry of the porous media adds further complexities to the liquid-vapor-heat transfer. In addition to these difficulties, it should be noted that even basic quantities such as the soil water potential or the hydraulic and thermal conductivities as functions of moisture content

and temperature are not easy to measure.

In the past, particular mechanisms of moisture and heat transfer in porous media have been emphasized while others have been totally ignored (Harmathy, 1969; Young, 1969; Whitney and Porterfield, 1968; King, 1969; Matthes and Bowen, 1963; Wiegand and Taylor, 1961; Cary, 1961). In most cases, this tendency to emphasize only some of the mechanisms has been adequate for particular situations. However, continued reliance on simplified analyses has led to contradictions and difficulties in generalizing to other cases (Fulford, 1969).

In general, the movement of water and heat in porous media may be analysed using three levels of analysis: molecular, microscopic and macroscopic. For the molecular level of analysis, one develops transport theories based on the movement of molecules. Statistical mechanical concepts might be used to overcome the difficulty of discontinuous media. At the microscopic level, one may utilize the continuous medium approach and examine the detailed behavior of fluids within the pores. An example of this approach is the application of the Navier-Stokes equation to the problem of finding the detailed fluid velocity pattern within the pores. The difficulty of this approach is in the complexity of the boundary conditions between the phases present. This difficulty may be circumvented by using a macroscopic level of analysis in which one replaces microscopic variables by

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their volume averages. These averages are taken over an elementary volume large enough to contain a representative assortment of pores, but also small enough to maintain approximately constant values of macroscopic variables within the element (Klute, 1969). Therefore, at this level of analysis, overall macroscopic values of physical properties of a representative volume element are introduced, such as hydraulic and thermal conductivities, diffusivities and volumetric heat capacities, among others. A study of the connection between the description of the transport processes on the microscopic and macroscopic levels provides further insight into the transport processes, especially with respect to the calculation of the macroscopic transport coefficients from appropriate microscopic or molecular aspects of the porous media.

Two main macroscopic models generally form the basis for predicting water and temperature distributions in porous media: the mechanistic model of Philip and de Vries (1957), based on diffusion and heat flow theory, which has been adapted for porous media; and the phenomenological approach based on irreversible thermodynamics (deGroot and Mazur, 1962; Prigogine, 1967; Fitts, 1962; Katchalsky and Curran, 1965; Hanley, 1969). In both these macroscopic theories, the principal problem is to express the microscopic phenomena of flow in proper macroscopic terms, insuring that those mechanisms of primary importance are included while those of secondary importance are neglected. This evaluation

of the relative significance of the mechanisms tends to be arbitrary depending on the interests and objectives of the researcher. Because the transfer mechanisms are not yet completely understood, more complex models -- which are presumably more correct in some details -- may not necessarily be more correct overall (Gupta and Churchill, 1973).

The paper published by Philip and de Vries (1957) consolidating most of the previous knowledge on the influence of temperature gradients on moisture movement laid the groundwork for a better understanding of simultaneous heat and water movement in the soil. The "simple" vapor diffusion theory based on the modified Fick's equation for porous media, predicted the vapor flux density as

$$q_v = -fD_{\alpha v} \nabla e_v = -D_v \nabla e_v \quad (1-1)$$

where

- $q_v$  is the vapor flux density ( gm/cm<sup>2</sup>/sec )
- $f = \alpha a$  is a pore geometry factor ( dimensionless )
- $\alpha$  is a tortuosity factor for diffusion of gases in porous media ( dimensionless )
- $a = \phi - \theta$  is the volumetric air content of the medium ( cm<sup>3</sup> air/cm<sup>3</sup> soil )
- $\phi$  is the porosity of the porous medium ( dimensionless )
- $\theta$  is the volumetric water content of the medium ( cm<sup>3</sup> water/cm<sup>3</sup> soil )
- $D_{\alpha}$  is the molecular diffusion coefficient of water

vapor in air (  $\text{cm}^2/\text{sec}$  )

$\nu$  is a mass-flow factor arising from differences in boundary conditions governing air and vapor components ( dimensionless )

$\rho_v$  is the density of water vapor (  $\text{gm}/\text{cm}^3$  )

$D_v = fD_{a,v}$  is the diffusion coefficient of water vapor in the porous medium (  $\text{cm}^2/\text{sec}$  )

The transport of water vapor in soils under isothermal and solute-free conditions has been studied experimentally by Jackson (1964a, b, c, 1965) and Rose (1963a, b) who found that (1-1) describes isothermal water vapor transport in a satisfactory manner.

However (1-1), while adequate in isothermal conditions, underestimated the vapor flux significantly under temperature gradients, so that the ratio of the observed vapor flux to the value predicted by the simple diffusion theory ranged from about 4 to 18 (Philip and de Vries, 1957). Moreover, the above equation predicted a maximum vapor transfer at a much lower moisture content than the observed one.

The Philip and de Vries theory, in short, attempts to reconcile those discrepancies by taking into account the following two factors which were previously neglected. At low moisture content, the liquid phase is not continuous but is confined to small "islands" in the necks of the pores

between solid particles. Water vapor, however, does not necessarily flow around these water-filled necks, as was assumed in the simple diffusion theory. It can condense on one side of these "islands", move in the liquid phase through the liquid wedge and evaporate from the other side. These "islands" therefore act effectively in shortening the actual path length for vapor diffusion. Thus, the entire pore volume -- not just the air-filled porosity -- is effective in vapor transfer as a series-parallel process of flow through regions of vapor and liquid. This liquid-assisted vapor transfer at low moisture contents was confirmed experimentally under isothermal conditions by Rose (1963a, b, 1965). Such liquid-vapor interaction, therefore, is not restricted to temperature induced diffusion as Philip and de Vries suggested.

The second factor considered was the temperature gradient across air-filled pores within the porous medium. It was found that this gradient is several times greater than the average gradient across the porous medium as a whole, because of the lower thermal conductivity of the air. According to Philip and de Vries, the ratio of the temperature gradient in the air-filled pores to the overall temperature gradient may be as large as 3.2 for dry sand or higher (Woodside and Kuzmak, 1958). This represents a large increase in the thermally induced vapor flow because of the non-linear dependence of vapor pressure on temperature. This ratio can be measured according to the method of de Vries

(1963) when certain assumptions are made about the shape of the soil particles and their thermal conductivities.

Taking into account the above factors in the vapor flux equation, Philip and de Vries developed an approximate analysis which generally provides satisfactory agreement with the experimental observations. In order to describe thermally induced liquid movement, Philip and de Vries modified Darcy's equation by incorporating the temperature dependence of surface tension and its effect on matric potential. Table 1-1 summarizes the equations and parameters of the Philip and de Vries model (Philip and de Vries, 1957; de Vries, 1958; de Vries and Peck, 1958b; de Vries, 1975).

Some of the shortcomings of this analysis are that the temperature coefficient of the matric potential is greater than that of the surface tension of pure water considered by Philip and de Vries (Wilkinson and Klute, 1962; Cary, 1966; Jury and Miller, 1974); and that the Philip - de Vries model predicts zero thermally induced water flux in a saturated system, which has been shown not to be the case (Taylor and Cary, 1960; Corey and Kemper, 1961; Cary, 1966). From a practical viewpoint, the determination of the numerous soil and water parameters appearing in the equations of Table 1-1 makes the applicability of that model difficult.

Due to the fact that all transfer of heat and moisture occurs under non-equilibrium conditions, the concepts of the theory of non-equilibrium thermodynamics may be applied to

TABLE 1-1

Phillip and de Vries Model\*

(1-2)	$q_v/\rho = -D_{\theta v} \nabla \theta - D_{Tv} \nabla T$	vapor			} Flux Equations
(1-3)	$q_l/\rho = -D_{\theta l} \nabla \theta - D_{Tl} \nabla T - K_l$	liquid			
(1-4)	$q_w/\rho = -D_{\theta} \nabla \theta - D_{T} \nabla T - K_l$	water			
(1-5)	$q_h = -\lambda \nabla T - \rho L' D_{\theta v} \nabla \theta$	heat			
(1-6)	$\partial \theta / \partial t = \nabla (D_{\theta} \nabla \theta) + \nabla (D_{T} \nabla T) + \partial K / \partial z$	water			
(1-7)	$C \partial T / \partial t = \nabla (\lambda \nabla T) + \rho L' \nabla (D_{\theta v} \nabla \theta)$	heat			
(1-8)	$D_{\theta v} = f D_a \nu (Mg/RT) p_s^s \partial h / \partial \theta$	vapor moisture diffusivity			} Transport Coefficients
(1-9)	$D_{Tv} = \zeta f D_a \nu (Mg/RT) h dp_s^s / dT$	thermal vapor diffusivity			
(1-10)	$D_{\theta l} = K (\partial \psi / \partial \theta)_T$	liquid moisture diffusivity			
(1-11)	$D_{Tl} = \gamma \psi K$	thermal liquid diffusivity			
(1-12)	$D_{\theta} = D_{\theta v} + D_{\theta l}$	isothermal moisture diffusivity			
(1-13)	$D_T = D_{Tv} + D_{Tl}$	thermal moisture diffusivity			

\* See List of Symbols for the definitions of the various terms involved.

porous media (Groenevelt and Bolt, 1969; Kay and Groenevelt, 1974; Groenevelt and Kay, 1974 ). Such an approach was first attempted for porous solids by Luikov (1966) and Taylor and Cary (1960 ). For a system in which the simultaneous flow of heat and water only are considered, the appropriate fluxes may be written in a form similar to those derived by Philip and de Vries (Table 1-2 ). Jury (1973) presented a derivation and a comparison of such equations with those of Philip and de Vries.

The non-equilibrium thermodynamics approach is more general than the Philip and de Vries's one because it does not invoke any models or mechanisms and can be easily extended to include other influencing factors, such as osmotic or concentration gradients, among others. Certain theorems and restrictions allow the use of the Onsager reciprocity relation which states that

$$L_{wq} = L_{qw} \quad (1-18)$$

thus reducing the number of the unknown phenomenological coefficients (Table 1-2) by one. Cary (1963, 1964 ), among others, has demonstrated the validity of the Onsager relation in soils. The main problem with this phenomenological approach is that it does not provide insight into the transport coefficients, which makes their calculation difficult. Other limitations include the following: the domain for which the equations apply must be very close to equilibrium for the Onsager reciprocal relations to be valid. The condition for linear

TABLE 1-2

Non-equilibrium Thermodynamics Model\*

		water	Flux
(1-14)	$q_w = -L_{ww} \nabla \phi - L_{wq} \nabla (\ln T)$		
(1-15)	$q_h = -L_{qw} \nabla \phi - L_{qq} \nabla (\ln T)$	heat	Equations
(1-16)	$\partial \theta / \partial t = \nabla (L_{ww} \nabla \phi) + \nabla (L_{wq} \nabla (\ln T))$	water	Transient
(1-17)	$C \partial T / \partial t = \nabla (L_{qw} \nabla \phi) + \nabla (L_{qq} \nabla (\ln T))$	heat	Flow Equations

\* See List of Symbols for the definitions of the various terms involved.

phenomenological relations inherent in the general theory implies constant coefficients, a situation which does not correspond to real porous media flow conditions. Although in recent years significant progress has been made with regard to far-from-equilibrium thermodynamics (Glansdorff and Prigogine, 1971; Prigogine and Nicolis, 1977), such progress has not yet reached the area of flow through porous media.

The similarity of the equations in Tables 1-1 and 1-2 has prompted a comparison of the two previously discussed approaches by several researchers (Gee, 1966; Dirksen and Miller, 1966; Hadas, 1968; Cassel et al., 1969). However, these scientists were not able to demonstrate any clearcut advantage of one method over the other in approximating the observed data.

Analytical solutions of the non-linear transient equations (1-6) and (1-7) or (1-16) and (1-17) of Tables 1-1 and 1-2, respectively, are not available, unless it is assumed that the transport coefficients appearing in those equations are constant. This assumption is the basis for the analytical solutions presented by Crank (1956), de Vries and Peck (1958), Luikov and Michailov (1965), Husain et al. (1971). However, the transport coefficients -- like conductivities and diffusivities, which represent the thermophysical properties of porous media -- are not constant but depend on moisture content and temperature

(Klute, 1973). Therefore, numerical methods are the appropriate means for solving these non-linear equations.

The numerical approach, however, is limited by the lack of satisfactory measurements of porous media properties under non-isothermal conditions, which are needed for model descriptions (Fulford, 1969; Wooding and Morel-Seytoux, 1976; Whitaker, 1977). Therefore, the difficulty in comparing theoretical and model results with experimental data is the major obstacle to carrying out numerical calculations on coupled systems.

Experimental investigations of simultaneous water and heat transport have been almost exclusively carried out in the laboratory (Stallman, 1967; Jackson et al., 1975). Little or no emphasis has been placed on investigating field situations. The hot and dry surface layers of bare soils are one example where temperature effects on water transfer are very pronounced because of the predominance of moisture transport in the vapor phase. Also, in deeper layers of the ground, seasonal climatic trends may create persistent temperature gradients which can transport water in a vertical direction.

However, few investigations -- based primarily on the Philip and de Vries theory -- have been carried out in the field. Investigations of the non-isothermal water flux of the upper 15 cm of a bare soil (Rose, 1968a, b, c) showed that the thermally induced vapor flux was of comparable

magnitude to the liquid flux and was oscillatory in direction and magnitude. A field and modeling study of heat transfer in bare soils (Wierenga and deWit, 1970) showed close agreement between predicted and observed soil temperatures for a wet soil. A study of the simultaneous water and heat fluxes within the top 10 cm of a field soil (Jackson et al., 1974, 1975) showed that the Philip and de Vries theory best predicts the soil water flux under diurnal conditions at intermediate water contents.

At present, a wide discrepancy seems to exist between the 'field-scale' approach of the hydrogeologists and the 'local scale' approach of the soil physicists. The hydrogeologists' approach has been largely empirical and crudely averaging, while the more physically based "micro" approach of soil physicists has so far not been successful in describing the field condition and its associated heterogeneity (Swartzendruber and Hillel, 1973). These two approaches are parallel lines of attack that have not converged. If both approaches moved towards a common scale of system characterization, the above mentioned discrepancy might cease to exist.

In order to reconcile these approaches, I propose the development of a theory which will treat the subsurface flow domain as an integrated entity, rather than as a series of isolated or loosely connected local systems. Several scientists (Childs, 1960; Stallman, 1964, 1967; Freeze,

1969a; Klute, 1969; van Bavel, 1969; Vachaud et al., 1975) have argued for an integrated approach to the problem of ground water recharge and discharge. In emphasizing the division of Hydrology into surface and groundwater Hydrology, hydrogeologists have tended to forget that events at the surface and underground waters are connected -- not just as a matter of geologic continuity -- but in a real sense, in that there is continuous movement of water from one domain into the other. This connecting link constitutes the unsaturated zone.

Accordingly, the following main objectives are set forth for this thesis:

to develop and apply a methodology for subsurface coupled heat and water transport suitable for field applications;

to develop and test a general computer simulation model for the simultaneous water and heat movement in unsaturated-saturated subsurface domains based on an adaptation of the Philip and de Vries model;

to evaluate the influence of coupling on diurnal subsurface moisture and heat transfer, and to use the coupled flow equations to calculate evaporation from dry land surfaces.



## CHAPTER 2

### THEORETICAL DEVELOPMENT

#### 2.1 Introduction

In this chapter, the equations for water and heat transport in porous media are derived. These will be used in Chapter 4 for the development of a general digital simulation model of non-isothermal transport in porous media. The following presentation is based on the transport phenomena viewpoint and is concerned with the fluxes of mass, momentum and energy which describe the macroscopic equations of change for porous media. These quantities can be determined from basic principles of physics listed below (Bird et al., 1960):

$$\text{Continuity equation } \frac{\partial \rho}{\partial t} + \nabla(\rho v) = 0$$

$$\text{(Conservation of mass equation)} \quad (2-1)$$

$$\text{Momentum equation } \rho \frac{Dv}{Dt} = \rho g - \nabla p + \mu \nabla^2 v \quad (2-2)$$

$$\text{Thermal energy eqn. } \rho c \frac{DT}{Dt} = -\nabla q_{cd} - T \left( \frac{\partial p}{\partial T} \right)_\rho \nabla v + \mu \Phi_v \quad (2-3)$$

where

$\rho$  is the mass density (gm/cm<sup>3</sup>)

$v$  is the microscopic vector flow velocity (cm/sec)

$\mu$  is the dynamic viscosity (poise)

$p$  is the point fluid pressure (dyne/cm<sup>2</sup>)

$c$  is the specific heat capacity (cal/gm/C)

$q_{cd}$  is the conductive heat flux ( cal/cm<sup>2</sup>/sec )

$\Phi_v$  is the viscous dissipation function ( sec<sup>-2</sup> )

D/Dt is the substantial time derivative

and all other quantities are as defined previously. A detailed derivation of the simultaneous heat, mass and momentum transfer in porous media from basic principles has recently been given by Whitaker (1977). However, for reasons of simplicity and brevity, a less rigorous approach in deriving the required equations will be followed here.

Before proceeding, it is essential to examine the parameters of interest in this study and the assumptions made in deriving appropriate equations, which are necessary for the determination of these parameters. Pressure potential or pressure head of interstitial water and temperature of the porous medium, as functions of space and time, are the main quantities sought in the present development. The pressure potential of interstitial water is the action of its energy per unit quantity of water that results from a pressure that is different from the reference pressure of one standard atmosphere. If a unit weight is taken as the unit quantity of water, then the pressure potential has the unit of length (cm) and is often called pressure head  $\psi$  (see also p. 26). The pressure head of interstitial water is positive in saturated porous media, zero at the water table and negative in unsaturated media. This negative pressure potential is also known as matric or capillary potential (Rose, 1966, Corey et al., 1967).

## 2.2 Assumptions

The following are the major assumptions and approximations underlying the derivation of the coupled non-isothermal equations of water and heat transfer in porous media to be presented in this chapter:

- 1) the system is comprised of a non-deformable and chemically inert matrix with liquid water and its vapor in the voids among the grains;
- 2) liquid flow can be described by a Darcy-type equation, which implies -- among other things -- that the flow is laminar;
- 3) all flow parameters are unique functions, so that hysteresis is avoided;
- 4) solute effects are negligible; no water composition variable or electrochemical effects are considered;
- 5) the liquid water and its vapor are in a continuous local phase equilibrium in the pores;
- 6) the macroscopic heat flux equation as presented by de Vries (1958) with negligible heat transfer by air convection, radiation and viscous generation of heat (2-55) is considered to be a valid approximation of porous media heat flux;
- 7) the soil relative humidity is independent of temperature at constant water content;
- 8) air pressure remains constant and air effects (entrapped air, solution of soil air) are negligible.

When the above assumptions are applied to porous media, they generally present no serious limitations (de Vries and Peck, 1958). Probably the most serious exception is assumption 3) above, which removes hysteresis from consideration. It is well-known that relationships such as the water characteristic function ( $\psi$  vs  $\theta$ ) and to a smaller degree the hydraulic conductivity function ( $K$  vs  $\theta$  or  $K$  vs  $\psi$ ) exhibit hysteretic behavior, especially for the near-surface domain. However, as Philip (1955) pointed out, hysteresis does not in itself invalidate the use of subsurface water flow equations, as long as the water characteristic relation adopted is appropriate to the phenomenon under study. In order to sidestep the problem, scientists considered monotonically drying or wetting flow problems and avoided materials which exhibit pronounced hysteretic behavior, such as swelling soils and others. In other cases a mean wetting-drying characteristic curve was shown to be satisfactory under field conditions (Watson et al., 1975). Rose (1971) concluded that variations caused by hysteresis, though real, are likely to be negligible in relatively dry soils and therefore it should be possible to ignore hysteresis in practice without serious errors. Royer and Vachaud (1975), however, concluded that hysteresis was too important to be neglected in their field study.

Although problems involving hysteresis have been solved numerically, assuming that the hysteretic functions were known in sufficient detail (Whisler and Klute, 1965; Rubin,

1967; Ibrahim and Brutsaert, 1968; Freeze, 1969a, 1971), the complexity of the developed theoretical techniques for handling hysteretic phenomena quantitatively, and the uncertainties associated with them make the applicability of such techniques difficult (Poulovassilis, 1962; Topp and Miller, 1966; Topp, 1969, 1971; Poulovassilis and Childs, 1971). Considerable research is still required in the area of hysteresis, so that the techniques developed recently can be simplified and effectively used in the hysteretic behavior of field soils (Watson et al., 1975; Klute, 1973). Also evaluations of the errors introduced both by neglect of hysteresis and by the use of approximate treatments are required.

In the following sections, the constitutive relationships between fluxes and appropriate gradients for vapor and liquid, as well as for heat transport, are developed. Transport parameters or coefficients are defined and/or briefly discussed. Subsequently the transient water and heat flow equations are derived by invoking conservation principles. As will be pointed out, the equations developed are more general than those usually found in the literature, in that they are valid for both unsaturated and saturated domains, as well as for non-homogeneous porous media. Finally, a field-oriented methodology is developed for estimating the various transport coefficients involved in coupled, non-isothermal equations.

### 2.3 Vapor Transport

By making the following assumptions

- 1) the water vapor behaves as an ideal gas, which means that the vapor density  $\rho_v$  ( gm/cm<sup>3</sup> ) is related to the vapor pressure  $p_v$  ( cm H<sub>2</sub>O ) by the ideal gas law (2-4), and

$$\rho_v = ( M/RT ) e g p_v \quad (2-4)$$

where

M is the molecular weight of water vapor ( gm/mole )

R is the universal gas constant ( erg/mole/K )

T is temperature ( K )

$\rho$  is the liquid water density ( gm/cm<sup>3</sup> )

g is the acceleration of gravity ( cm/sec<sup>2</sup> )

- 2) the total gas pressure P is constant throughout the porous medium,

a modified Fickian type expression to describe vapor flux ( $q_v$ ) in porous media can be written as follows (van Bavel, 1952; Rollins et al., 1954; de Vries, 1975):

$$q_v/\rho = -f D_a v (Mg/RT) \nabla p_v \quad (2-5)$$

where  $v = P/(P-p_v)$  is the mass flow factor which is always close to unity; f is a pore geometry factor (dimensionless), and  $D_a$  is the molecular diffusion coefficient of water vapor in air ( cm<sup>2</sup>/sec ).

The molecular diffusion coefficient  $D_a$  of water vapor in air is a function of temperature and total gas pressure and may be expressed as (Kruger et al., 1970)

$$D_a = c (P_o/P) (T/T_o)^n \quad (2-6)$$

where  $P_o$  is the standard atmospheric pressure (1 atm);  $P$  is the total gas pressure (atm);  $T$  and  $T_o$  are absolute (Kelvin) temperatures;  $T_o = 273.15$  K;  $c = 0.217$  cm<sup>2</sup>/sec and  $n = 1.88$ . (2-6) is an empirical relationship based on both isothermal and non-isothermal experimental data and on theoretical considerations (de Vries and Kruger, 1967).

The pore geometry factor  $f$  is a modification designed to account for the effects of the increase of the diffusion path length that results from the presence of the solid matrix and the effects that result from the presence of the liquid phase enhancing flow (see p. 7). Philip and de Vries (1957) expressed  $f$  as follows:

$$f = \alpha \phi \quad \text{for } \theta \leq \theta_x \quad (2-7a)$$

$$f = \alpha (a + \kappa \theta) \quad \text{for } \theta > \theta_x \quad (2-7b)$$

where  $\alpha$  is tortuosity (dimensionless), usually approximated by the constant value 0.66 (Penman, 1940);  $\phi$  is porosity (dimensionless) and  $\theta_x$  is the moisture content at which liquid continuity first occurs in the porous medium. This latter quantity is approximated here by the moisture content corresponding to the matric potential of one bar of the characteristic curve ( $\psi$  vs  $\theta$ ). In equation (2-7b),  $\kappa$  is a function of moisture content. It is approximated as  $\kappa = a/a_x$  (Philip and de Vries, 1957), where  $a = \phi - \theta$  (air content) and  $a_x = \phi - \theta_x$ ;  $\kappa$  tends to unity when liquid continuity no longer exists and to zero near saturation.

The pore geometry factor for a gas insoluble in water may also be represented as (Currie, 1960, 1961; Rose, 1968a, b)

$$f = (D/D_s) (D_s/D_o) \quad (2-8)$$

where  $D$  is the diffusion coefficient in moist soil of a gas insoluble in water ( $\text{cm}^2/\text{sec}$ );  $D_o$  and  $D_s$  are diffusion coefficients of the same gas in air and dry soil respectively ( $\text{cm}^2/\text{sec}$ ). The ratio  $(D/D_s)$  accounts for the reduction of diffusion by the presence of water, and  $(D_s/D_o)$  accounts for the tortuosity or the presence of soil matrix.

In order to express the vapor flux (2-5) in terms of variables of interest, such as  $T$  and  $\theta$  or  $\psi$ , the thermodynamic relationship expressed in equation (2-9) is used (Edlefsen and Anderson, 1943). It is based on the assumption that a continuous equilibrium exists between vapor and liquid contents per unit volume

$$p_v = p_v^s h = p_v^s \exp\{(Mg/RT)\psi\} \quad (2-9)$$

where  $p_v^s$  is the saturated water vapor pressure ( $\text{cm H}_2\text{O}$ ) and  $h$  is the soil relative humidity (dimensionless). On the basis of arguments presented by Philip and de Vries (1957), it can be shown that the relative humidity  $h$  is mainly a function of moisture content, and that the saturation vapor pressure  $p_v^s$  is a function of temperature only. Thus, the vapor pressure can be expressed as

$$p_v(\theta, T) = p_v^s(T) h(\theta) \quad (2-10)$$

Applying the chain rule of differentiation to  $\nabla p_v$  in (2-5)

and making use of (2-10), the following relationship is obtained:

$$\nabla p_v = p_v^s (\partial h / \partial \theta) \nabla \theta + h (dp_v^s / dT) (\nabla T)_a \quad (2-11)$$

where  $(\nabla T)_a$  represents the average temperature gradient across air-filled pores in the porous medium. This gradient, as is mentioned in Chapter 1 (p. 7), may be several times larger than the overall macroscopic gradient  $\nabla T$ , so that

$$(\nabla T)_a = \zeta \nabla T \quad (2-12)$$

where  $\zeta \geq 1$ . As indicated by Philip and de Vries (1957) and Rose (1968a, b), typical values of  $\zeta$  range from 1.3 to 3.0 for most soil materials.

In order to replace the  $\partial h / \partial \theta$  gradient in (2-11) by a pressure head gradient, (2-9) is differentiated with respect to  $\theta$  to give

$$\partial h / \partial \theta = (Mg/RT) h \partial \psi / \partial \theta \quad (2-13)$$

so that (2-11) becomes

$$\nabla p_v = p_v^s (Mg/RT) h \partial \psi / \partial \theta \nabla \theta + h (dp_v^s / dT) \{ (\nabla T)_a / \nabla T \} \nabla T \quad (2-14)$$

or

$$\nabla p_v = p_v^s (Mg/RT) h \nabla \psi + \zeta h (dp_v^s / dT) \nabla T \quad (2-15)$$

Substituting (2-15) in (2-5) yields the vapor flux in terms of the unknowns  $\psi$  and  $T$

$$q_v / \rho = -f D_a \nu (Mg/RT) \zeta p_v^s h \nabla \psi - \zeta f D_a \nu (Mg/RT) h (dp_v^s / dT) \nabla T \quad (2-16)$$

By defining the following generalized parameters:

$$K_{\psi v} = f D_a \nu (Mg/RT) \zeta p_v^s h \quad (2-17)$$

where  $K_{\psi v}$  (cm/sec) is the vapor conductivity; and

$$D_{Tv} = \zeta f D_a \nu (Mg/RT) h dp_v^s / dT \quad (2-18)$$

where  $D_{Tv}$  (cm<sup>2</sup>/sec/C) is the thermal vapor diffusivity,

the vapor flux, can be more simply written as

$$q_v/\rho = -K_{\psi_v} \nabla \psi - D_{T_v} \nabla T \quad (2-19)$$

For the saturated zone, the vapor flux becomes zero.

#### 2.4 Liquid Transport

The starting point for the theoretical formulation of liquid transport is the momentum principle -- expressed by the Navier-Stokes equation (Schlichting, 1968; Le Méhauté, 1976) -- which describes the isothermal flow of a Newtonian incompressible fluid with constant viscosity.

$$\underbrace{\rho DV/Dt}_{\text{Inertial Forces}^1} = \underbrace{\rho g - \nabla p + \mu \nabla^2 v}_{\text{Applied Forces}} \quad (2-20)$$

gravity    pressure    friction

Because the boundary conditions in porous media are extremely complex (the microscopic flow velocity  $v$  equals zero at the surface of every grain), the above equation must be transformed to a more useful form. Consequently, instead of dealing with microscopically varying values of velocity and pressure, only the mean values need to be considered. Also by making the following approximations:

- 1) for a porous medium the inertial forces are negligible, which is the case with a steady, laminar flow; and
- 2) the viscous (friction) forces are proportional to the

---

<sup>1</sup> These forces characterise the natural resistance of matter to any change in its state of motion.

mean velocity of the fluid flowing through a porous medium, which is an empirical approximation;

the Navier-Stokes equation (2-20) reduces to

$$0 = \rho g - \nabla \bar{p} + (\mu/k) \bar{v} = \rho (g - \nabla \bar{p}/\rho) + (\mu/k) \bar{v} \quad (2-21)$$

where  $\bar{v}$  is the macroscopic (mean) vector flow velocity and  $\bar{p}$  is the mean fluid pressure. Both of these quantities are the outcome of smoothing the actual microscopic distribution of velocity and pressure over a volume larger than that of the individual pores. Solving (2-21) for  $\bar{v}$  one obtains:

$$\begin{aligned} \bar{v} &= -(k\rho/\mu) [ -\nabla \bar{p}/\rho + g ] = -(k\rho/\mu) \nabla \phi' = \\ &= -(k\rho g/\mu) \nabla \phi = -K \nabla \phi = -K \nabla (\psi + z) \end{aligned} \quad (2-22)$$

$$\text{where } \phi' = g\phi = g[ (\bar{p}/\rho g) + z ] = g(\psi + z) \quad (2-23)$$

$\phi$  is the total (hydraulic) potential corresponding to the hydraulic head (cm);

$k$  is the intrinsic permeability (cm<sup>2</sup>) of the porous medium; and

$z$  is the elevation (cm), here taken as positive in the upward direction.

(2-22) is the Darcy equation (Hubbert, 1956) for the steady isothermal solute-free flow of water in isotropic saturated porous media with constant hydraulic conductivity  $K$ . By expressing that equation in the following form, the macroscopic flow velocity for an anisotropic medium is defined as

$$\bar{v} = q_t/\rho = -\bar{K} \nabla \phi \quad (2-24)$$

where  $\bar{K}$  is the hydraulic conductivity tensor.

In summary, provided that the inertial terms are

negligible, as is generally the case with porous media, the macroscopic mean flow velocity is directly proportional to the macroscopic mean potential gradient. This represents the hydrodynamic element in Darcy's equation. Implicit in this equation is the statistical requirement that the medium must be "sufficiently homogeneous" on the scale of the averaging volume -- the so-called "Darcy scale" -- for local mean quantities, such as  $\bar{v}$  and  $\bar{p}$  or  $\Phi$ , to exist (Philip, 1970).

Darcy's equation can be applied to unsaturated porous media (Richards, 1931; Childs and Collis-George, 1950) when the hydraulic conductivity  $K$  is allowed to vary as a function of the matric potential  $\psi$  or the volumetric moisture content  $\theta$ . This change is due to the fact that the unsaturated hydraulic conductivity decreases very rapidly as the porous media water content decreases from its saturation value and as the pressure head becomes negative. Thus, for unsaturated media, (2-22) is expressed as

$$q_c/\rho = -K(\psi) \nabla \Phi = -K(\theta) \nabla \Phi \quad (2-25)$$

Assuming the coordinate  $z$  to be positive in a downward direction, the hydraulic head becomes

$$\Phi = \psi - z \quad (2-26)$$

so that (2-25) is written as

$$q_c/\rho = -K(\psi) \nabla [\psi(\theta, T) - z] = -K \nabla \psi + K i \quad (2-27)$$

where both  $K$  and  $\psi$  are functions of moisture content and temperature, and  $i$  is a unit vector in the positive  $z$  direction.

In order to generalize Darcy's equation (2-22 and 2-27) to take into account non-isothermal conditions, (2-27) is expanded using the chain rule of differentiation

$$q_e/\rho = -K \frac{\partial \psi}{\partial \theta} \nabla \theta - K \frac{\partial \psi}{\partial T} \nabla T + K_i \quad (2-28)$$

or

$$q_e/\rho = -D_{\theta e} \nabla \theta - D_{T e} \nabla T + K_i \quad (2-29)$$

where the following generalized diffusivities are introduced:

$$D_{\theta e} = K \left( \frac{\partial \psi}{\partial \theta} \right)_T \text{ -- liquid moisture diffusivity (cm}^2\text{/sec)} \quad (2-30)$$

$$D_{T e} = K \left( \frac{\partial \psi}{\partial T} \right)_\theta \text{ -- liquid thermal diffusivity (cm}^2\text{/sec/C)} \quad (2-31)$$

In employing the diffusivity concepts mentioned above, it should be stressed that although vapor transport through porous media is mainly carried out by true diffusion, the process of liquid movement is not achieved by diffusion but by viscous flow. The term "diffusivity" arose in order to set the transport equation in a form analogous to the equations of diffusion and heat conduction. For equations of this form, numerous mathematical solutions are available (Crank, 1956; Carslaw and Jaeger, 1959). However, the main problem in applying the liquid moisture diffusivity concept to real situations is that such a concept is restricted to homogeneous unsaturated porous media (Kirkham and Powers, 1972). Therefore, in this work, (2-28) and (2-29) are written as functions of  $\psi$  and  $T$

$$q_e/\rho = -K_{\psi e} \nabla \psi - D_{T e} \nabla T + K_i \quad (2-32a)$$

where  $K_{\psi} = K$  (2-32b)

Thus, (2-32a) is more general than (2-29) because it is applicable to both saturated and unsaturated porous media and valid for heterogeneous conditions.

In order to estimate the liquid thermal diffusivity  $D_{Tl}$  (2-31) Philip and de Vries (1957) argued that in the range of dominant liquid transfer, the negative pressure potential  $\psi$  is determined by capillarity and thus the equation of capillarity holds

$$\psi = (2/r) \sigma \quad (2-33)$$

where  $\sigma$  is the water-air interfacial tension (dyne/cm);  $1/r$  is the mean curvature of the water-air interface ( $\text{cm}^{-1}$ ). Hence,

$$\partial\psi/\partial T|_0 = (2/r) d\sigma/dT = (\psi/\sigma) d\sigma/dT = (d\ln\sigma/dT)\psi = \gamma\psi \quad (2-34)$$

where  $\gamma = d\ln\sigma/dT$  is the temperature coefficient of surface tension, which is reasonably constant in the range of 10 to 30 C. Thus, the following simple surface tension model was used by Philip and de Vries (1957) and numerous subsequent investigators (Gee, 1966; Rose, 1968a, b, c; Cassel et al., 1969; Fritton et al., 1970) to estimate  $D_{Tl}$ :

$$D_{Tl} = \gamma\psi K \quad (2-35)$$

However, there are problems with this simple formulation. Measured values of  $\partial\psi/\partial T$  were consistently higher than the calculated estimates from the above equation (Wilkinson and Klute, 1962; Cary, 1966; Jury and Miller, 1974). The explanation for the differences is that several other mechanisms, besides the previously mentioned surface tension

model, also contribute to liquid flow in the presence of temperature gradients (Cary, 1966).

In order to circumvent this difficulty, I propose an alternative formulation which gives a better approximation to measured data. Invoking assumptions 5) and 7) listed previously in this chapter (see also 2-9 and 2-10), the following relation can be deduced by differentiation:

$$\partial\psi/\partial T = (R/Mg) \ln h \quad (2-36)$$

so that

$$D_{Te} = K (R/Mg) |\ln h| \quad (2-37)$$

Both the above described model (2-37) and the surface tension model for estimating  $D_{Te}$ , however, suffer from the limitation that they are not applicable to saturated conditions. Taylor and Cary (1960), reported several instances of thermally induced flow in saturated porous media.

## 2.5 Total Water Transport

In order to obtain the combined liquid and vapor flux or total water flux  $q_w/\rho$ , both liquid (2-32) and vapor (2-19) flux components are added algebraically as follows:

$$q_w/\rho = q_l/\rho + q_v/\rho = -K_\psi \nabla\psi - D_T \nabla T + K_i \quad (2-38)$$

where

$$K_\psi = K_{\psi_v} + K_{\psi_l} \quad \text{-- total hydraulic conductivity (cm/sec)} \quad (2-38)$$

$$D_T = D_{Tv} + D_{Tl} \quad \text{-- thermal water diffusivity (cm}^2\text{/sec/C)} \quad (2-40)$$

The total non-isothermal water flux (2-38) is governed by

Darcy's equation plus terms included to account for vapor flux and thermally driven liquid and vapor. This constitutive relation was termed "the general Darcy law" by Guymon and Luthin (1974).

## 2.6 Transient Flow Equations

Both vapor and liquid flux equations discussed previously describe only steady flow processes in which the flux and potential gradient at each point remain constant with time. In order to extend the flow processes to transient or unsteady conditions -- in which the flux and potential gradient vary with time -- the principle of conservation of mass, expressed by the continuity equation (Cooper, 1966; De Wiest, 1966; Eagleson, 1970) is introduced in (2-41) as:

$$\partial(\rho\phi S_w)/\partial t + \nabla(\rho\bar{v}) = 0 \quad (2-41)$$

where  $S_w$  is the volumetric degree of saturation ( $0 \leq S_w \leq 1$ ). By combining (2-41) with the previously derived flux equations, the transient flow equations result. Substituting Darcy's equation (2-22) into (2-41) yields

$$\partial(\rho\phi S_w)/\partial t = \nabla[ \rho K \nabla(\psi+z) ] \quad (2-42)$$

Expanding the left-hand-side of (2-42) and substituting in it the mathematical definitions of water and formation compressibilities (Jacob, 1950; De Wiest, 1966; Cooper, 1966; Cooley, 1971), one obtains (2-43)

$$\underbrace{[ \partial\theta/\partial\psi + (\theta/\phi) S_w ]}_{F} \partial\psi/\partial t = \nabla K [ \nabla(\psi+z) ] \quad (2-43)$$

where  $S_s$  is the specific storage coefficient ( $\text{cm}^{-1}$ ) and

$$F = \partial\theta/\partial\psi + (\theta/\rho) S_s \quad (2-44)$$

is a generalized storage coefficient ( $\text{cm}^{-1}$ ). It is assumed that the spatial variations in  $\rho$  are negligible due to the slight compressibility of water.

(2-43) is the transient isothermal flow equation which applies to both saturated and unsaturated porous media. For saturated media, (2-43) reduces to the elastic storage equation

$$S_s \partial\psi/\partial t = \nabla K [ \nabla (\psi+z) ] \quad (2-45)$$

For unsaturated media, (2-43) reduces to Richards' equation

$$C_w \partial\psi/\partial t = \nabla K [ \nabla (\psi+z) ] \quad (2-46)$$

where  $C_w = \partial\theta/\partial\psi$  (2-47)

is the specific water capacity ( $\text{cm}^{-1}$ ).

By applying the continuity principle to the non-isothermal vapor (2-19), liquid (2-29) and total water flux (2-38), the following differential equations are obtained:

$$\partial\theta_v/\partial t = - \nabla (q_v/\rho) + E = \nabla (K_{\psi v} \nabla \psi + D_{Tv} \nabla T) + E \quad (2-48)$$

$$\partial\theta_l/\partial t = - \nabla (q_l/\rho) - E = \nabla (K_{\psi l} \nabla \psi + D_{Tl} \nabla T - K_i) - E \quad (2-49)$$

$$\partial\theta/\partial t = - \nabla (q_w/\rho) = \nabla (K_{\psi} \nabla \psi + D_T \nabla T - K_i) \quad (2-50)$$

The possibility of water transfer from the liquid to the vapor phase and vice versa is accounted for by the source-sink (evaporation-condensation) term  $E$  in (2-48) and (2-49) (de Vries, 1958).

Assuming that liquid and vapor phases are always in

equilibrium -- which is shown to be a valid assumption (Novak and Coulman, 1974) -- the following relation holds (de Vries, 1958) for any small region of porous medium:

$$\theta_v = (\phi - \theta_l) \rho_v / \rho = (\phi - \theta_l) (\rho_v^s / \rho) h = (\phi - \theta_l) (\rho_v^s / \rho) \exp[(Mg/RT)\psi] \quad (2-51)$$

Differentiating the above relationship with respect to time by means of the chain rule and substituting the result together with the relation  $\theta = \theta_l + \theta_v$  in (2-50), one obtains the general non-isothermal transient flow equation

$$\begin{aligned} \partial\theta/\partial t &= \partial\theta_l/\partial t + \partial\theta_v/\partial t = \\ & [ 1 + (\rho_v^s/\rho) \exp\{Mg/RT\} (\phi - \theta_l) (Mg/RT) \partial\psi/\partial\theta ] \partial\theta_l/\partial t \\ & + [ (\rho_v^s/\rho) \exp\{Mg\psi/RT\} (\phi - \theta_l) (1/\rho_v^s) \partial\rho_v^s/\partial T - Mg\psi/RT^2 ] \partial T/\partial t \\ & = \nabla(K_\psi \nabla\psi + D_T \nabla T - K_i) \end{aligned} \quad (2-52)$$

or

$$\partial\theta/\partial t = (1+A) \partial\theta_l/\partial t + (B-G) \partial T/\partial t = \nabla(K_\psi \nabla\psi + D_T \nabla T - K_i) \quad (2-53)$$

where

$$A = (\rho_v^s/\rho) \exp[Mg\psi/RT] (\phi - \theta_l) (Mg/RT) \partial\psi/\partial\theta_l$$

$$B = (\rho_v^s/\rho) \exp[Mg\psi/RT] (\phi - \theta_l) (1/\rho_v^s) \partial\rho_v^s/\partial T$$

$$G = (\rho_v^s/\rho) \exp[Mg\psi/RT] (\phi - \theta_l) (Mg/RT^2) \psi$$

However, many terms in the above equation are negligibly small compared to dominant terms in that equation. Thus term A in the equation above is of the order of  $10^{-12} (\phi - \theta_l) \partial\psi/\partial\theta$  ( $\text{cm}^{-1}$ ), term B is of the order of  $10^{-7} (\phi - \theta_l)$  ( $\text{C}^{-1}$ ), and term G is of the order of  $10^{-14} (\phi - \theta_l)$  ( $\text{cm}^{-1} \text{C}^{-1}$ ). Therefore, for moisture contents above extreme dryness, terms A, B, and G can be neglected; so that the above equation becomes identical to (2-50).

In order to express (2-48), (2-49) and (2-50) in terms of one dependent variable ( $\psi$ ), the concept of the generalized storage coefficient (2-44) is invoked. For instance (2-50) becomes

$$F \frac{\partial \psi}{\partial t} = \nabla (K_{\psi} \nabla \psi + D_T \nabla T - K_i) \quad (2-54)$$

The above relationship constitutes the general, non-isothermal transient flow equation for both saturated and unsaturated porous media.

## 2.7 Heat Transport

The heat flux  $q_h$  through porous media may be expressed as follows:

$$q_h = q_{cd} + q_{lh} + q_{sv} + q_{sl} \quad (2-55)$$

where

$$q_{cd} = -\lambda^* \nabla T \quad (2-55a)$$

$$q_{lh} = L'(T_0) q_v \quad (2-55b)$$

$$q_{sv} = c_v (T - T_0) q_v \quad (2-55c)$$

$$q_{sl} = c_l (T - T_0) q_l \quad (2-55d)$$

$q_{cd}$  is the conductive (Fourier) heat flux;  $\lambda^*$  is the thermal conductivity of the porous medium (cal/cm/sec/C) in the hypothetical case where no liquid or vapor movement occurs;

$q_{lh}$  is the latent heat flux by vapor movement;  $L'(T_0)$  is the latent heat of vaporization of water at the arbitrary reference temperature  $T_0$ ;

$q_{sv}$  and  $q_{sl}$  are convective sensible heat fluxes transported by the moving vapor and liquid respectively;  $c_v$  and

$c_l$  are the specific heats of water vapor (at constant pressure) and liquid water, respectively.

The separation of  $q_h$  into these component parts is discussed by de Vries (1958), who recognized the approximate character of (2-55). The approximate nature of that relationship stems from the fact that while all processes of heat transfer were assumed to take place uniformly throughout the porous medium (notice the additive structure of 2-55), they in fact do not. Furthermore, it is assumed that heat transfer by air convection and radiation is negligible, which is usually the case (de Vries, 1958).

Identifying the heat of vaporization per unit mass at temperature  $T$  by

$$L'(T) = L'(T_0) + c_v(T - T_0) - c_l(T - T_0) \quad (2-56)$$

in (2-55), the following relation is obtained:

$$q_h = -\lambda \nabla T + L'(T) q_v + c_l q_w (T - T_0) \quad (2-57)$$

or, by replacing the water vapor flux  $q_v$  above by (2-19), one obtains

$$q_h = -\lambda \nabla T - \rho L'(T) K_{\psi} \nabla \psi + c_l q_w \Delta T \quad (2-58)$$

where

$$\lambda = \lambda^* + \rho L'(T) D_{TV} \quad (2-59)$$

$\lambda$  is the thermal conductivity of a porous medium including the effect of heat transfer by vapor movement under the influence of temperature gradients. Experimentally, it is this quantity which is measured and not  $\lambda^*$  because when a temperature,

gradient is imposed across a porous medium, fluid motion will certainly occur;

$\Delta T$  is the difference in temperature between the cross-sections in question.

In terms of  $\theta$ , (2-59) becomes

$$q_h = -\lambda \nabla T - \rho L' (T) D_{\theta v} \nabla \theta + c_l q_w \Delta T \quad (2-60)$$

At saturation, the second term of the right-hand side of (2-58) and (2-60) becomes zero, so that the saturated heat flux equation becomes

$$q_h = -\lambda \nabla T + c_l q_w \Delta T \quad (2-61)$$

In order to derive the transient heat flow equation, the principle of heat conservation is used in a manner similar to the one used in deriving the water flow equations. The equation for the conservation of heat, in the absence of sources or sinks, may be expressed as

$$\partial H / \partial t = -\nabla q_h \quad (2-62)$$

where  $H$  is the total heat content of a unit volume of moist porous medium (cal/cm<sup>3</sup>). The total heat content term may be broken down into the following constituents:

$$H = H_d + H_{lv} + H_v + H_l + H_w \quad (2-63)$$

where

$$H_d = c_d (T - T_0) \quad (2-63a)$$

$$H_{lv} = L' (T_0) \rho \theta_v \quad (2-63b)$$

$$H_v = c_v \rho \theta_v (T - T_0) \quad (2-63c)$$

$$H_l = c_l \rho \theta_l (T - T_0) \quad (2-63d)$$

$$H_w = -\rho \int_0^{\theta} W d\theta \quad (2-63e)$$

$$W = (RT/Jh) \partial h / \partial T \quad (2-63f)$$

$H_d$  is the heat content of the dry porous medium;  $H_{lv}$  the latent heat of the vapor;  $H_v$  and  $H_l$  the heat contents of vapor and liquid water, respectively; and  $H_w$  is the heat of wetting. (2-63f) -- representing the differential heat of wetting  $W$  -- is obtained according to thermodynamic theory (Edlefsen and Anderson, 1943);  $J$  in that equation is the mechanical equivalent of heat. By grouping the heat capacity terms from (2-63a, c and d), the following total heat capacity of a moist porous medium may be defined

$$C = c_d + c_v \rho \theta_v + c_l \rho \theta_l \quad (2-64)$$

Combining (2-55) and (2-63) in the heat conservation equation (2-62) and making use of definitions (2-56) and (2-64), one obtains

$$C \partial T / \partial t + L'(T) (\rho \partial \theta_v / \partial t + \nabla q_v) - \rho W \partial \theta_l / \partial t = \nabla (\lambda^* \nabla T) - c_v q_v \nabla T - c_l q_l \nabla T \quad (2-65)$$

where the continuity equation, as indicated by the first two terms of (2-50) is used as well. By combining the last two terms of the right-hand side of (2-65), the following general transient heat flow equation is obtained

$$C \partial T / \partial t + L'(T) (\rho \partial \theta_v / \partial t + \nabla q_v) - \rho W \partial \theta_l / \partial t = \nabla (\lambda^* \nabla T) - c_l q_w \nabla T \quad (2-66)$$

The term  $\rho W \partial \theta_l / \partial t$  representing the heat content change due to liberation of the heat of wetting is a small quantity, especially for porous media with a small clay fraction and, therefore, can be neglected. The  $\partial \theta_v / \partial t$  term may also be neglected due to its negligibly small magnitude. Finally

replacing  $q_v$  in the above equation by (2-19), one obtains the reduced transient heat flow equation

$$c \partial T / \partial t = \nabla(\lambda \nabla T) + \rho L' (T) \nabla(K \psi \nabla \psi) - c_e q_w \nabla T \quad (2-67)$$

At saturation, the second term of the right-hand side of the above equation becomes zero and (2-67) reduces to

$$c \partial T / \partial t = \nabla(\lambda \nabla T) - c_e q_w \nabla T \quad (2-68)$$

Table 2-1 summarizes the final forms of the developed equations and transport coefficients.

The derived flow equations (2-54) and (2-67) form a system of coupled partial differential equations which, in principle, may be solved in order to predict the evolution of a given flow system subject to appropriate boundary and initial conditions. However, the flow equations are non-linear; that is, the various transport parameters appearing in (2-54) and (2-67) are functions of the dependent variables  $\psi$  (or  $\theta$ ) and  $T$ ; this fact makes the solution of the above equations very difficult. Chapter 4 contains a more complete elaboration of this problem and a discussion of methods that may be utilized to solve the flow equations.

## 2.8 Proposed Field-oriented Methodology for Transport Coefficients

As mentioned in Chapter 1, the coupled non-isothermal flow equations have not been adequately tested by application to field problems. Accordingly, field data --

TABLE 2<sup>a</sup>-1

Present Model

(2-19)	$q_v/\rho = -K_{\psi v} \nabla \psi - D_{Tv} \nabla^2 \psi$	vapor	Flux Equations
(2-32)	$q_l/\rho = -K_{\psi l} \nabla \psi - D_{Tl} \nabla^2 \psi$	liquid	
(2-38)	$q_w/\rho = -K_{\psi} \nabla \psi - D_T \nabla^2 \psi + K_l$	water	
(2-58)	$q_h = -\lambda \nabla T - \rho L' K_{\psi v} \nabla \psi + c_l q_w \Delta T$	heat	
(2-54)	$F \partial \psi / \partial t = \nabla (K_{\psi} \nabla \psi) + \nabla (D_T \nabla T) - \partial K / \partial z$	water	Transient Flow Equations
(2-67)	$C \partial T / \partial t = \nabla (\lambda \nabla T) + \rho L' \nabla (K_{\psi v} \nabla \psi) - c_l q_w \nabla T$	heat	
(2-17)	$K_{\psi v} = f D_a \nu (Mg/RT)^2 p_v^{sh}$		Transport Coefficients
(2-32b)	$K_{\psi l} = K$		
(2-18)	$D_{Tv} = \zeta f D \nu (Mg/RT) h \, dp_s/dt$		
(2-37)	$D_{Tl} = K (R/Mg) \ln h$		
(2-39)	$K_{\psi} = K_{\psi v} + K_{\psi l}$		
(2-40)	$D_T = D_{Tv} + D_{Tl}$		
(2-44)	$F = \partial \theta / \partial \psi + (\theta/\phi) S_s$	generalized storage coefficient	

necessary to develop relevant models -- are extremely scarce. One of the major difficulties in applications of such models to field situations is the calculation of transport coefficients because they constitute difficult-to-measure physical properties of the porous and fluid media. In this section I will develop simplified procedures for estimating the transport parameters for a unified unsaturated-saturated profile without sacrificing accuracy in relation to the analytical relations of Table 2-1. Next, the heat and water transport equations will be considered in one-dimensional form. Formulations based on both pressure head  $\psi$  and water content  $\theta$  as the dependent variables will be put forward.

By introducing a new quantity  $D^*$  defined as

$$D^* = D_{\theta v} / D_{Tv} \quad (2-69)$$

and substituting from Table 1-1 the analytical expressions for  $D_{Tv}$  and  $D_{\theta v}$ , the following expression results:

$$D^* = (p_v^s \partial h / \partial \theta) / (\zeta h dp_v^s / dT) \quad (2-70)$$

The advantages of using the above expression over the expressions for the transport coefficients  $D_{\theta v}$  and  $D_{Tv}$  are clearly evident. Simply stated, using the  $D^*$  definition, one avoids the following terms common in the analytical formulas of  $D_{\theta v}$  and  $D_{Tv}$ :  $f$  (or  $f(a)$  and  $\zeta$  if Rose's 1968a, b formulation is used),  $D_a$ ,  $v$ ,  $Mg/RT$ , thus eliminating the uncertainties associated with their direct calculation. With the exception of  $\zeta$ , which may be approximated from

literature data or simply as indicated in Chapter 4 (p. 141), the evaluation of  $D^*$  may not be difficult in the field, provided that the soil psychrometers used for measuring soil relative humidity ( $h$ ) function properly.

I suggest further that the measurement of heat flux, thermal conductivity and water flux can be achieved under field conditions as described in Chapter 3, together with moisture, temperature and pressure potential measurements. Thus, after measuring the above quantities appearing in (2-60), the only unknown remaining in the equation is the coefficient  $D_{\theta_v}$ , which may be calculated as

$$D_{\theta_v} = [ -q_h - \lambda(\partial T/\partial z) + c_2 q_w \Delta T ] / [ \rho L' \partial \theta/\partial z ] \quad (2-71)$$

$K_{\psi_v}$  can be obtained by multiplying  $D_{\theta_v}$  by the specific water capacity  $C_w$  (2-47). Having thus estimated  $D^*$  and  $D_{\theta_v}$ , it is obvious that  $D_{T_v}$  can be estimated from the definition of  $D^*$  (2-69).

In view of the uncertainties regarding the Philip and de Vries' (1957) surface tension model for  $D_{T_l}$ , I propose an alternative formulation (2-37). The unsaturated hydraulic conductivity may be calculated from the non-isothermal expression of the water flux, once the latter is known for each layer in the profile.

As for the saturated region, the water flux may be calculated from the heat flux equation (2-61) as follows:

$$q_l = [ q_h + \lambda \partial T/\partial z ] / (c_l \Delta T) \quad (2-72)$$

Once the saturated water flux is known, the liquid thermal

diffusivity,  $D_{TL}$  may be calculated from the non-isothermal liquid flux equation (2-32) as

$$D_{TL} = (-K \partial \psi / \partial z - q_l / \rho + K_i) / (\partial T / \partial z) \quad (2-73)$$

where the saturated  $K$  may be measured by piezometric methods (Chapter 3).

This proposed methodology may be used to establish and solve non-isothermal equations for field systems. Although a discussion on the accuracy and limitations of this approach is presented later (Chapter 3), it is important to remember that this methodology depends mainly on the accuracy of the estimation of the water fluxes and, particularly, of the heat fluxes.

## CHAPTER 3

### FIELD AND LABORATORY STUDIES

#### 3.1 Introduction

A general lack of adequate data on the simultaneous heat and water transfer in porous media has severely limited field-testing of the non-isothermal theories and modeling of coupled systems. For this reason, the significance of thermally induced flow, especially under field conditions, has not yet been definitely assessed. At the time I designed the set of field experiments for this study in early 1974, there were no comprehensive field experiments on non-isothermal flow reported in the literature. Only a few aspects of the problem had been considered. Rose (1968a, b) worked with non-isothermal water flux only; whereas, Wierenga and de Wit (1970) worked with the heat flux only. In recent years, there has been evidence of a more complete treatment of the coupled aspects of the problem. Jackson et al. (1974, 1975) investigated heat and water fluxes under field conditions. However, their work concentrated only on the top 10 cm of the soil, and several relevant quantities in the non-isothermal flow equations were not directly measured in their experiments.

Thus, an important objective of this research was to design a field experiment to measure directly the relevant physical quantities that would enable me to implement the methodology for non-isothermal studies under field conditions that I proposed in Chapter 2 (Section 2.8). This program of field studies will be supported by appropriate laboratory studies.

### 3.2 Preliminary Considerations

A major problem with the field measurement approach was the selection of a suitable field site. At the outset, it appeared that the following criteria would have to be met:

- 1) surficial materials at the site should be of uniform texture with clay contents less than 20-25%;
- 2) the area should be characterized by a shallow water table;
- 3) the area should be easily accessible and close to the base station. It would be preferable to have a meteorological station located a reasonably short distance from the field site.

The reasons for establishing the first criterion are to avoid the complications that would arise from hydraulic and thermal heterogeneities, serious swelling and hysteretic effects which occur in clay-rich soils. The criterion of shallow water table is a practical one, designed to facilitate the installation of instrumentation and reduce

costs. Proximity to the base station will, in general, assist the field operation; while, the presence of a nearby meteorological station will provide the researcher with a suitable set of data readily available.

### 3.3 Location and Surficial Geology of the Study Area

A field site meeting most of the criteria mentioned above was selected near Taber, Alberta (Lsd. 11-Sec. 13-Twp. 10- Rg. 17-W4M), approximately 50 km east of the Canada Agriculture Lethbridge Research Station, Lethbridge, Alberta (Fig. 3-1). The study area is part of a large terrace above the escarpment of the Oldman River (Fig. 3-1). It is entirely underlain by glacial till. This unit ranges in thickness from several centimeters to more than nine meters. In the immediate vicinity of the study area, this till unit is found at a depth of approximately 5.5 meters. Two types of material overlie the till: (a) alluvial sand and gravel and (b) aeolian sand. In the study area, the deposits overlying the till consist of sandy material that is classified texturally as sandy loam to sand. Some discontinuous thin silt or clay loam lenses are interbedded with the sand.

The water table depth is variable, ranging from 2 to 3 meters below the surface of the study area. In general, the lack of potholes indicates good internal drainage.

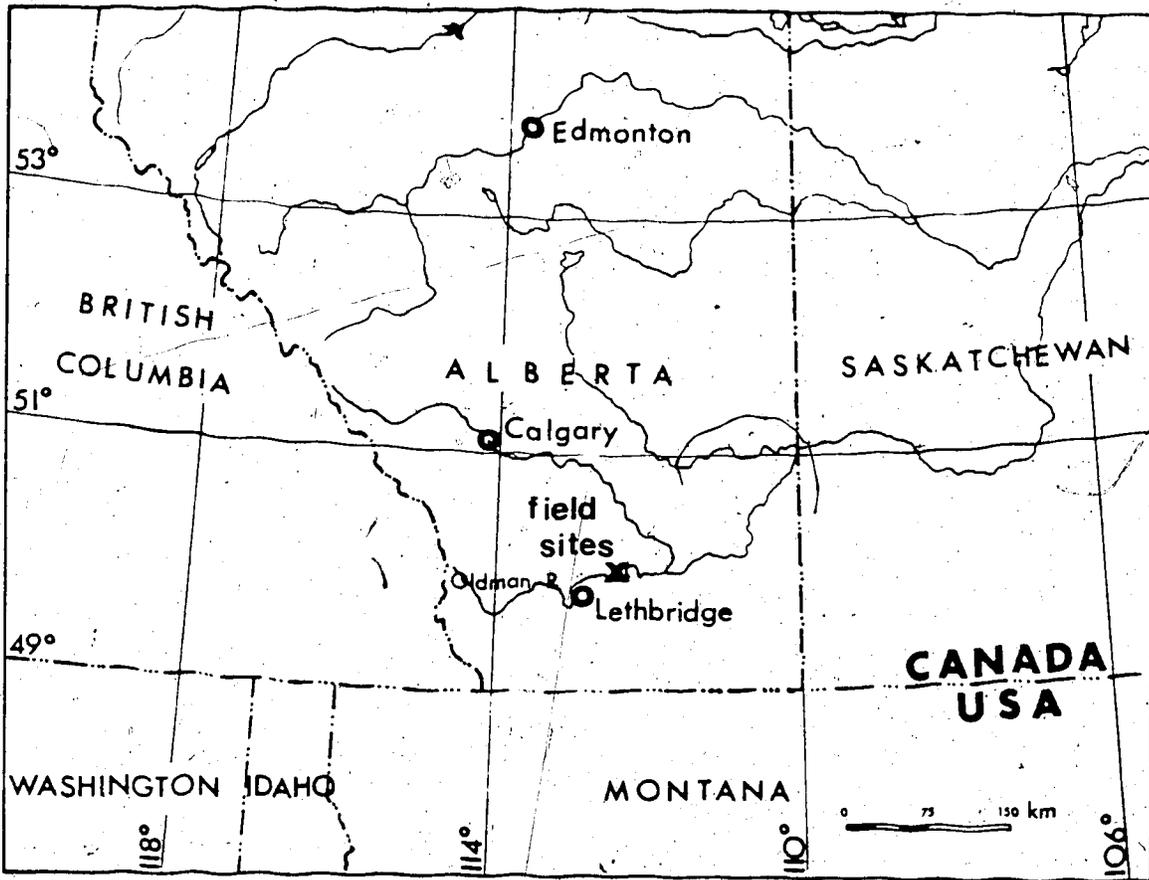


Figure 3-1. Location of study area

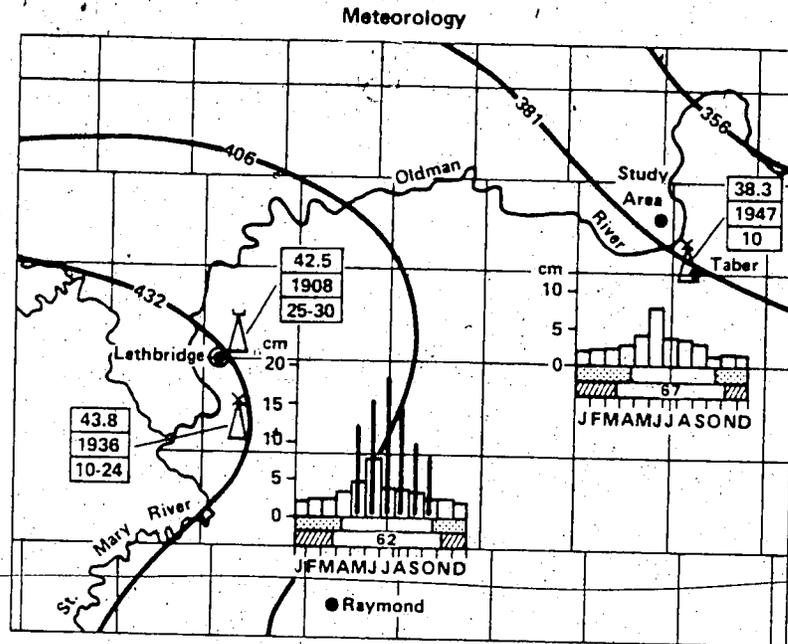
### 3.4 The Field Sites

Two sites, which were located approximately 150 meters apart, were selected for detailed study. An area approximately 9x9 meters square around each site was fenced to protect them from cattle grazing nearby.

None of the two sites was, however, entirely satisfactory. The extreme sandiness of one of the sites (Site 1) severely restricted the range of field-measured hydraulic head distribution and limited the effectiveness of laboratory support data on the range of water characteristic and hydraulic conductivity functions. The second site (Site 2), although having the more favorable sandy loam textures, was characterized by a relatively high degree of heterogeneity of the subsurface profile. In analysing the field data, however, more emphasis was placed on data from the second site.

### 3.5 Weather Observations

The Taber area is generally characterized by hot and dry summers and cold winters (Fig. 3-2). A small weather station is located approximately five kilometers from the field sites.



Legend

- ..... Isohyet, mean annual precipitation in cm ..... —380—
- ..... Meteorological station .....
- ..... Standard rain gauge only .....

Precipitation data:

- ..... Mean annual precipitation in cm .....
- ..... Year of commencement of observations .....
- ..... Number of years of record averaged to determine the mean annual precipitation figure .....
- ..... Mean monthly potential evapotranspiration\* .....
- ..... Mean monthly precipitation .....
- ..... Period when surface is usually snow covered .....
- ..... Period with mean daily temperature below freezing (0°C) .....
- ..... Figure indicates percentage of mean annual precipitation falling as rain .....

Sources of data:

Climatic Maps of Alberta (Longley, 1968); Monthly Record of Meteorological Observations (Meteorological Branch, Canada Department of Transport); and Provisional Evaporation Maps of Canada, Department of Transport Circular 4531 (Bruce and Weisman, 1957).

\*Evapotranspiration estimates are based on the Provisional Evaporation Maps of Canada.

(from: Tokarsky, 1974)

Figure 3-2. Meteorology of study area

### 3.6 Measurement of Basic Parameters and Equipment Required for the Present Study

In the following paragraphs, a brief description of the parameters required for coupled non-isothermal field studies will be presented ; for instance, types of materials, hydraulic potential, water content, water characteristic functions, hydraulic conductivity, density and porosity, temperature, thermal conductivity, heat capacity and water and heat fluxes. Also the equipment and methods of installation used to measure the above mentioned parameters will be briefly described.

Hydrometeorological equipment at the study area consisted of a hygromograph placed in an instrument shelter, a Gen atmometer and a standard rain gauge. This instrumentation was installed at Site 1. Each of the two sites was equipped with the instrumentation depicted diagrammatically in Fig. 3-3. Three piezometers were installed at Site 1 (1a, 1b and 1c) and two at Site 2 (2a and 2b) in June 1975. The rest of the instrumentation was installed during June 1976. All lead wires protruding from the ground surface were protected by passing them through rubber tubes, the outer ends of which were covered by plastic bags. For the collection of field data daily or weekly visits to the sites were made at irregular intervals during the summer-early fall 1976 measurement period, hereafter referred to as the 1976 measurement period.

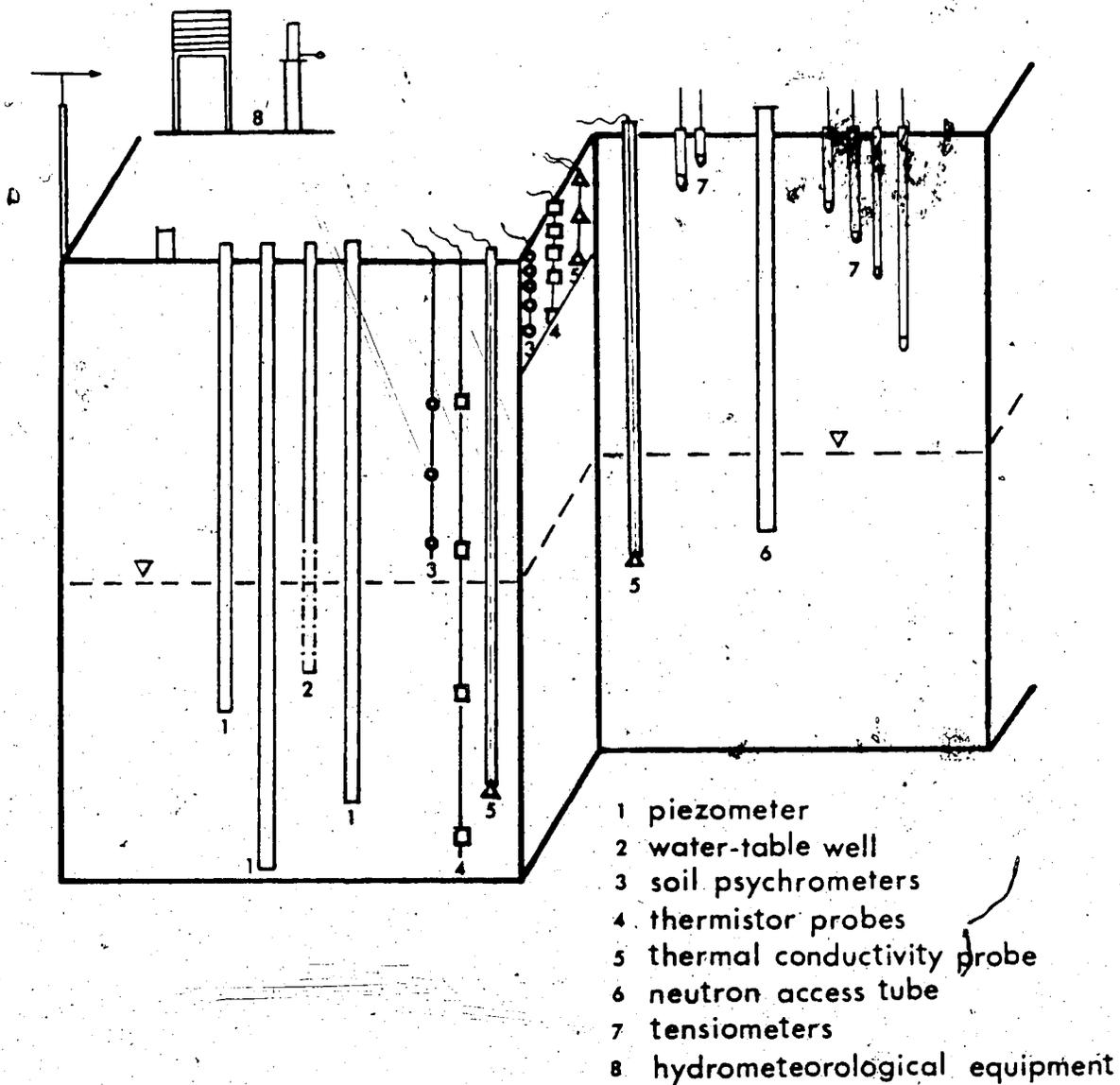


Figure 3-3. Site instrumentation diagram

### 3.6.1 Soil Types

Both sites were sampled during the summers of 1975 and 1976 using a Stirling auger drill and a hollow-stem auger. Depth intervals of approximately 30 cm -- with a finer spacing for the upper layers of the profile -- were sampled down to 485 cm depth. Soil texture was determined in the laboratory using the hydrometer method (Day, 1965).

### 3.6.2 Hydraulic Potential

#### 3.6.2.1 Piezometers

Piezometers were installed in order to measure saturated hydraulic potentials at the sites. They were constructed from 3.8 cm I. D. PVC pipe. The lower 30 cm of each pipe were hacksaw slotted and wrapped with fiberglass tape to form an intake, and the lower end of the pipe was capped. The piezometers were emplaced by lowering them inside of the 15 cm hollow-stem auger after the center-bit was removed. A mixture of sand from the hole and pea gravel was poured around the outside of the PVC pipe to cover the slotted interval. The hole was then filled with the excavated material and the surface around the protruding end of the pipe was sealed with bentonite. The upper end of the piezometer was capped using a PVC fitting with a small hole drilled in it for pressure equalization.

Two piezometers (1d and 2d) were neither slotted nor

capped at the lower end but a stainless steel screen of approximately 1 mm mesh was attached to the lower end of the tube. The purpose of this type of instrumentation was to enable calculation of predominantly vertical hydraulic conductivities, as will be discussed later (Sections 3.6.5 and 3.7.6).

Piezometers were installed at the following approximate depths: 565 (1b), 435 (1d), 405 (1c) and 350 (1a) cm at Site 1 and 475 (2b), 440 (2d) and 390 (2a) cm at Site 2. After installation, the piezometers were developed by repeated bailing.

#### 3.6.2.2 Tensiometers

Although the pressure potential or head is positive compared to atmospheric pressure under saturated conditions, it is negative under unsaturated conditions. This negative pressure head is due to capillary and adsorptive forces which attract and bind water in the soil and thus lower its potential energy below that of bulk water (Hillel, 1971). Tensiometers (Richards, 1949, 1965; Klute and Gardner, 1962) are used to measure negative pressure head up to approximately -0.8 bar, which is the air-entry or bubbling pressure of the tensiometer porous cup.

All tensiometers were tested in the laboratory prior to installation in the field and the porous cup conductance and response time constant for most of them were determined

according to the procedures outlined in Danielson (1956). The average response time constant was approximately 2 minutes. Scales directly reading in cm H<sub>2</sub>O were attached to each mercury manometer tensiometer and adjusted for the zero reading.

For field installation, a hole was made in the soil to the appropriate depth using an approximately 2.5 cm I. D. King tube. Before inserting the tensiometer, a handful of loose soil from the hole and a small amount of water was poured into the hole to insure water continuity between the tensiometer cup and the soil. The tensiometer was inserted into the hole with a twisting downward motion and the soil surface around the tensiometer was sealed with a small amount of bentonite. Tensiometers were installed in duplicate at both sites to depths of approximately 30, 60, 90, 120 and 180 cm in a semicircle around the neutron access tube (Section 3.6.3). After installation, all tensiometers in each nest were filled with deaerated distilled water and the mercury pot was filled.

In order to minimize the influence of temperature on the operation of the tensiometers, the first reading of the field instruments was taken as early in the morning as possible before the sun had warmed the tensiometers to a temperature different from that of the soil.

### 3.6.2.3 Soil Psychrometers

Because the upper limit of the tensiometer range is about -0.8 atmospheres, soil psychrometers are used to measure water potential at higher tensions or suctions. Soil psychrometers are thermocouple psychrometers which measure the relative vapor pressure or relative humidity of the water vapor in a system (Brown and van Haveren, 1972). Soil water potential may be inferred from measurements of relative humidity  $h$  using the thermodynamic relation (Rose, 1966)

$$\psi = (RT/Mg) \ln h \quad (3-1)$$

Because the vapor pressure depends on both the matric (or negative pressure head) and osmotic components of the soil water potential, psychrometers measure both components while tensiometers only measure the matric component of soil water potential.

The psychrometers used for this study were of the Peltier type. They were constructed following procedures outlined in Wiebe et al. (1971) and Lopushinsky and Klock (1970), except that ready-made Chromel-Constantan (0.025 mm in diameter from Omega Engineering Inc.) thermocouple junctions were used. The thermocouple junction was protected by a cup-shaped ceramic bulb, constructed using methods described by Lopushinsky and Klock (1970). These ceramic bulbs were checked for their air-entry value by means of a hanging water column. The ceramic cup was considered

satisfactory if the air-entry value was in the range of at least 200 cm H<sub>2</sub>O. Prior to the insertion of the porous cup, thermocouple junctions were cleaned carefully using an ultrasonic device. All soil psychrometers were calibrated under controlled temperature conditions with KCL salt solutions for which the vapor pressure was known. Fig. 3-4 shows two of the calibration curves obtained. A number of ready-made Wescor Inc. psychrometers were also used.

For field installation, a trench approximately 90 cm deep was dug at each site (Fig. 3-3) and two or three soil psychrometers were emplaced in the side walls of the trench at chosen depths. The copper lead wires were laid horizontally in the trench for a short distance before being brought to the ground surface. At depths greater than 90 cm, the psychrometers were taped in pairs on a wooden dowel at the appropriate depths and the dowel was inserted in an augered hole. Psychrometers were installed at depths ranging from approximately 1 cm to 240 cm. The field recording apparatus consisted of a battery operated Keithley 150B microvolt ammeter, a milliamperemeter and an HP field chart recorder (Moseley 7100B).

### 3.6.3 Water Table and Water Content

Water table wells were constructed by slotting PVC pipe throughout most of its length, wrapping it with fiberglass and emplacing it in boreholes. The volumetric water content

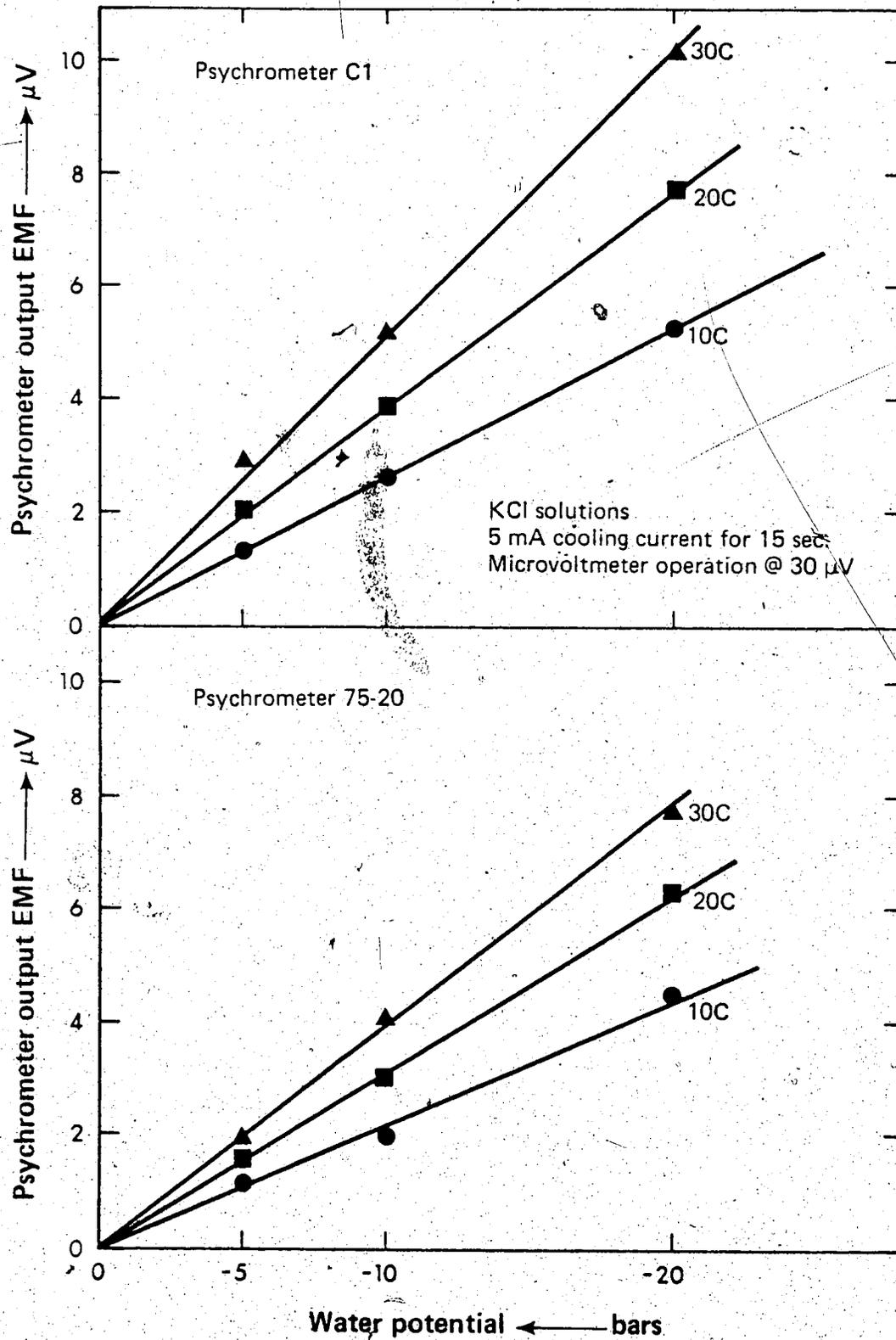


Figure 3-4. Psychrometer calibration curves

from a depth of approximately 20 cm below the ground surface down to the water table was measured using the neutron scattering method (Gardner, 1965; Long and French, 1967). At each site, an aluminum access tube, approximately 4 meters long, 4.0 cm I. D. and sealed at its bottom, was inserted in an augered hole. A Nuclear-Chicago model 5810 neutron depth probe in conjunction with a portable scaler model 5920 was used to take three one-minute counts for each 15 or 30 cm depth interval. Standard counts were taken before and after water content measurements. The ratio of the average count to the average standard count was used in a linear regression equation provided by the manufacturer to estimate the water content on a volumetric basis.

Prior to field use, the neutron probe was calibrated using a sand with a composition similar to that at the field sites. This sand was passed through a 2 mm sieve and was packed in layers to an average density of  $1.5 \text{ gm/cm}^3$  in a  $0.22 \text{ m}^3$  drum. By sampling the sand for moisture content using a small hand auger, and comparing the average water content of two samples for each depth with that obtained using the neutron probe, the calibration curve of Fig. 3-5 was obtained. The linear regression equation was used to obtain a best fit to the measured data.

#### 3.6.4 Water Characteristic Curves

The relation between water content and pressure head

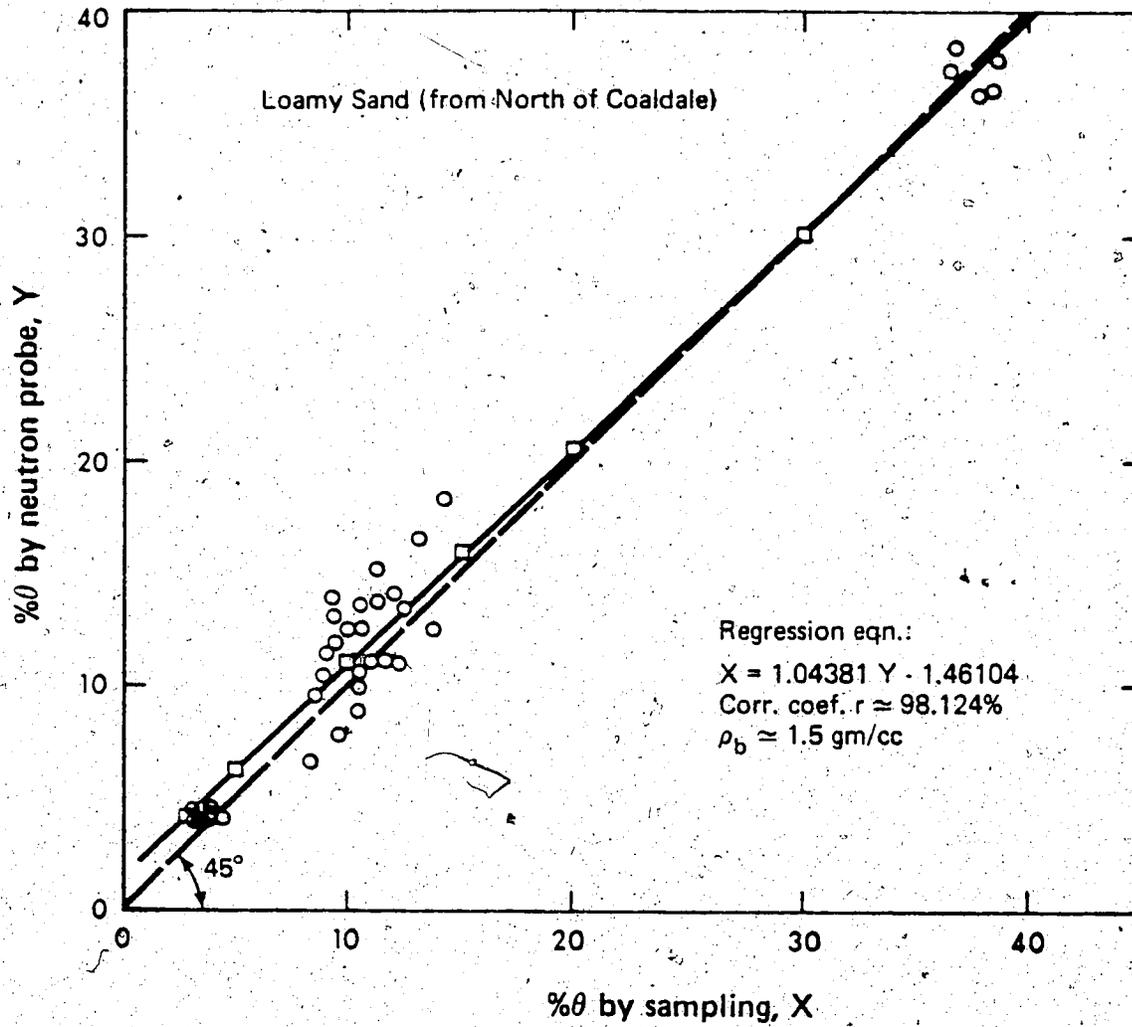


Figure 3-5. Neutron calibration curve

(water characteristic curve) at each site was obtained from simultaneous field measurements using the neutron probe and the tensiometers. However, due to the limited range of water contents and pressure heads observed during the measurement period, characteristic curves were determined in the laboratory in order to check the field results and to extend the range of measurements.

Four separate methods were utilized for testing the soil samples in the laboratory in order to obtain water characteristic curves over a sufficiently wide range of tensions. For tensions above 15 bars, vapor equilibration techniques involving saturated  $H_2SO_4$  solutions were employed (Danielson, 1956). For measurements in the 1 to 15 bar tension range, a procedure described by Richards (1954, 1965) involving a pressure membrane apparatus was used. For the tension range of 100 to 1,000 mb, pressure cookers with ceramic porous plates were utilized (Richards, 1954, 1965). A saturation-capillary pressure (or pressure head) experiment (Laliberte et al., 1966) was employed to measure the water characteristic function for tensions less than 100 mb. Data from gravimetric moisture determinations were converted to volumetric moisture contents by multiplying by the bulk density of the soil samples.

### 3.6.5 Hydraulic Conductivity

#### 3.6.5.1 Saturated Hydraulic Conductivity

The saturated hydraulic conductivity was measured in the field using the piezometer method (Kirkham, 1955; Hvorslev, 1951). When the inlet section of a piezometer is constructed by slotting the casing, hydraulic conductivity is measured essentially in a horizontal direction while with only the end of the casing available as an intake, hydraulic conductivity is determined in a predominantly vertical direction.

The hydraulic conductivity is determined by the use of the following formula based on Darcy's equation (Kirkham, 1945)

$$K = [\pi R^2 \ln(y_1/y_2)] / [S(t_2 - t_1)] \quad (3-2)$$

or, using Hvorslev's (1951) definition of basic time lag  $T'$ ,

$$K = \pi R^2 / (ST') \quad (3-3)$$

where  $R$  is the radius of the piezometer;

$y_1$  is the distance from the water table to the water level in the piezometer at time  $t_1$ ;

$y_2$  is the distance from the water table to the water level in the piezometer at time  $t_2$ ;

$S$  is a shape factor with dimensions of length which depends on the geometry of the intake of the piezometer.

Values of the shape factor for different configurations of

the piezometer intake are given by Luthin and Kirkham (1949), Hvorslev (1951), Youngs (1968), among others. For the slotted piezometers used in this study, the shape factor is given as (Hvorslev, 1951)

$$S = 2\pi L / [ \ln \{ L/D + \sqrt{1 + (L/D)^2} \} ] \quad (3-4)$$

(where L and D are the length and diameter of the piezometer intake respectively), or as a graph relating S/D vs L/D (Luthin and Kirkham, 1949; Al-Dhahir and Morgenstern, 1969), or as a table of values presented by Youngs (1968). For the open end piezometer, Hvorslev (1951) proposed

$$S = 2.75D \quad (3-5a)$$

while Luthin and Kirkham (1949) suggested

$$S = 2.45D \quad (3-5b)$$

The latter relation is preferred by Maasland (1957) because the first one (3-5a) is based on small tank experiments.

Saturated hydraulic conductivity of disturbed 1 mm sieve samples was also determined in the laboratory using the constant head method (Klute, 1965).

### 3.6.5.2 Unsaturated Hydraulic Conductivity

Unsaturated hydraulic conductivity over a range of water contents was determined in the laboratory using the methods of Brooks and Corey (1964) and Laliberte et al. (1966). It was shown (Brust et al., 1968; Klute, 1972) that these methods agree better with field measured conductivities than others.

Briefly, the determination procedure was as follows. An average characteristic (desaturation) curve ( $\psi$  vs  $S_w$  or  $\theta$ ) obtained from three soil samples was derived and the relationship between hydraulic conductivity and pressure head was determined. The methods and equipment employed were those described in Brooks and Corey (1964), Anat et al. (1965), Laliberte et al. (1966), van Schaik and Laliberte (1968) and van Schaik and Graham (1969). From the desaturation curve, the residual saturation  $S_r$  was determined by a trial and error procedure (Brooks and Corey, 1964). The effective saturation  $S_e$ , defined by Brooks and Corey (1964) as

$$S_e = (S_w - S_r) / (1 - S_r) \quad (3-6)$$

is linear for  $S_e$  less than approximately 0.8 when plotted versus  $\psi$  on a log-log paper. The slope of this straight line portion is called the pore-size distribution index  $\lambda'$  (Brooks and Corey, 1964). The intercept of the straight line at  $S_e = 1.0$  is called the bubbling or air entry pressure  $\psi_b$ , which corresponds very closely to the minimum pressure head at which air begins to enter a saturated porous medium and the gas phase first becomes continuous. The relative hydraulic conductivity  $K_r (=K/K_{sat})$ , may then be calculated as

$$K_r = S_e^{(2+3\lambda')} / \lambda' \quad (3-7)$$

or

$$K_r = (\psi_b / \psi)^\eta \quad \text{for } \psi < \psi_b \quad (3-8)$$

where  $\eta = 2 + 3\lambda'$ .

Accordingly, by combining the experimental desaturation data with the calculated value of residual saturation, the relationship between  $\psi$  and  $\theta$  from saturation to residual saturation is obtained. When the experimentally determined  $K_r$  vs  $\psi$  relationship is plotted on a log-log paper, a straight line results for  $\psi < \psi_b$ , as is implied by (3-8) above. This line has a slope of  $-\eta$  and intercepts the  $\psi$ -axis at the air-entry pressure  $\psi_b$ , where  $K_r = 1.0$ . This straight line may be extrapolated to higher absolute values of  $\psi$ . Thus, by combining this  $K_r$  vs  $\psi$  relation with the  $\psi$  vs  $\theta$  relationship for the same soil, the hydraulic conductivity as a function of water content from residual saturation to saturation is obtained.

The unsaturated hydraulic conductivity may also be determined in the field using a water balance equation as described by Rose et al. (1965) and others.

$$q_w/\rho = R + I - E - \int_0^z \partial\theta/\partial t dz \quad (3-9)$$

where  $R$  is the rate of precipitation (actually "effective" precipitation);

$I$  is the rate of irrigation application;

$E$  is the evaporation rate.

Once the unsaturated water flux  $q_w/\rho$  is known (Section 3.6.10.2), the isothermal and non-isothermal expression for  $q_w/\rho$  (2-38) in one-dimensional form may be used to calculate  $K$ . Thus, using the non-isothermal water flux equation (2-38) in combination with (2-37), the unsaturated hydraulic conductivity may be calculated as

follows

$$|K| = \frac{q_w/\rho + K_{\psi} \partial\psi/\partial z + D_{Tv} \partial T/\partial z}{-\partial\psi/\partial z - (R/Mg) |\ln h| \partial T/\partial z + 1} \quad (3-10)$$

or, using the much simpler isothermal water flux equation (2-22)

$$|K| = (q_w/\rho) / (-\partial\psi/\partial z) + 1 \quad (3-11)$$

The procedures for calculating hydraulic conductivity proposed by Brooks and Corey (1964) using (3-7) or (3-8), or those developed by Childs and Collis-George (1950), Marshall (1958) and Millington and Quirk (1959, 1960) using the water characteristic function become field methods if the water characteristic is determined by field measurements. Although these methods may be adequate for wet soils which satisfy the capillary model of flow, they are not satisfactory for drier soils. In this case, adsorptive forces become dominant and the above capillary tension-based models may not be adequate (Gardner, 1974). These computational methods for obtaining the hydraulic conductivity function are most successful when applied to soils possessing a narrow range of pore size distributions (Nielsen et al., 1972). For well-aggregated soils, where considerable amounts of water are relatively immobile in intra-aggregate pores (residual saturation), better results are obtained if the water-filled pore space  $S_w$  is replaced by an effective water-filled pore space ( $S_w - S_r$ ), as was done in the method of Brooks and Corey (1964).

### 3.6.6 Density and Porosity

Bulk density was calculated from cores of known volume obtained in the field to depths of approximately 90 cm. Alternatively, a Cs-gamma density probe (Model P205) was also used to measure bulk densities at various depths.

Particle densities were determined using the pycnometer method (Blake, 1965). Once bulk and particle density is known, porosity  $\phi$  can be determined from the following relationship:

$$\phi = 1 - (\rho_b / \rho_s) \quad (3-12)$$

where  $\rho_b$  is bulk density and  
 $\rho_s$  is particle density.

### 3.6.7 Temperature

Soil temperatures were measured in the field using general purpose rugged thermistor probes of the series 400 (Fisher Catalogue No. 15-176-22) in combination with a YSI Telethermometer model 42. All thermistor probes were calibrated in the laboratory with mercury thermometers. The average thermistor temperature deviated less than 0.11 C from the mercury thermometer temperature in the range of 0 to 30 C. For field installation, the same procedure as for the soil psychrometers was used. Thermistors were emplaced at depths of approximately 1, 2.5, 5, 10, 30, 60, 120, 250, 370 and 500 cm at both study sites.

Air temperatures were measured using a hygrothermograph which provided continuous temperature and air humidity recordings over weekly periods. The hygrothermograph, which was also checked for accuracy in the laboratory, was placed in an instrument shelter approximately 1.3 meters above the ground surface.

### 3.6.8 Thermal Conductivity

The thermal conductivity of the subsurface profile at the field sites was measured using thermal conductivity probes (Blackwell, 1954; Jaeger, 1956; Carslaw and Jaeger, 1959; de Vries and Peck, 1958a). The following formula is applied for such determinations

$$\lambda = [Q \ln(t_2/t_1)] / [4\pi(T_2 - T_1)] \quad (3-13)$$

where  $\lambda$  is the thermal conductivity of the porous medium (cal/cm/sec/C);

$Q = I^2 R'$  is the heat produced per unit time and unit length of the probe heating element;  $I$  is the current and  $R'$  is the resistance per centimeter of the heat source;

$(T_2 - T_1)$  is the temperature rise (or drop) during the time interval  $(t_2 - t_1)$ .

The thermal conductivity probes used for this study were similar to those described by Slusarchuk and Foulger

(1973).<sup>1</sup> The following modifications were employed. One bead thermistor (GB35L1-Fenwal Electronics, "Thermistor Manual") was potted in a hole in the wall of a 4.85 mm OD plastic tube. Teflon-coated constantan wire (of 0.127 mm diameter plus 3 mil teflon wall) was wound tightly in a bifilar manner around the plastic tube using a lathe to form a heating element approximately 33 cm long. The four lead wires (2 thermistor leads and 2 constantan leads) were connected to a four-wire coaxial cable. A stainless steel ring, 3.8 cm in diameter, with a groove near its perimeter and small protruding rods from two opposite sides, was attached near the top of the 8.0 mm O.D. stainless steel tube. A plastic cap was then glued into the groove of the ring to seal and protect the lead wire-coaxial cable junctions. An arch-shaped thin stainless steel rod was attached to the ring. A long steel wire was connected to the arch for recovery purposes (Fig. 3-6). The probes were checked for leaks by inserting them for several days in a long pipe filled with water.

In order to insert and recover the probes at depths below the water table, a device was designed (Fig. 3-7) to fit and lock on the two protruding rods of the ring mentioned above. This device was connected to steel rods

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<sup>1</sup>Details on the operation and construction of thermal conductivity probes may also be found in Wechsler (1966); Janse and Borel (1965); Jackson and Taylor (1965); Beck et al. (1971), Fritton et al. (1974), among others.

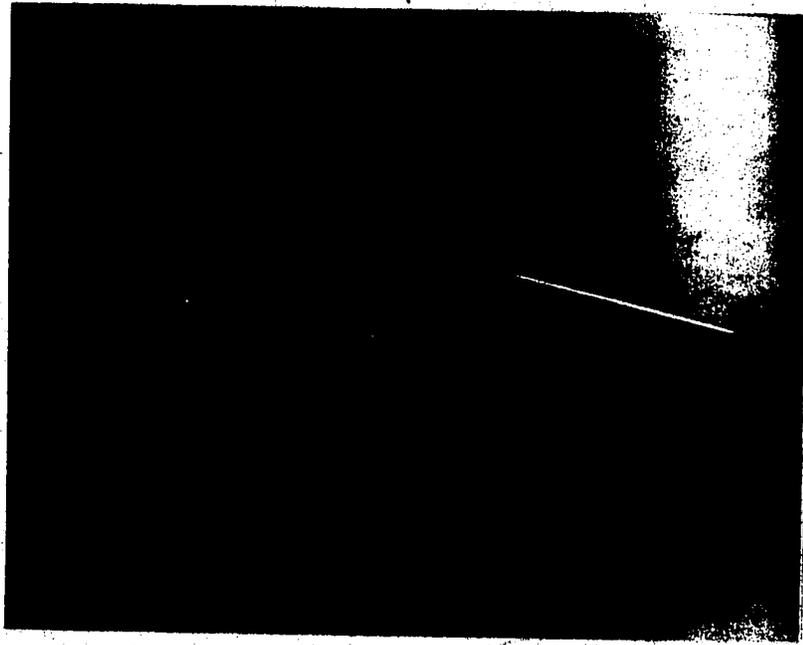


Figure 3-6. Thermal conductivity probe

which fit together to facilitate installation in boreholes of any desired depth. Aluminum conduit tubes, approximately 5 cm in diameter, were inserted in drilled holes at depths of approximately 305 and 340 cm in Site 1, and 375 cm and 440 cm in Site 2. The conductivity probes were emplaced into the soil at the bottom of the conduit tubes by using the device described above. At shallower depths of approximately 6, 30 and 60 cm the probes were simply inserted horizontally into the walls of the trench dug at each site. In all cases, only the heating curve was considered. The duration of each experiment in the field was approximately 12 minutes.

Prior to field installation, the thermal conductivity probes were calibrated in the laboratory using air-dry and water-saturated 20/30 mesh Ottawa sand (ASTM designation C-190). A 12 V battery in combination with an EICO converter and a Lambda voltage regulator was used (Fig. 3-8) to provide a constant voltage source of 40 V in the field and laboratory experiments. A digital multimeter was used to monitor the change of the resistance of the heater element with time. A typical calibration curve is shown in Fig. 3-9, where the thermal conductivity of the dry Ottawa sand calculated at three different times is shown in order to indicate the variation of thermal conductivity measurements. (The thermistor resistance versus temperature curve was plotted using the manufacturer's data). A random check of the thermistor resistance and the temperature indicated by a mercury thermometer showed a satisfactory agreement with the

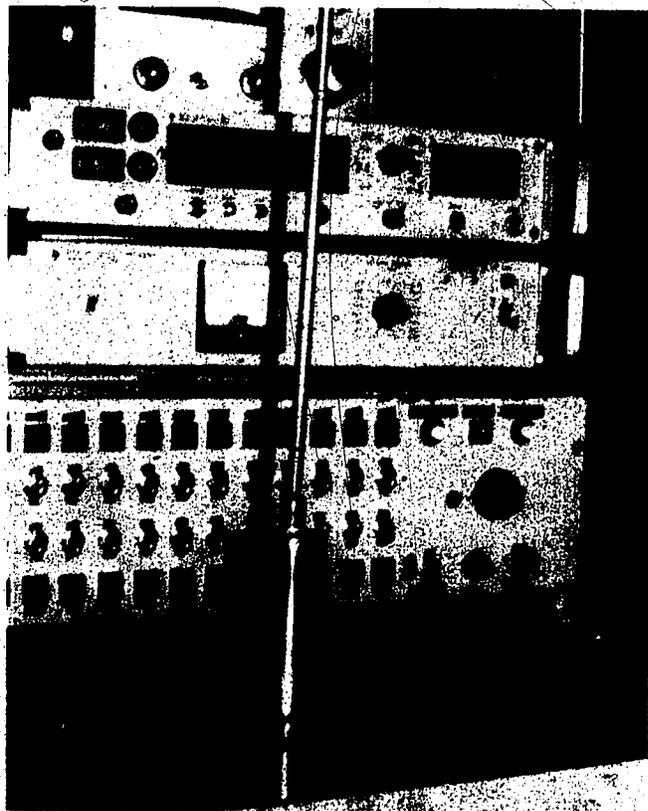


Figure 3-7. Thermal conductivity probe insertion and recovery apparatus

plotted curve. Comparison of the mean value of thermal conductivity for the coarse-grained dry Ottawa sand obtained from five probes ( $\lambda = 7.214 \times 10^{-4}$  cal/cm/sec/C) by Slusarchuk and Foulger (1973) as well as of their guarded hot plate value ( $7.262 \times 10^{-4}$  cal/cm/sec/C) -- which was treated as their thermal conductivity standard -- with the mean value  $\{(7.114 \pm 0.168) \times 10^{-4}$  cal/cm/sec/C} obtained from our ten probes under the same conditions, showed a satisfactory correspondence (Table 3-1). For calibration purposes, the ratios of our air-dry and saturated Ottawa sand thermal conductivities for each probe to those of Slusarchuk and Foulger (1973) using the guarded hot plate apparatus were joined by straight lines, assuming a linear relationship between thermal conductivity and water content. Therefore, at intermediate water contents between air dryness and saturation, the calculated thermal conductivity may be divided by the above mentioned ratio at the appropriate water content to give a standardized thermal conductivity value.

Several empirical (Kersten, 1949) and semi-empirical equations (de Vries, 1963) have been developed for calculating  $\lambda$ . However, as van Rooyen and Winterkorn (1957) indicated, none of those equations was able to give consistently dependable results. The thermal conductivity probe method avoids all problems involved with a theoretical calculation of thermal conductivity (Kimball et al., 1976, Hadas, 1977).

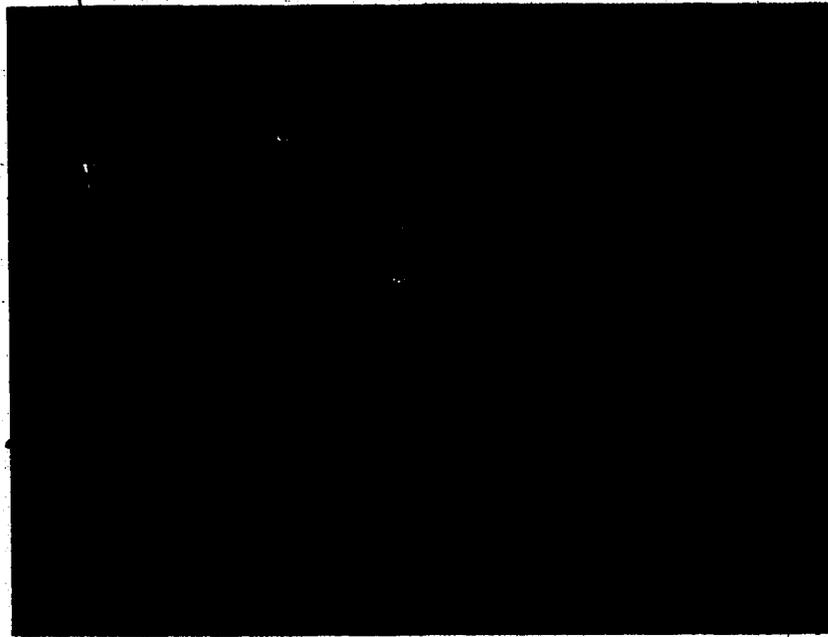
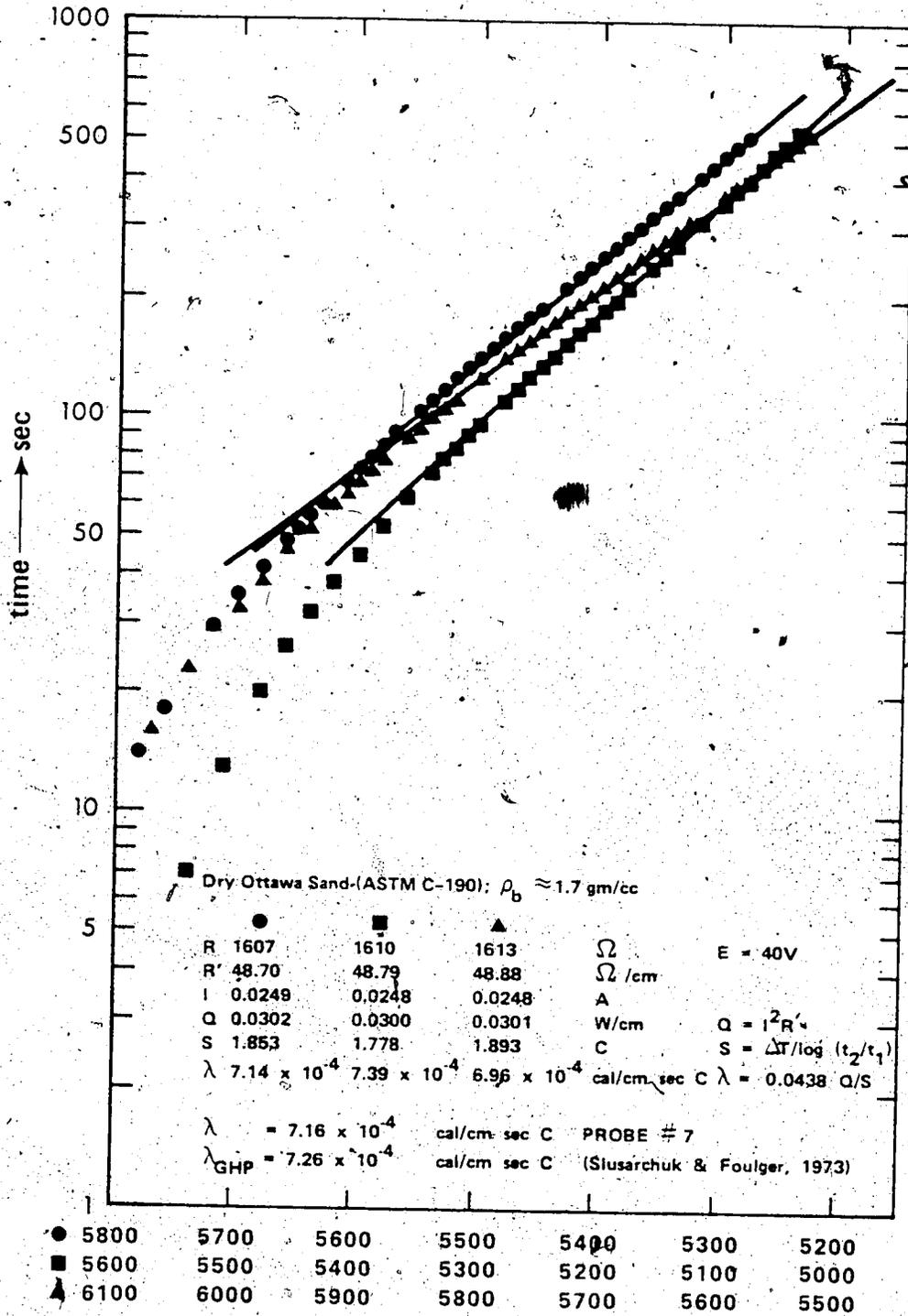


Figure 3-8. Field equipment for thermal conductivity measurements



R thermistor  $\leftarrow \Omega$   
 Figure 3-9. Typical calibration curves for thermal conductivity measurements

TABLE 3-1

Measured thermal conductivity of air-dry 20/30 mesh Ottawa sand

Probe	Thermal Conductivity* $\lambda \times 10^{-4}$ (cal/cm sec C)	Ratio of measured $\lambda$ to the GHP** value obtained using the GHP**
1	7.137	0.983
2	8.197	1.129
3	6.303	0.868
4	7.150	0.985
5	6.910	0.951
6	6.433	0.886
7	7.163	0.986
8	7.320	1.008
9	7.032	0.968
10	7.497	1.032

Mean  $\lambda$   $7.114 \times 10^{-4}$   
 Standard error of mean,  $S_m$   $1.679 \times 10^{-5}$

\*Each entry represents an average of 3 to 4 determinations.  
 \*\*Guarded hot plate:  $\lambda_{GHP} = 7.262 \times 10^{-4}$  cal/cm sec C (Slusarchuk and Foulger, 1973)  
 \*\*\* $S_m = s/\sqrt{n}$ , where s is the standard deviation.

### 3.6.9 Heat capacity

The volumetric heat capacity of a soil (de Vries, 1963) can be found by adding the heat capacities of the mineral matter ( $C_{mm}$ ), the organic matter ( $C_o$ ), the water ( $C_w$ ) and the air constituents in a unit volume of porous medium. The heat capacity of air is very small and can be neglected. Thus, the volumetric heat capacity of a soil is given as

$$C = x_{mm}C_{mm} + x_oC_o + \theta C_w \quad (3-14)$$

where  $C$  is the volumetric heat capacity ( $\text{cal/cm}^3/\text{C}$ ) of a moist porous medium and  $x_{mm}$ ,  $x_o$  are the volumetric fractions of mineral matter and organic matter respectively, and  $\theta$  is the volumetric water content. de Vries (1963) gives the following average values of heat capacities:  $C_{mm} = 0.46 \text{ cal/cm}^3/\text{C}$  and  $C_o = 0.60 \text{ cal/cm}^3/\text{C}$ . The volumetric heat capacity of water is unity. Therefore, the above equation becomes

$$C = 0.46x_{mm} + 0.60x_o + \theta \quad (3-15)$$

for each volume increment of the subsurface profile. Notice that for non-deformable soils and for negligible heat of wetting (Stigter, 1969) the volumetric heat capacity is a linear function of the volumetric water content.

The organic matter content on a weight basis for each 30 cm depth increment (with a finer spacing in the first 30 cm) was determined in the laboratory using a variant of the Walkley and Black (1934) wet oxidation method (Piper, 1950; Richards, 1954).

In order to obtain the volumetric percentages of organic and mineral fractions of the various soil layers, an average organic matter density of  $1.3 \text{ gm/cm}^3$  (de Vries, 1963) was assumed. The average mineral particle density was found to be  $2.64 \text{ gm/cm}^3$  in the top 60 cm of the profile. This value was assigned to the entire subsurface profile. Using these density values together with the field-measured bulk densities, the organic and mineral matter fractions  $x_o$  and  $x_{mm}$  were calculated as follows:

$$x_o = \alpha' (\rho_b / \rho_s) \quad (3-16)$$

$$x_{mm} = (1 - \alpha') \rho_b / \rho_s \quad (3-17)$$

where  $\alpha'$  is the organic matter fraction by weight, measured experimentally. Values of  $x_o$  and  $x_{mm}$  at each depth in the profile remain constant for non-deformable media. However, because the volumetric water percentage  $\theta$  varies in time, the volumetric heat capacity (3-14) varies as a function of time.

### 3.6.10 Heat and Water Fluxes

#### 3.6.10.1 Heat Flux

The heat fluxes at different depths in the subsurface profile were computed by the temperature integral or calorimetric method (Portman, 1954; Lettau and Davidson, 1957; Tanner, 1963; Kimball and Jackson, 1975). In this method, the heat flux is calculated from the change of the heat content or storage in the subsurface profile over a

given time interval. The equation for the heat flux computation can be derived from the heat balance equation (2-62), which in one-dimensional form is

$$C \partial T / \partial t = -\partial q_h / \partial z \quad (3-18)$$

Multiplying both sides of (3-18) by  $dz$  and integrating from depth  $z$  to depth  $z+dz$  results in

$$q_h|_z = q_h|_{z+dz} + \int_z^{z+dz} C \partial T / \partial t dz \quad (3-19)$$

The term under the integral represents the change in heat content per unit time. Equation (3-19) is applied by dividing the subsurface profile into  $N$  layers of thickness  $\Delta z_i$ . Accordingly, it is possible to discretize (3-19) in the following manner:

$$q_h|_i = q_h|_{i+1} + C_i \Delta z_i \Delta T_i / \Delta t \quad (3-20)$$

Due to the fact that the heat content of all soil layers ( $C_i$ ) can be determined, the heat flux at any depth in the subsurface profile can be computed if the heat flux at any one particular depth can be estimated. Generally, this reference depth is taken to be at least 100 cm (Kimball and Jackson, 1975). In the present study, the reference depth has been chosen below the water table depth, where the heat flux can be calculated from the thermal conductivity and the temperature gradient with reasonable accuracy.

The heat flux meter approach (Lettau and Davidson, 1957; Philip, 1961; Fuchs and Tanner, 1968) might appear to be an attractive alternative to the above procedure, especially if the thermal conductivity of the meter and the porous medium are the same. Unfortunately this approach can

only determine heat flow by conduction because the meter is impervious to liquid and gas. Therefore, heat transfer by water liquid and vapor movement cannot be determined. The same limitation is apparent with the null-alignment method (Kimball and Jackson, 1975), where null points in the temperature gradient are used to provide zero heat fluxes at known depths in the profile.

### 3.6.10.2 Water Flux

The total water flux in the unsaturated zone can be measured in the same way as the heat flux; that is, by accounting for the change of water content in the subsurface profile over a given time interval. If a one-dimensional water balance is employed, the following difference equation is obtained in a manner analogous to (3-20):

$$q_w/\rho L_i = q_w/\rho L_{i+1} + \Delta z_i (\Delta \theta_i / \Delta t) \quad (3-21)$$

Once the water flux at a particular depth is known, the water fluxes along the whole profile can be easily calculated using the above equation (Richards et al., 1956; Rose et al., 1965; Rose and Krishnan, 1967; van Bavel et al., 1968; Flocker et al., 1968; Hillel et al., 1972; Nielsen et al., 1973). However, a reference water flux at a certain depth may not be easy to determine. The major problem with this approach is that the hydraulic conductivity function must be determined. The procedure I have adopted is the following: (1) sample soil from any layer of the subsurface profile and determine the hydraulic

conductivity-water content function in the laboratory; (2) use the non-isothermal flux equation (2-38) in one-dimensional form to calculate the water flux at the bottom of this layer, the  $K$  function being known. Other relevant parameters, such as the depth distribution of hydraulic head, are already known.

The procedure followed by Nielsen et al., 1964, 1973; Davidson et al., 1969, among others -- which involves covering the ground surface with plastic sheets and assuming zero water flux (no evaporation) at the surface -- may not be appropriate under conditions not near saturation. Suppression of evaporation will increase the subsurface temperature regime and change the water vapor flux contribution to total water flow. The method used by Rose (1968c) for calculating bare soil evaporation by application of the principle of water conservation (3-9) in a volume of surface soil, in combination with the non-isothermal water flux equation (2-38) in one-dimensional form, may be preferable. Application at the field sites of the method proposed by Brutsaert (1975) for calculating evaporative fluxes based on non-dimensionless parameters (similarity concepts) resulted in unacceptably high evaporative fluxes. Therefore, this approach was not taken further. With regard to the saturated water flux, this may be calculated from the heat flux equation as suggested in (2-72). (An evaluation of such a method is presented in section 3.8).

The potential evaporative flux from a saturated surface was measured at the field sites using a Gen atmometer (Mukammal, 1961). This atmometer consists of a flat black porous plate (Bellani plate), 7.5 cm in diameter, kept moist by distilled water held in a tube which is connected to a supply reservoir.

### 3.7 Experimental Results and Discussion

#### 3.7.1 Soil Types and Analyses

Site 1 is comprised of uniform medium sand (Figs. 3-10 and 3-11) of an average particle density of  $2.6542 \text{ gm/cm}^3$ . Underlying the sand is a clay loam till found at depths below approximately 5.5 m. However, an isolated clay loam lens was sampled at a 430-460 cm depth interval. The variation with depth of other physical properties of the Site 1 sand is indicated in Fig. 3-10. Although the textural profile is nearly uniform, the saturated hydraulic conductivity is variable (Fig. 3-10). This situation is probably due to differences in the compaction state of the porous material, as well as to experimental errors.

Site 2 has a more complicated geological setting than Site 1. The subsurface units are texturally variable both laterally and vertically, with sandy loam predominating (Fig. 3-11). Fig. 3-12 shows the variation with depth of soil textures, as well as other physical properties of a

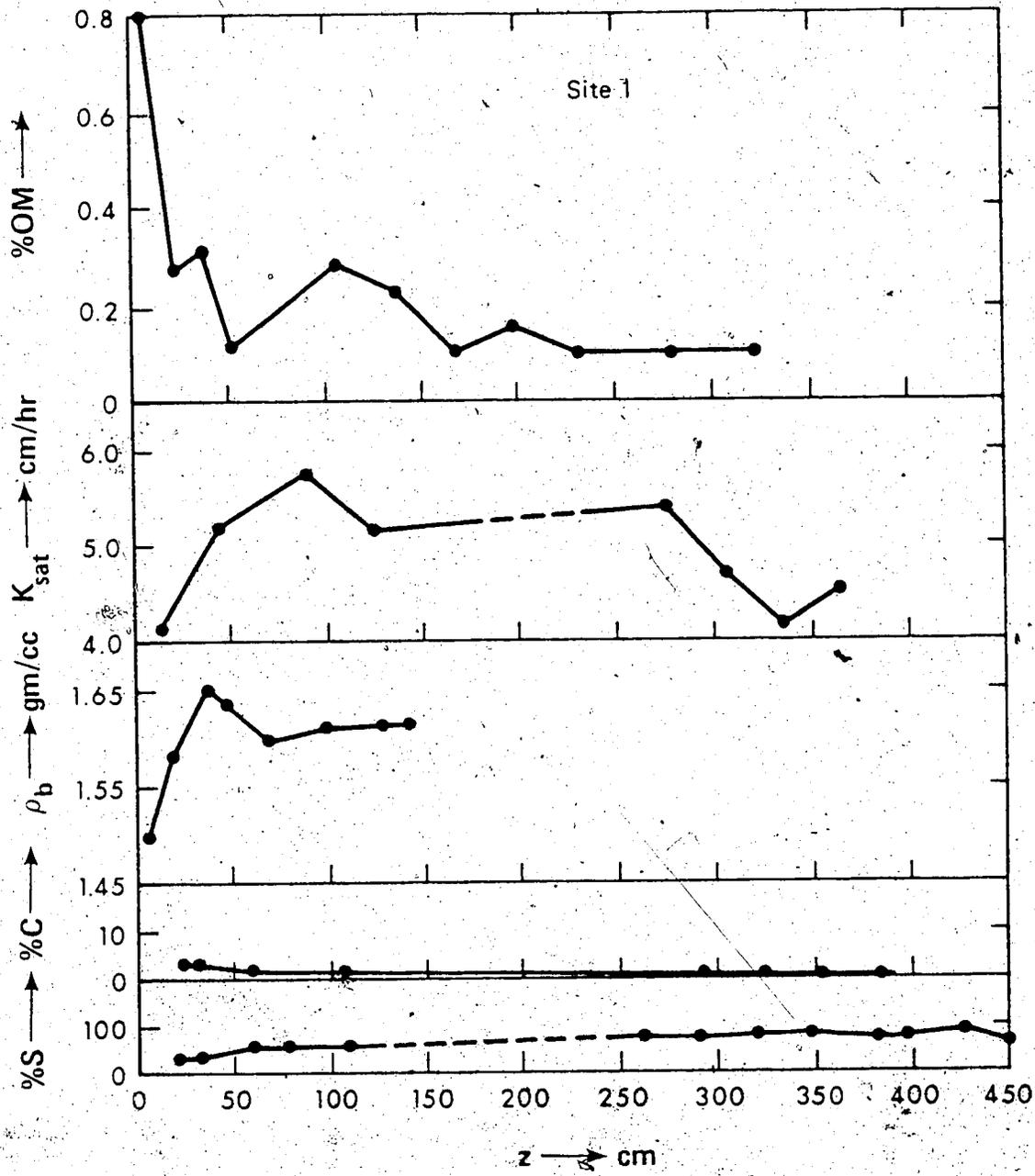


Figure 3-10. Physical properties of Site 1

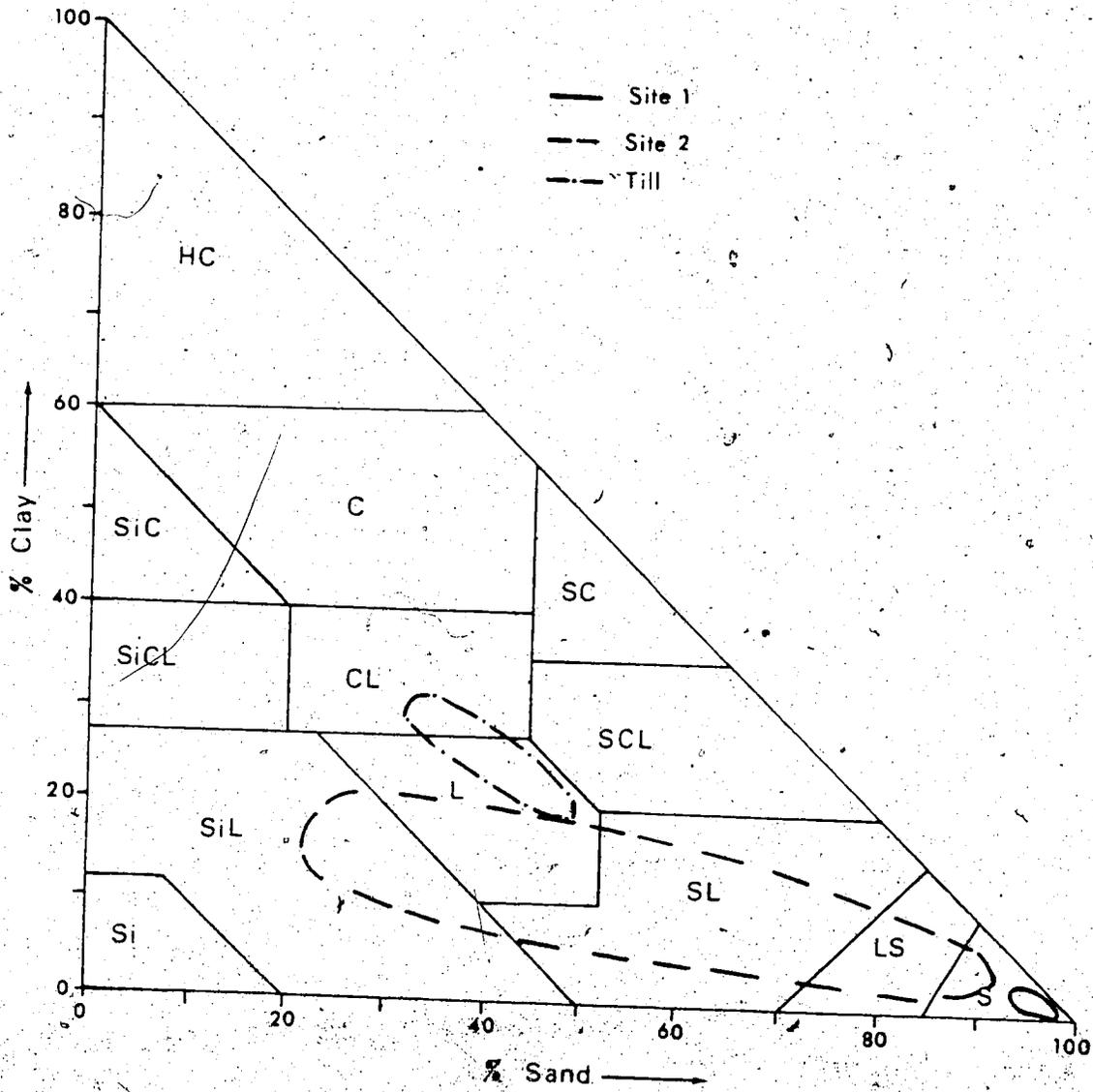


Figure 3-11. Soil texture triangle for the study area

sampled borehole at Site 2. A correlation between percentage of sand and saturated hydraulic conductivity is apparent (Fig. 3-12). The average particle density of the top 30 cm of the soil was  $2.6281 \text{ gm/cm}^3$ .

### 3.7.2 Hydraulic Head

The hydraulic head values at the Taber sites, determined from the piezometers, showed a relatively small fluctuation during the 1975-1976 measurement period (Fig. 3-13). Because of the relatively high hydraulic conductivity of the porous materials of the sites, the recovery rate of each piezometer after removal of water from them was relatively rapid, ranging from a few minutes to several hours depending on where the piezometer was terminated. Therefore, it was not necessary to correct head measurements for the effects of time lag (Hvorslev, 1951; Freeze, 1969b).

The time distribution of hydraulic head as indicated by tensiometers and piezometers at Site 1, as well as the water table fluctuations during a nineteen-hour measurement period, are shown in Fig. 3-14. The advantage of such prolonged measurements is that the diurnal changes of several physical parameters can be studied in detail to assess their significance. From Fig. 3-14 it can be deduced that the direction of flow was generally downwards. However, the direction of flow was not always constant depending on whether water was infiltrating after a rainfall or was

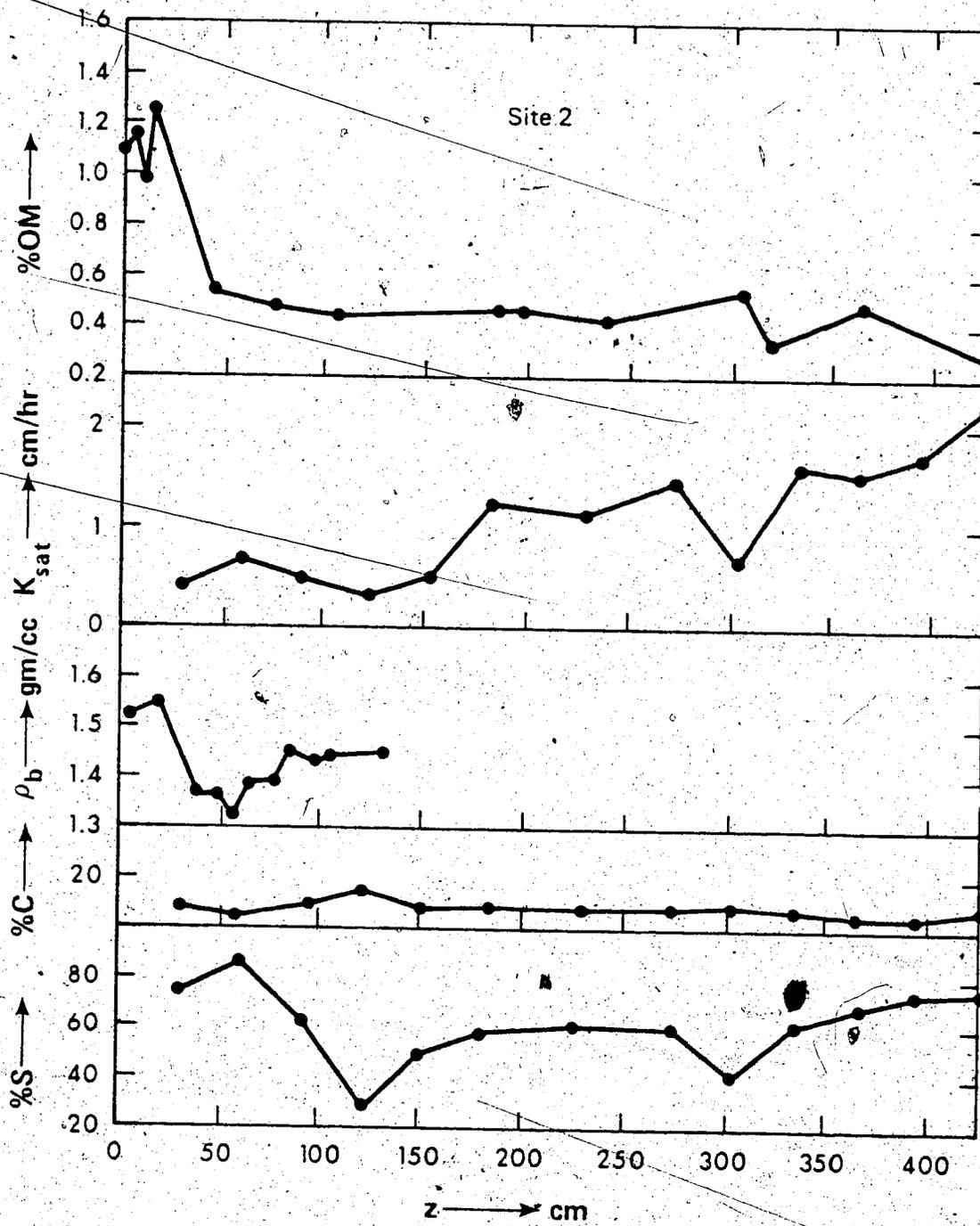


Figure 3-12. Physical properties of Site 2

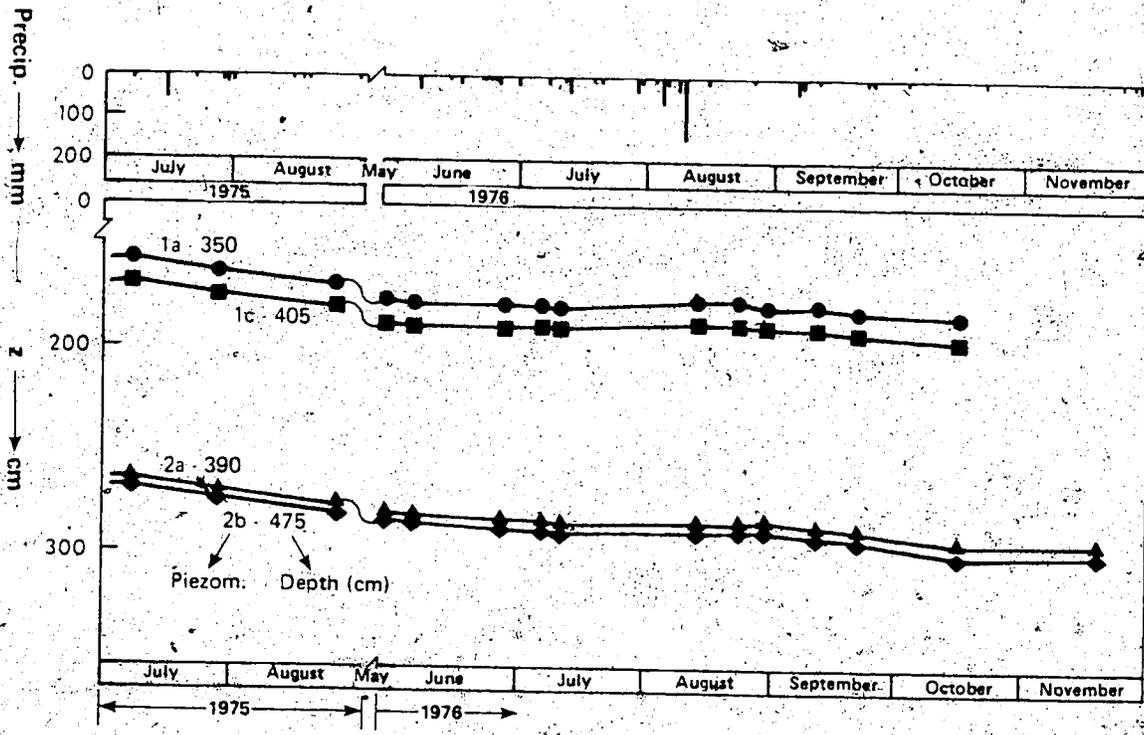


Figure 3-13. Time distribution of piezometric water levels

evaporating during an extended drying period. For example, the period of measurements depicted in Fig. 3-14 (August 11-12, 1976) followed a period of significant rainfall (Fig. 3-13) and water was still percolating downward. However, toward the end of the measurement period, the hydraulic head gradient between tensiometer 6 and piezometer 1a was reversed, indicating the completion of the percolation process and a return to evaporation-controlled upward flow. The piezometric head distribution indicated downward water flow at shallow depths superimposed on a deeper upward water flow condition (Fig. 3-14). This saturated flow pattern was consistent throughout the 1976 measurement period.

The hydraulic head distribution at Site 2 was more complicated and variable than at Site 1. The significant degree of heterogeneity of the subsurface profile of Site 2 contributed to this hydraulic head pattern. Fig. 3-15 presents a twenty-four-hour measurement of hydraulic head, where a reversal of hydraulic head gradient between tensiometers 4 and 6 is observed twice during that measurement period. However, the observed hydraulic head distribution in the saturated zone with an upward water flow pattern at shallow depths superimposed on a deeper downward water flow pattern was consistent throughout the 1976 measurement period.

Despite the care taken in constructing and calibrating the soil psychrometers, their performance in the field was

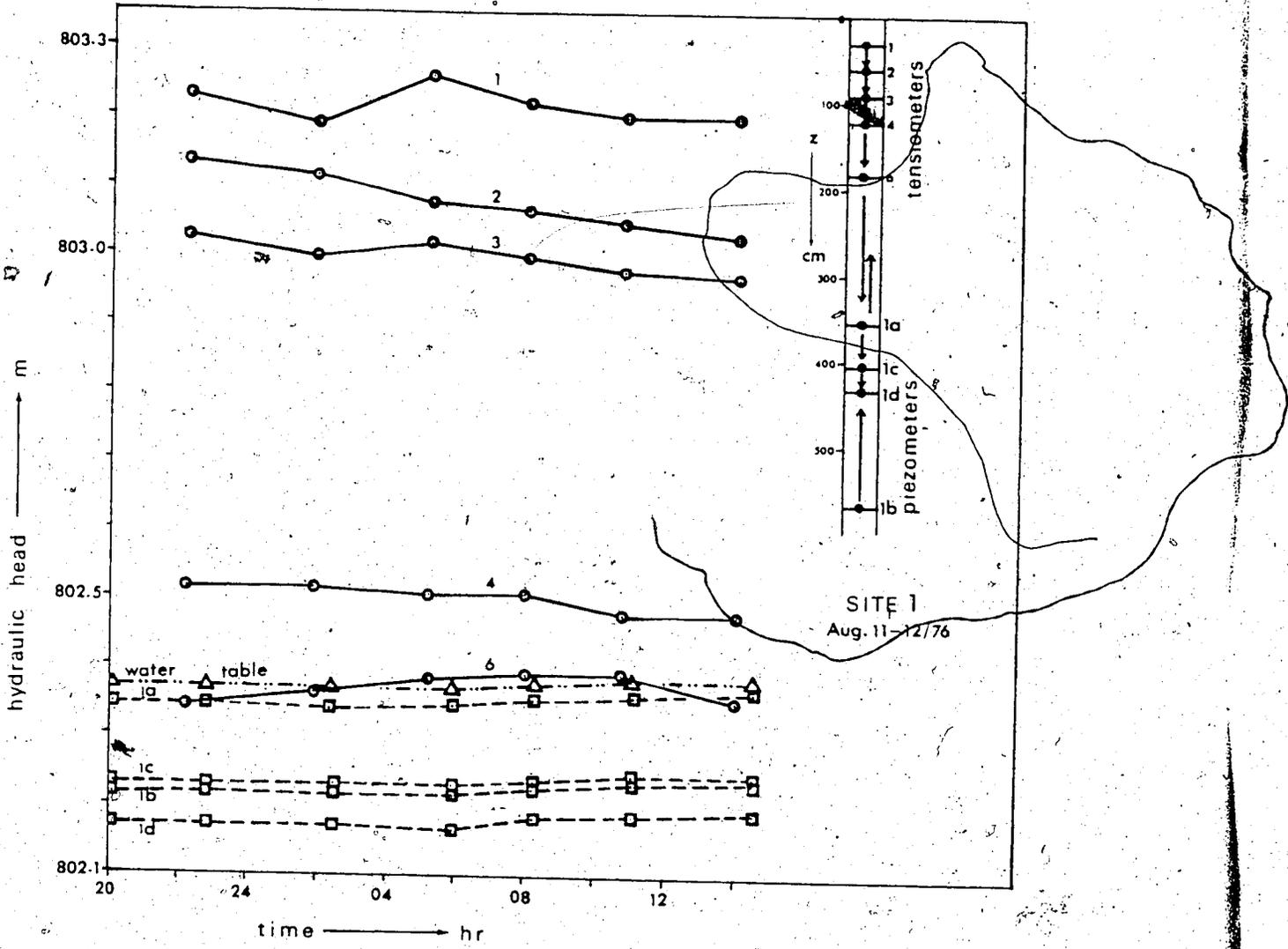


Figure 3-14. Time distribution of hydraulic head at Site 1

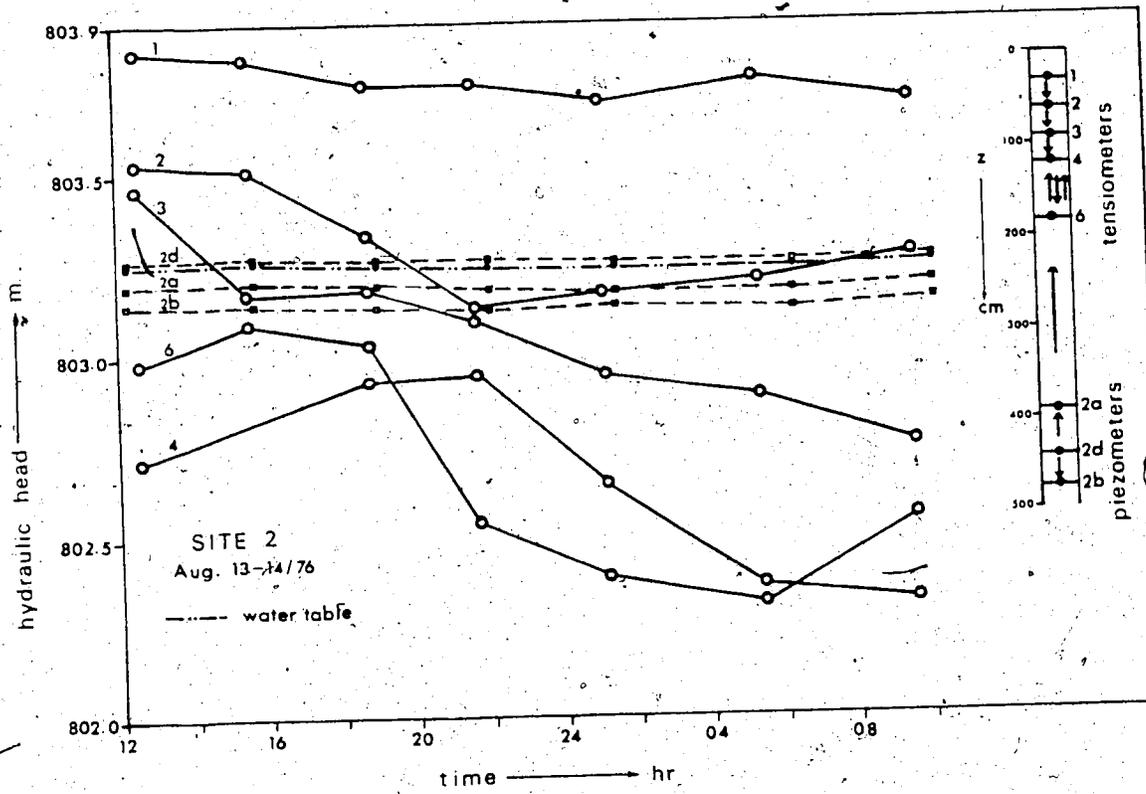


Figure 3-15 Time distribution of hydraulic head at Site 2

not satisfactory. Normally, soil psychrometers are most useful for dry soils with tensions above one atmosphere because of the higher resolution of the psychrometer output. However, after installation, an extended wet period followed with soil water tensions usually in the tensiometer range. This situation reduced the effectiveness of psychrometric measurements. Although occasional good psychrometer readings were obtained, they were not consistent. In addition, the calibration of the psychrometers left in the field probably changed with time as a result of corrosion of the psychrometer wire (Wiebe et al., 1971). It was considered impractical to remove and recalibrate the psychrometers during the course of the field measurement period. The procedure of encasing thermocouple psychrometers in perforated stainless steel tubes (Moore and Caldwell, 1972) would have facilitated removal, recalibration and reinsertion in the field.

### 3.7.3 Water Contents

A typical distribution of water contents at Site 1 -- obtained by using the neutron probe -- is shown in Fig. 3-16. Due to the very uniform grain size of the sand, the water content distribution indicated in that figure is a smooth curve. In contrast, the distribution of moisture with depth at Site 2 is complicated (Fig. 3-17). The presence of lower hydraulic conductivity layers, such as the silty loam (SiL) or loam (L) layer in between the predominantly sandy

loam (SL) layers, produces the observed moisture "bulges" just above those low conductivity layers. This water content distribution with depth was persistent throughout the 1976 measurement period.

#### 3.7.4 Temperature and Potential Evaporation

The variation of soil temperature with time and depth at Site 2 for a diurnal period is shown in Fig. 3-18 together with the air temperatures at the site. A similar graph for Site 1 is shown in Appendix A. A dissipation of the amplitude of the temperature wave with depth is particularly evident. Assuming nearly harmonic temperature-time distribution, the damping depth  $D$  -- that is the depth at which the amplitude of a fluctuation is diminished by a factor of  $1/e$  or 0.37 times the amplitude of the surface temperature -- is given by the formula (van Wijk and de Vries, 1963)

$$D = (2\lambda/C\omega)^{1/2} \quad (3-22)$$

where  $\omega$  is the radial frequency and equals  $2\pi$  times the frequency of the temperature variation. Thus, for the diurnal variation,  $\omega$  equals  $2\pi/86,400$  or  $7.27 \times 10^{-5} \text{ sec}^{-1}$ . Therefore, considering the near-average values indicated in Table 3-2, which represent the top 60 cm of the subsurface profile for the month of August 1976, the damping depths for the diurnal temperature variation for Sites 1 and 2 are 14.9 and 9.3 cm respectively. Correlated with a smaller damping depth is a more rapid decrease of the temperature amplitude

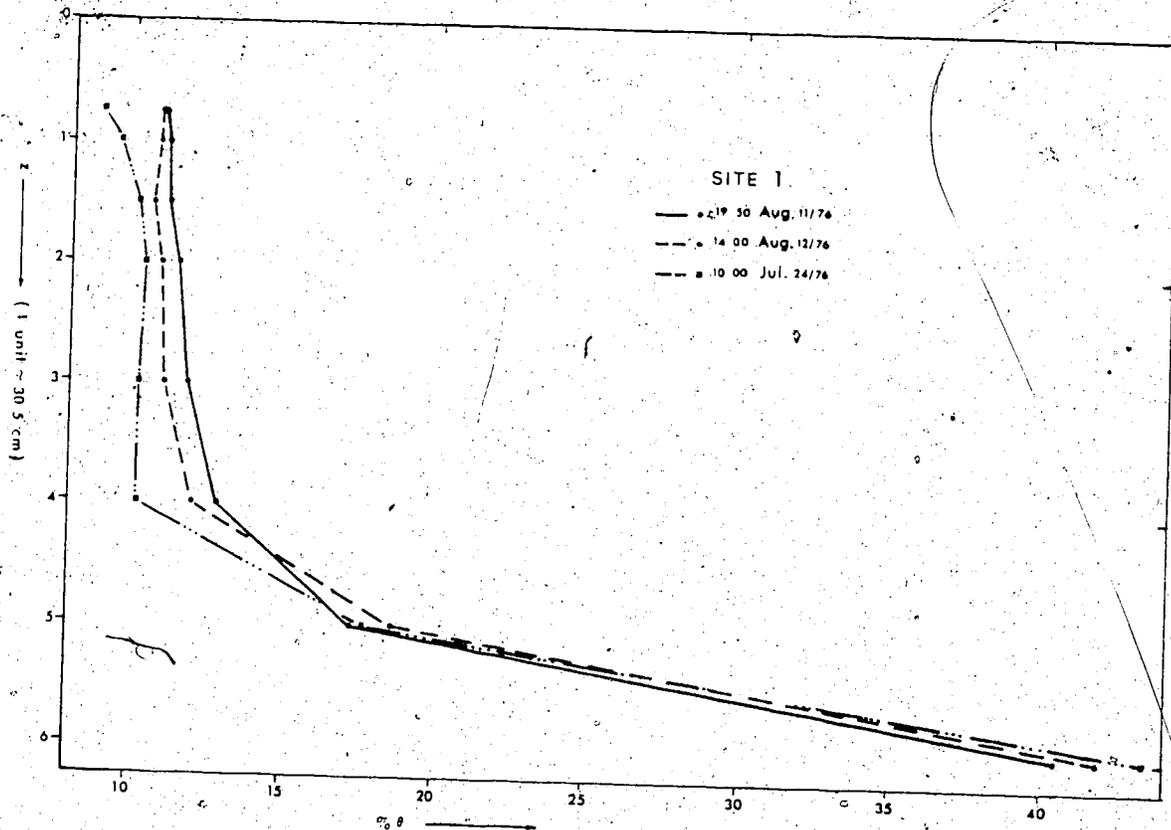


Figure 3-16. Time-depth distribution of water contents at Site 1

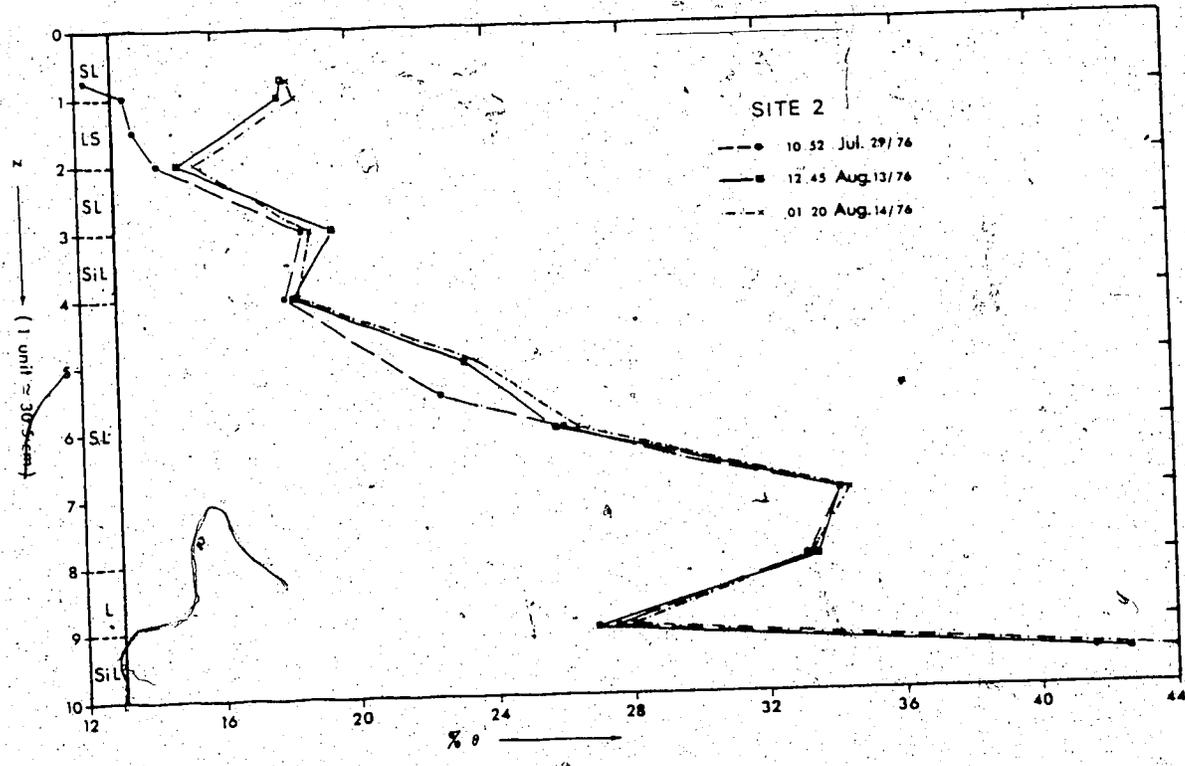


Figure 3-17. Time-depth distribution of water contents at Site 2

(Figs. 3-18 and A-1) as shown by van Wijk and de Vries (1963).

The cumulative potential evaporation as indicated by the Gen atmometer at the Taber sites during two diurnal periods in August 1976 are shown in Figs. A-2 and A-3 of Appendix A. The air temperatures and wind speeds -- as indicated by a portable anemometer -- are also shown on those figures. A correlation between air temperature and wind speed on the one hand and potential evaporation on the other are apparent from those figures.

### 3.7.5 Characteristic Curves

The water characteristic curve obtained from field measurements during the 1976 measurement period for Site 1 is shown in Fig. 3-19 together with laboratory-determined values. Despite the appreciable scatter of data, a satisfactory agreement between field and laboratory data is observed.

The field water characteristic relationship for Site 2 obtained during the same period indicated two distinct characteristic curves, one for the uppermost 45 cm and another for the 45 to 180 cm depth interval (Figs. 3-20 and 3-21). All field tensiometer data were carefully scrutinized to reject the data from tensiometers which had air-bubbles in the manometer tube, too much air in the tensiometer air trap, or had been serviced a short time before the

TABLE 3-2

Typical values of parameters required for the estimation of damping depths for the diurnal temperature variation at the sites

Site	$\theta$	$\% \sigma$	$x$ mm	C (CGS units)	$\lambda$
1	.16	.37	.601	.389	$3.155 \times 10^{-3}$
2	.11	.86	.604	.443	$1.385 \times 10^{-3}$

95

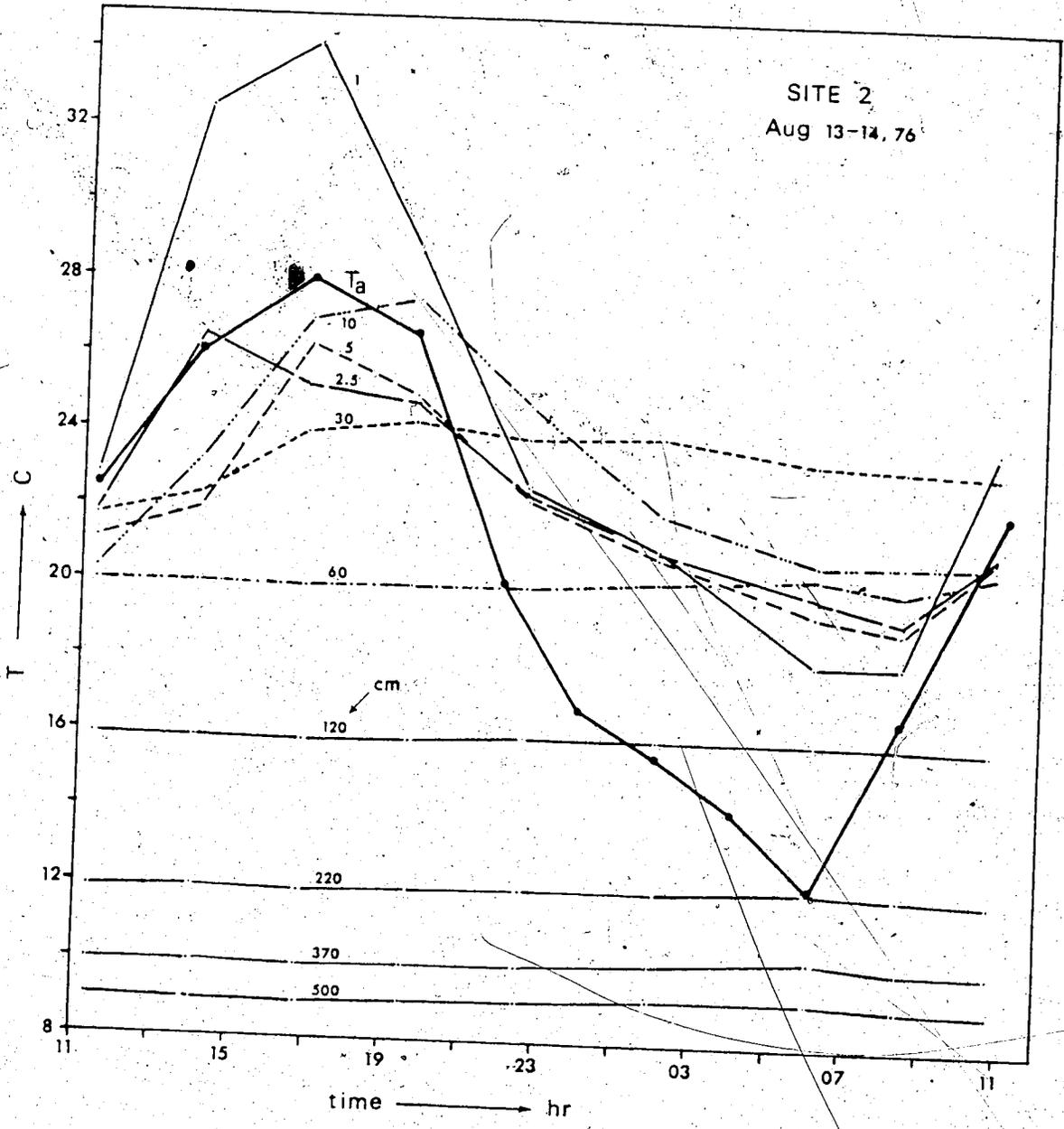


Figure 3-18. Time-depth distribution of temperature at Site 2

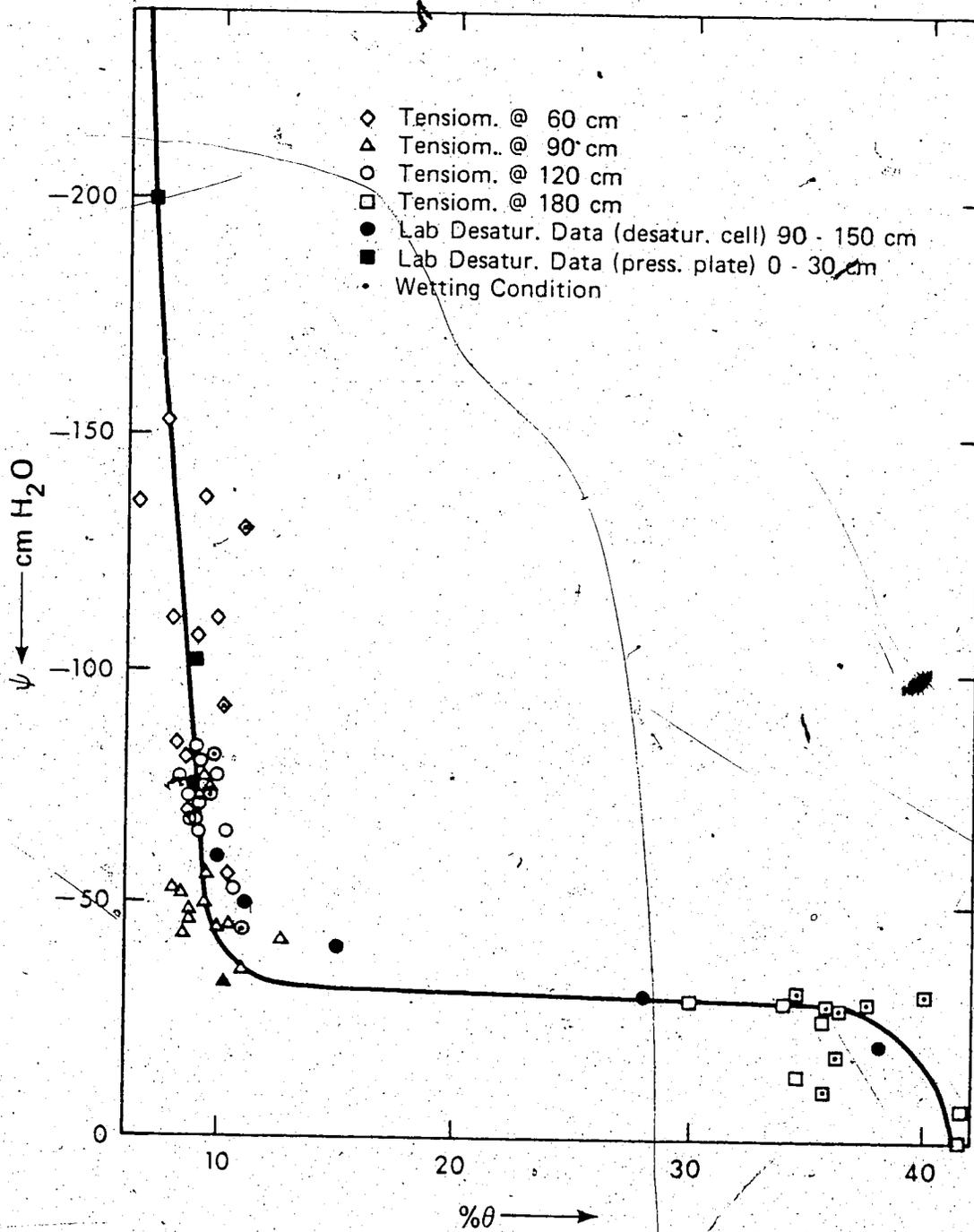


Figure 3-19. Water characteristic curve for Site 1

measurement. The data were classified in Figs. 3-20 and 3-21 according to whether the soil was wetting or drying during the period of measurement. The data scatter around the mean characteristic curve (Fig. 3-21) is approximately  $\pm 1.5\%$  volumetric moisture. This indicates that field hysteresis was probably not important. The overall composite characteristic curve for Site 2 obtained from vapor equilibration techniques, pressure membrane and pressure plate apparatuses, and desaturation cells is shown in Fig. 3-22 together with field-measured data. The reader should refer to Appendix B for further laboratory data and their comparison with field-observed water characteristic values.

The relation between pressure head and water content in unsaturated soils is not generally a unique and single-valued one. Here, a laboratory experiment was used to assess the major wetting and drying curves of the uppermost 20 cm of the soil at Site 2. The results of this experiment are shown in Fig. 3-23. A significant degree of hysteresis, approximately twice that inferred for the top 180 cm of Site 2 (Fig. 3-21), was observed for that soil.

#### 3.7.6 Hydraulic Conductivity

The saturated hydraulic conductivity  $K_{sat}$  of soils below the water table was calculated in the field using the Hvorslev (1951) method. Table 3-3 shows the results of these analyses which represent averages of approximately three

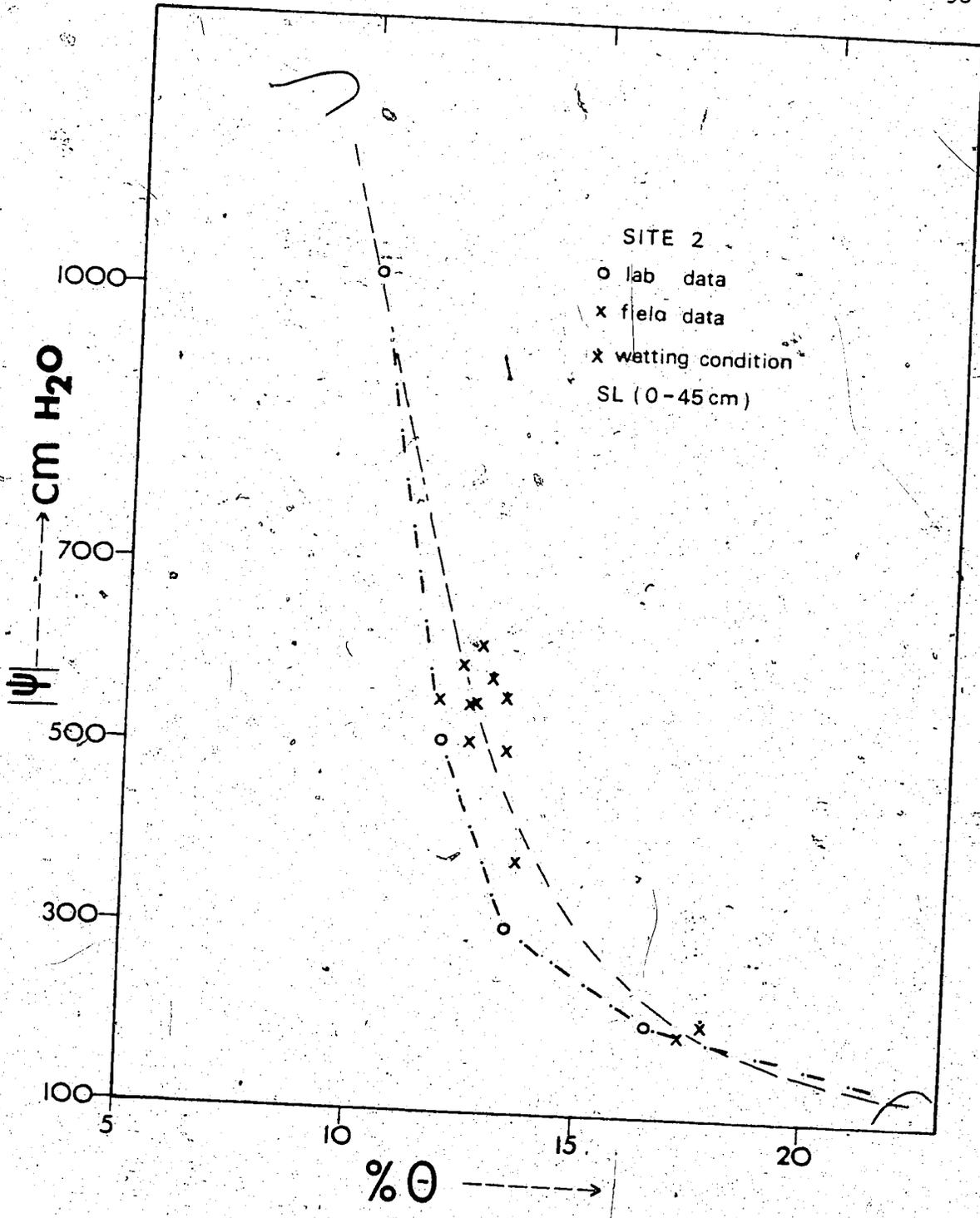


Figure 3-20. Water characteristic curve for Site 2 (0-45 cm)

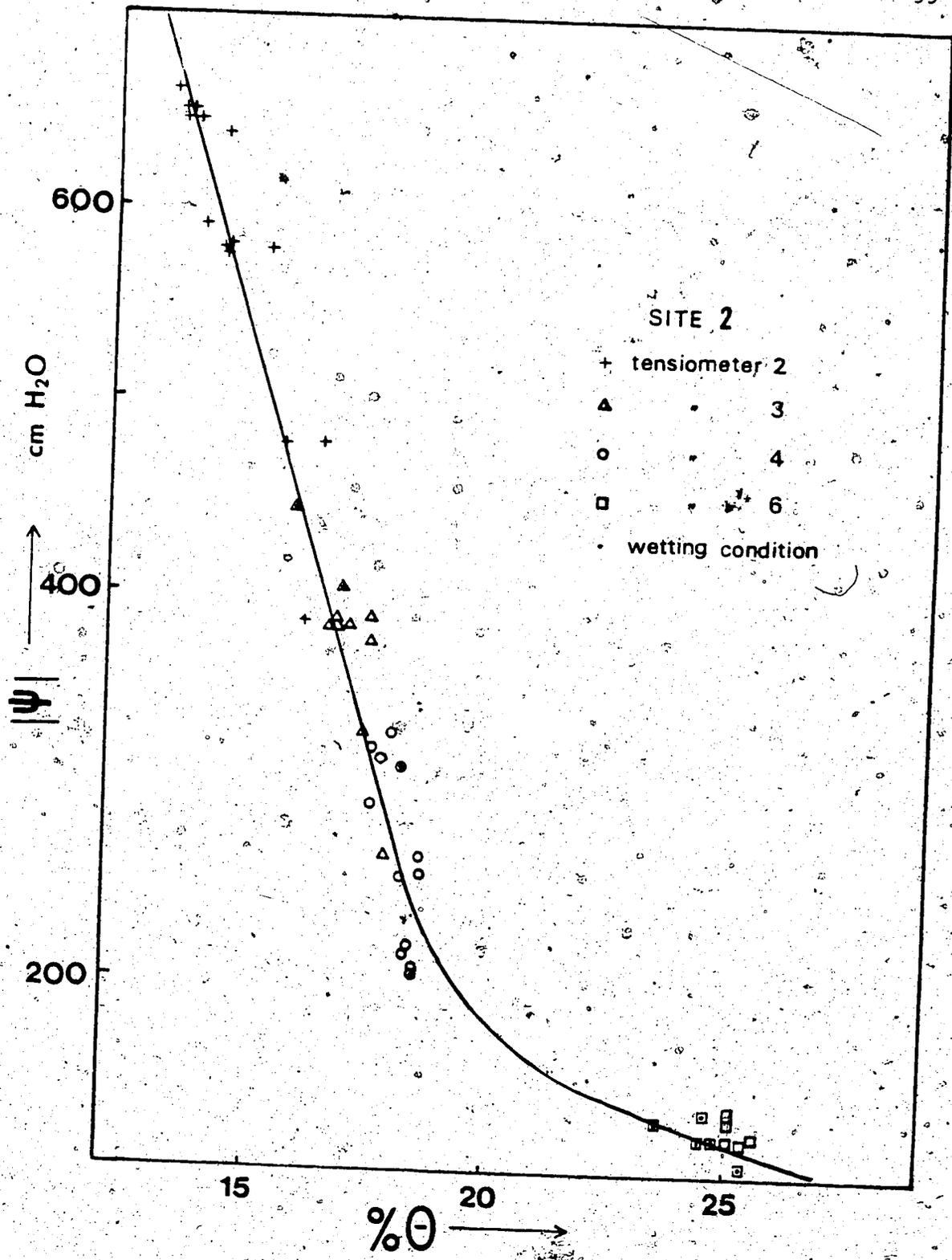


Figure 3-21. Field water characteristic curve for Site 2 (45-180 cm)

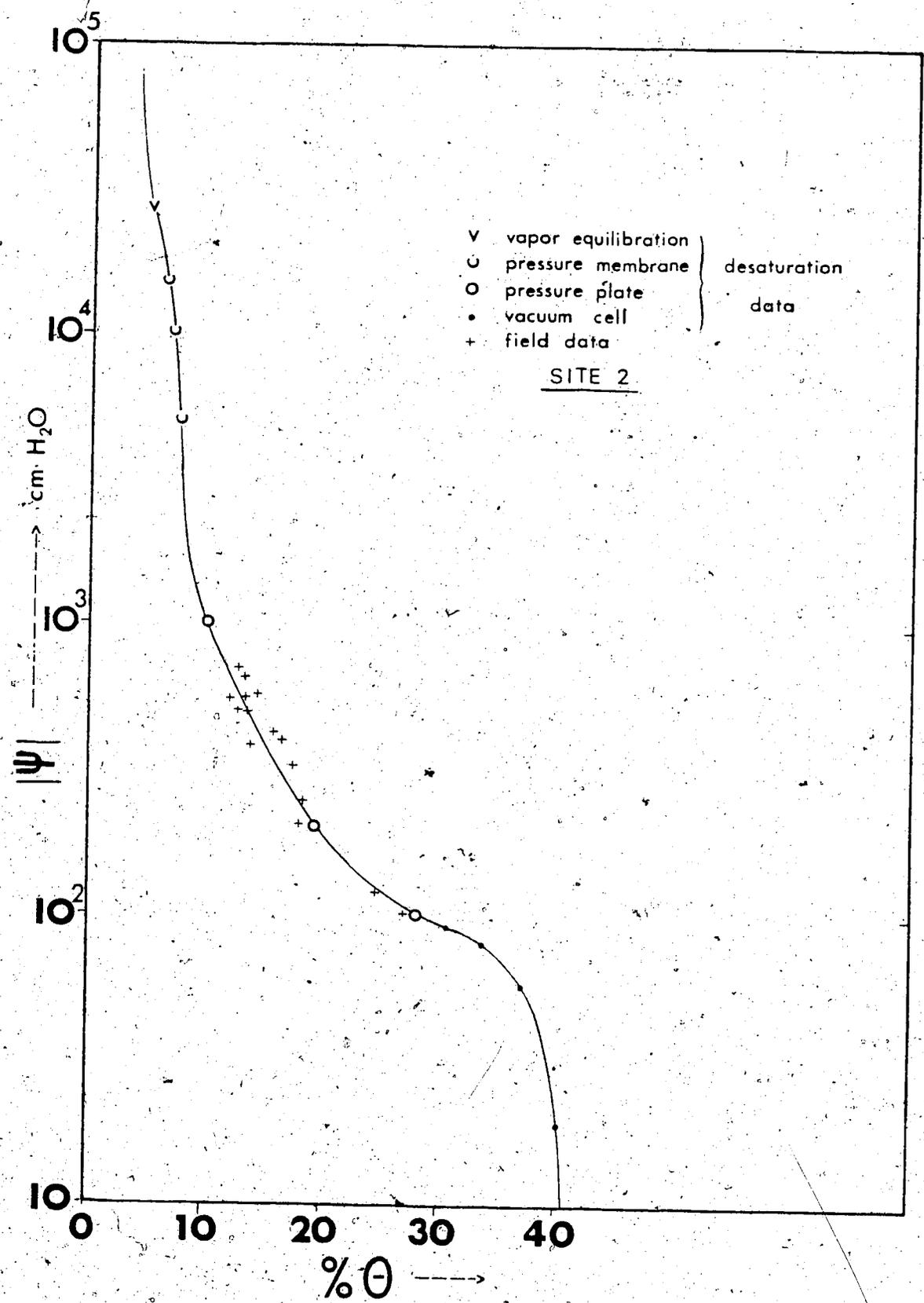


Figure 3-22. Overall characteristic curve for Site 2

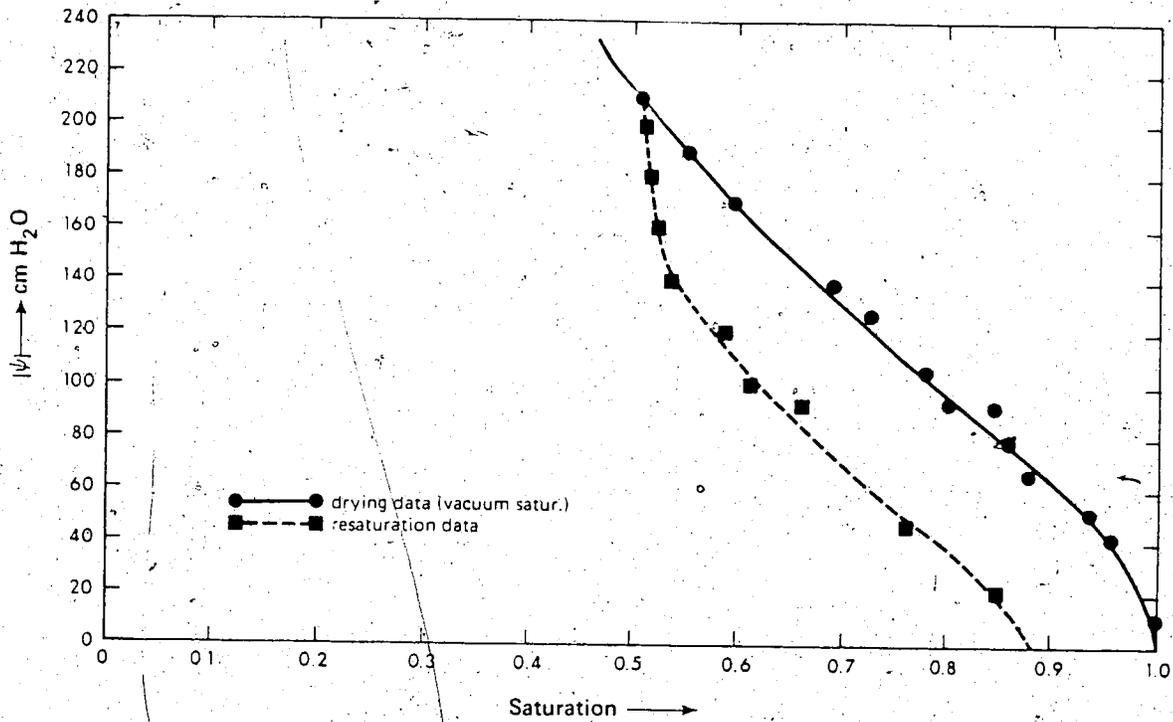


Figure 3-23. Hysteresis loop

tests together with  $K_{sat}$  values determined in the laboratory using the constant head method. In general, the agreement between field and laboratory values of hydraulic conductivity and their correlation with soil texture falls within the expected range of reliability for such measurements.

The results of the laboratory hydraulic conductivity measurements are presented in two sets of curves for each site. Each set consists of the following four relationships: ( $\psi$  vs  $S_w$  or  $\theta$ ), ( $S_e$  vs  $\psi$ ), ( $K_r$  vs  $\psi$ ) and ( $K$  vs  $\theta$ ). Only the  $K_r(\psi)$  and  $K(\theta)$  relationships for the top 20 cm of Site 2 are shown here (Figs. 3-24 and 3-25) as the latter is used as an input relationship in the simulation study to be presented in Chapter 4. (The rest of these relationships are shown in Appendix C). The laboratory hydraulic conductivity measurements are characterized by their limited range of water content or pressure head values over which the hydraulic conductivity can be determined. The extension of measured hydraulic conductivity values to lower water contents or higher absolute values of pressure head is of dubious validity, especially when the extrapolation is well beyond the measured data. Although the above mentioned method of hydraulic conductivity measurement provides a satisfactory tool for extending the hydraulic conductivity values through the linear portion of the  $K_r(\psi)$  relationship, caution should always be exercised in interpreting and quantifying such extrapolated results.

TABLE 3-3

Saturated hydraulic conductivity analyses

Site and Piezometer Depth (cm)	Apparent K, cm/sec		Lab K (cm/sec) <sub>sat</sub>	Soil Texture
	Horizontal	Vertical		
1a	350	1.1x10 <sup>-4</sup>	1.2x10 <sup>-3</sup>	S
1c	400	6.0x10 <sup>-4</sup>		L-CL
1d	430		9.7x10 <sup>-4</sup>	S
1b	565	1.4x10 <sup>-6</sup>		CL*
2a	390	3.5x10 <sup>-4</sup>	4.7x10 <sup>-4</sup>	LS
2d	440		2.4x10 <sup>-4</sup>	SL
2b	475	2.9x10 <sup>-5</sup>	5.4x10 <sup>-4</sup>	SL-L

\*Till

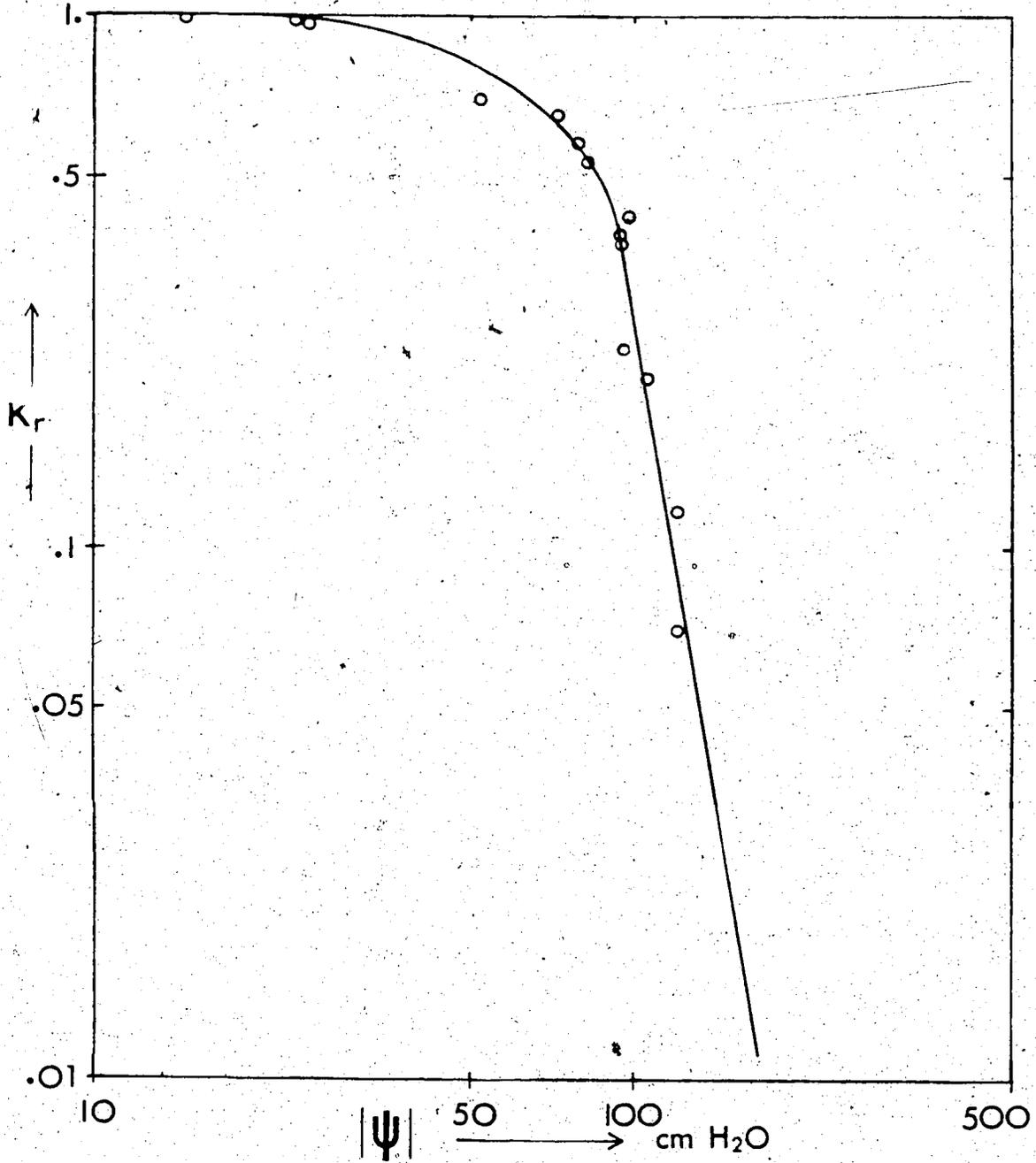


Figure 3-24.  $K_r$  ( $\psi$ ) relationship for Site 2 (0-20 cm)

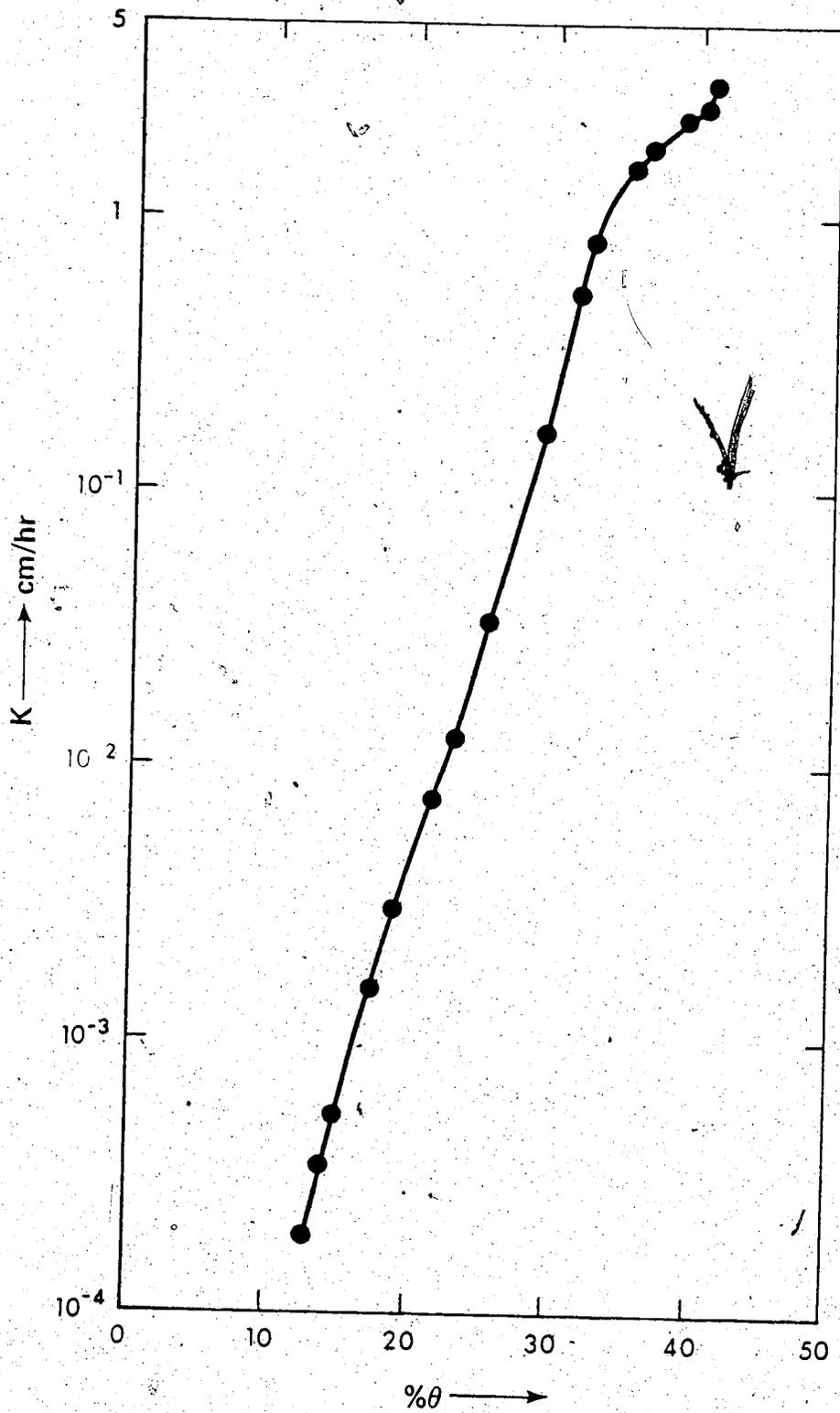


Figure 3-25.  $K(\theta)$  relationship for Site 2 (0-20 cm)

The porosity value used in the hydraulic conductivity experiments was calculated from (3-12) using field- and laboratory-measured values of bulk and particle density of the upper soil layers of the sites. It was assumed that the calculated value of 41% porosity was representative of the field condition and was constant. Measurements of water contents at saturation near the water table using the neutron probe confirmed the representativeness of such a porosity value. This assumption with regard to the porosity distribution -- although used extensively in subsurface water modeling studies -- is probably an oversimplification. However, a lack of field data prevented the more detailed description of porosity variation.

An attempt to calculate the unsaturated hydraulic conductivity by field methods was made using graphically smoothed data from Site 2. Because of the relatively high water contents (15 to 25% by volume) at Site 2 below a depth of a few centimeters, and because measurement errors would probably be reduced, the isothermal field method based on (3-11) was utilized with the reference flux calculated as described in Section 3.6.10.2. The agreement between field measured and laboratory determined hydraulic conductivity values was found to be satisfactory (Fig. 3-26).

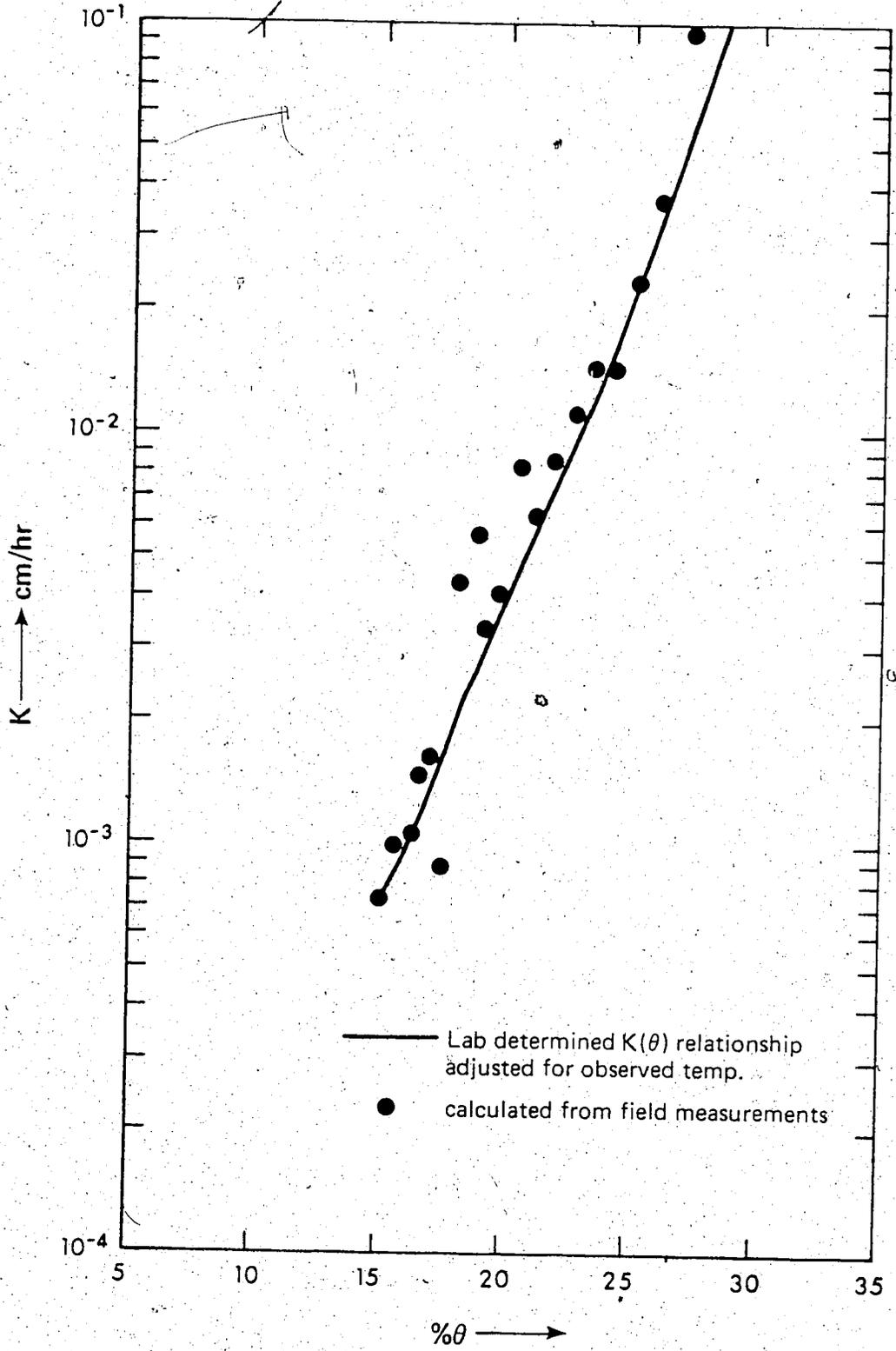


Figure 3-26. Field-determined  $K(\theta)$  curve for Site 2

### 3.7.7 Thermal Conductivity and Heat Capacity

Figure (3-27) shows a typical field curve obtained during the month of July 1976 from Site 1 using the thermal conductivity probe. The value of thermal conductivity calculated from these data is also indicated. The points on such graphs asymptotically approach a straight line somewhere between 100 and 200 seconds after the start of the test. The early time deviation is due to initial lag effects (Wechsler, 1966) mainly attributable to the effects of probe diameter and conductivity, and contact resistance between the test medium and the probe.

Assuming that the entire subsurface profile is homogeneous with respect to thermal conductivity, a relationship between thermal conductivity and water content  $\lambda(\theta)$  is represented in Fig. 3-28 by a hand-drawn line passing through the points. The limited range of water contents over which the thermal conductivities were determined in the field, as well as thermal conductivity heterogeneities, prevented a better definition of the  $\lambda(\theta)$  relationship.

The volumetric heat capacity  $C(\theta)$  function, calculated from the procedure outlined in Section 3.6.9, is shown in Fig. 3-29. The deviations from non-linearity observed in that figure are due to the variation in bulk density and organic matter content (Fig. 3-12).

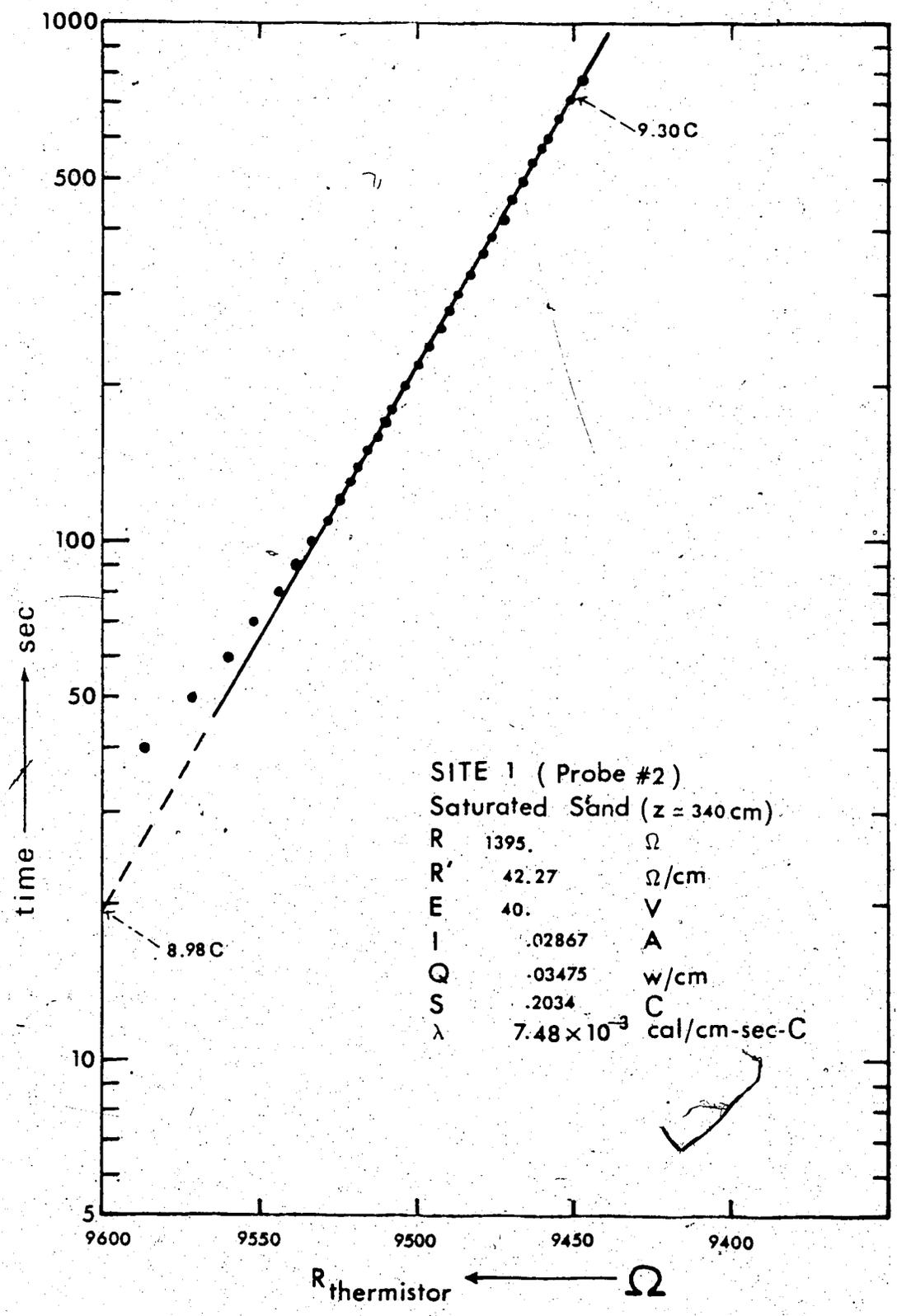


Figure 3-27. Field-determined thermal conductivity

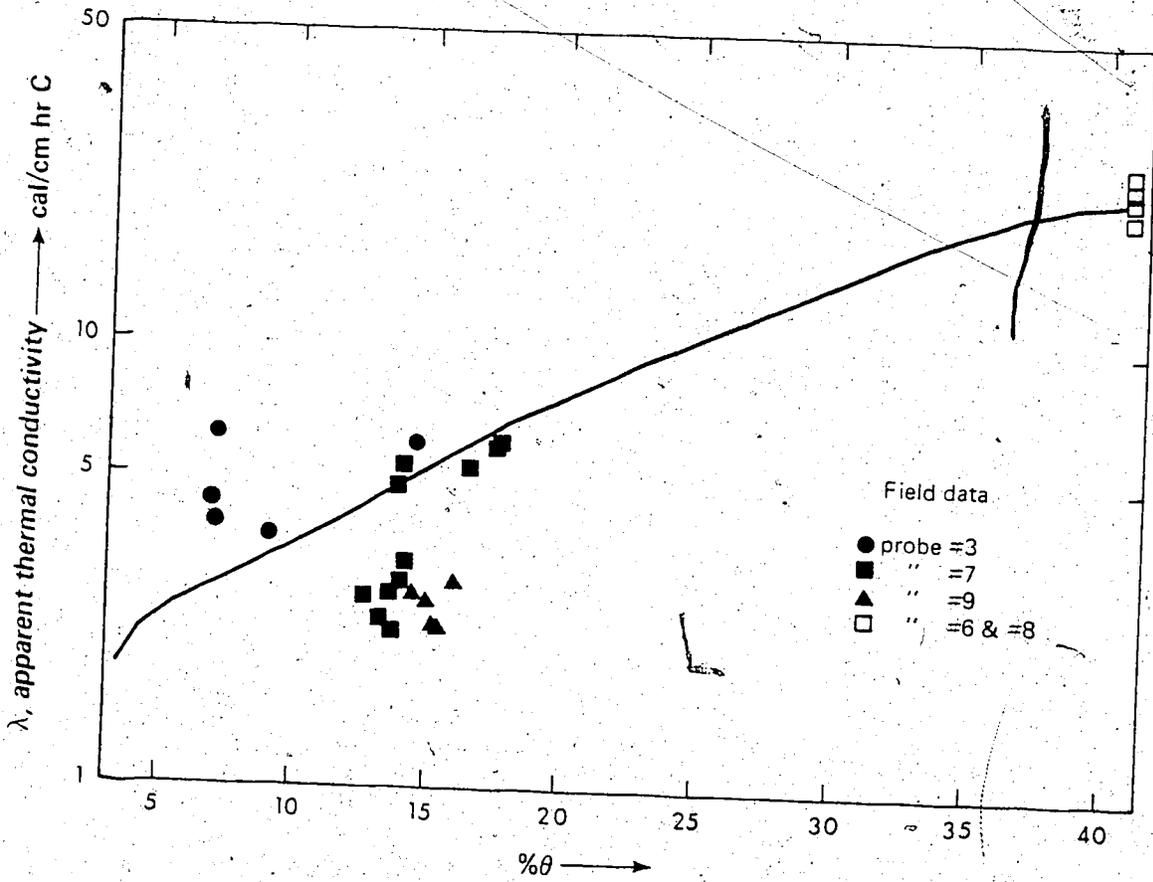


Figure 3-28.  $\lambda$  ( $\theta$ ) relationship for Site 2

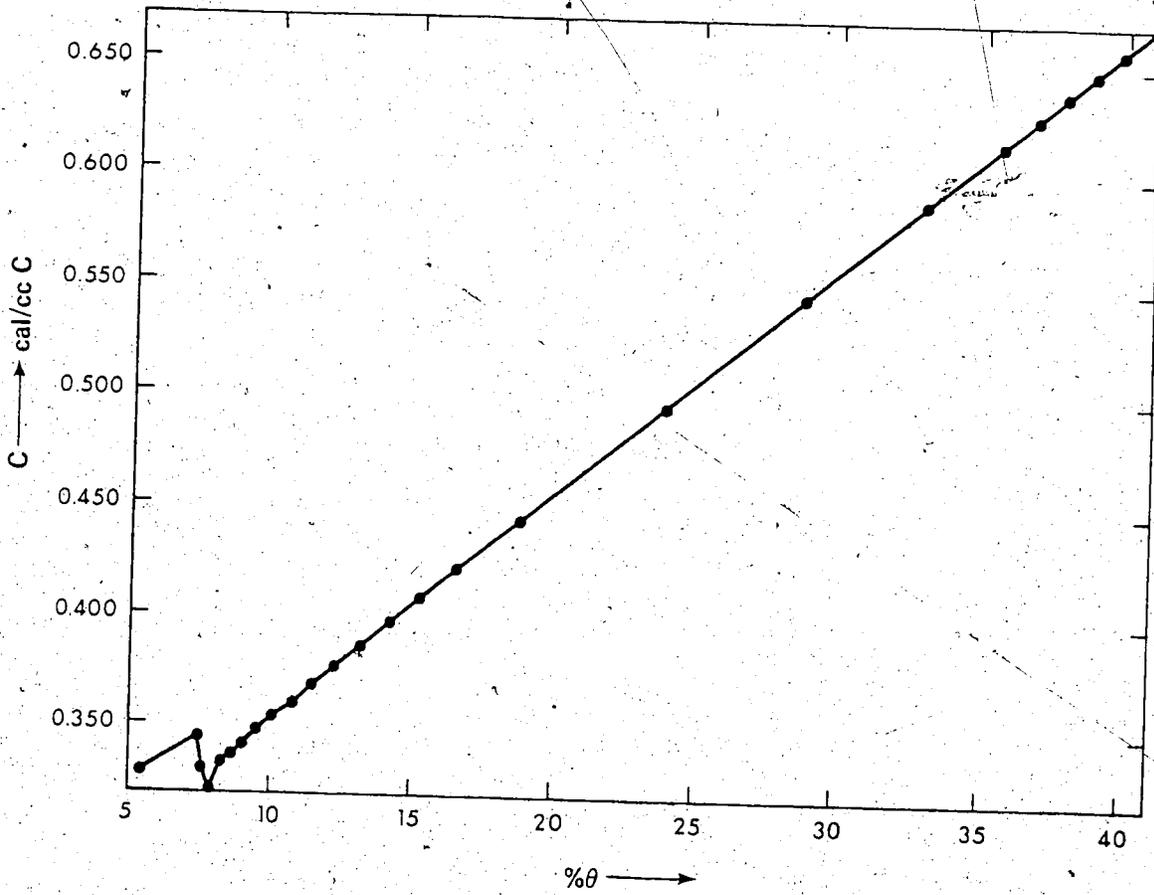


Figure 3-29. C (θ) relationship for Site 2

### 3.8 Evaluation of Field and Laboratory Studies

Reliable field measurements can be achieved by using properly designed and calibrated field instrumentation in combination with careful field installation involving minimum soil disturbance and appropriate spacing. However, even if appropriate precautions are taken, the field researcher is faced with many difficulties in assuring the long-term accuracy of the instrumentation. For example, in the case of the mercury tensiometers, the problems of maintaining the associated manometer completely full of liquid under partial vacuum, time lag and temperature influences on tensiometer performance cause appreciable difficulties in obtaining accurate measurements of matric potentials over a long period of time. Other problems with tensiometers relate to difficulties in maintaining constant physical contact with the soil, especially with windy conditions; disruptions caused by repeated servicing; and plant roots which tend to grow around the base of the tensiometer.

As mentioned earlier, the field use of soil psychrometers was not satisfactory. This result is typical of problems reported by other workers (Maclean, 1974; Mayo, 1976). Thus, few, successful field measurements with soil psychrometers are reported in the literature. (Enfield and Hsieh, 1971; Merrill and Rawlins, 1972; Moore and Caldwell, 1972; Wheeler et al., 1972). The major shortcomings of this

instrumentation are related to the delicacy of the psychrometric measurements themselves and the frequent recalibration of field psychrometers necessary for accurate measurements.

The variation of water content and temperature is usually very small under normal conditions and it is often not possible to measure these changes. Only when the magnitude of the changes are large, such as in the upper soil zone and capillary fringe, can these changes be measured with reasonable accuracy. Difficulties in measuring small temperature and moisture gradients also influence the accuracy of derived data which are functions of these variables. Thus, the possibility of accurately specifying the heat flux and particularly the water flux at some location in the subsurface profile is not great. In addition, the small magnitude of several parameters involved in the calculation of the subsurface flow regime and especially of the thermal diffusion coefficients, coupling coefficients and conductivity coefficients add to the difficulties in applying flow theories.

The methodology proposed in Section 2-8 would appear to make the field endeavor easier. However, the small magnitude of relevant quantities often poses serious error problems. For example, I found that calculating the saturated water flux from the heat flux equation (2-61), as was suggested by Stallman (1963) and Bredhoeft and Papadopoulos (1965), was

not a satisfactory measure of water flux if compared with the value obtained from a Darcy-type expression. This apparent discrepancy is probably due to the very small magnitude of the convective term in (2-61), which, in association with small errors in measurements of the various quantities involved in that equation, makes this procedure questionable for field situations.

The field methodology depends strongly on the accurate determination of water and especially of the heat fluxes in the subsurface profile (Taylor and Cary, 1965). However, relatively small errors in the calculation of heat and water flux propagate and amplify in subsequent transport coefficient calculations. For example, let HF be the ratio of the heat flux calculated using the temperature integral method (Section 3.6.10.1) over the heat flux calculated using (2-58) or (2-60). Also let DC be the ratio of the water vapor diffusion coefficient  $D_{0v}$  -- (2-71) neglecting the convective term -- estimated using the heat flux calculated by the temperature integral method over the diffusion coefficient calculated using the heat flux equation (2-58) or (2-60). I found that for the surface 120 cm of Site 2 soils, a ratio of heat fluxes HF ranging from 1.0 to 1.8 resulted in a ratio of water vapor diffusion coefficients DC ranging from 1 to over 30. This discrepancy is caused in part by error propagation involved in (2-71), which requires that two nearly equal numbers be subtracted (provided the temperature gradient is negative) and the

difference divided by a small number.

Similarly, let WF be the ratio of the water flux obtained by using a water balance equation (Section 3.6.10.2) over the water flux calculated using the non-isothermal water flux equation (2-38). Also, let HC be the ratio of the hydraulic conductivity calculated using the proposed field procedure (Section 3.6.5.2) -- with the water flux calculated from a water balance equation -- over the hydraulic conductivity calculated using the same field procedure but with the water flux calculated by (2-38). I found that for the upper 120 cm of Site 2 soils, a WF ratio ranging from 1 to 10 resulted in an HC ratio ranging from 1.1 to over 17.

Because of the problems originating from measurement errors, field heterogeneities, replacement of some field data by laboratory data and inadequacies in the model expressions of the various transport parameters -- as opposed to actually measured quantities -- the proposed field methodology was not carried any further with the data presented here. Ideally, however, with the availability of better field equipment, better installed and calibrated, this methodology will prove to be of practical significance in environments where temperature gradients are very pronounced.

In order to determine the magnitude of the uncertainty involved in every experimental measurement, an error

analysis similar to the ones performed by Gardner (1965), Hanks and Jacobs (1971), Fritton (1974), Flühler et al. (1976), among others, has been carried out. Let a measured quantity  $F$  be a function of several independent variables  $x_i$  representing measured input data, that is  $F = f(x_1, x_2, \dots, x_n)$  and that these input data are in error by  $\pm\Delta x_1, \pm\Delta x_2, \dots, \pm\Delta x_n$ , respectively. These errors will cause an error  $\Delta F$  in the computed result  $F$ . Expanding the function  $f$  in a Taylor series and neglecting all higher order terms, as the  $\Delta x_i$ 's will all be small quantities, one obtains (Doebelin, 1975)

$$\begin{aligned} f(x_1 \pm \Delta x_1, x_2 \pm \Delta x_2, \dots, x_n \pm \Delta x_n) = \\ f(x_1, x_2, \dots, x_n) + \Delta x_1 \frac{\partial f}{\partial x_1} \\ + \Delta x_2 \frac{\partial f}{\partial x_2} + \dots + \Delta x_n \frac{\partial f}{\partial x_n} \end{aligned} \quad (3-23)$$

The absolute error  $E_a$  is given by

$$E_a = \Delta F = |\Delta x_1 \frac{\partial f}{\partial x_1}| + |\Delta x_2 \frac{\partial f}{\partial x_2}| + \dots + |\Delta x_n \frac{\partial f}{\partial x_n}| \quad (3-24)$$

where the absolute value signs are used to avoid possible reduction of the total error by negative signs of partial derivatives associated with positive  $\Delta x_i$ 's, or vice versa. Thus, the actual error  $\Delta F$  will never exceed  $E_a$  as long as the  $\Delta x_i$ 's do not exceed their estimated values. The form of (3-24) is useful because it indicates which variables ( $x_i$ 's) exert the strongest influence on the accuracy of the overall result. The maximum error approach is different from the standard error approach (Beers, 1957; Lyon, 1970), in which a statistical average of the errors  $\Delta x_i$ 's liable to be present -- usually the root-mean-square errors -- is

estimated.

In order to illustrate the practical usefulness of this technique, approximate measures of the uncertainty in the various parameters involved in calculating the heat flux (3-20) in a general manner, as related to the present field measurements, are obtained using the maximum error approach outlined above. The results of this analysis are detailed in Table 3-4. For error analysis it is necessary to arrive at an estimate of error ( $\Delta x_i$ ) for each of the variables. These error estimates could be standard deviations, 95% confidence intervals, ranges or other measures of error. The maximum absolute error estimates used here (column (4) of Table 3-4) were based on the instrumentation and experiments used for this study. The error estimates of specific heats  $c_s$ ,  $c_o$  and density of organic matter  $\rho_o$  are based on data given by de Vries (1963). The variable  $x_i$  exerting the greatest influence on the accuracy of the overall result is indicated by an arrow in column (6) of the table for each of the four example calculations shown there.

It should be noted that for this analysis no errors were assigned to the problem of measuring true field conditions caused by instrumentation emplacement and the resulting disturbance of the soil, field heterogeneities, annual heat wave influences (Hanks and Tanner, 1972), data smoothing, departure of reality from theory, and possibly other factors. Because the computed errors depend on the

TABLE 3-88  
Maximum error analysis for heat flux parameters at site 2

(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)
Equation & magnitude of P	x <sub>i</sub>	Magnitude of x <sub>i</sub>	Approx. max. abs. error Δx <sub>i</sub>	(∂P/∂x <sub>i</sub> ) Δx <sub>i</sub>	Contrib. to abs. error of term x <sub>i</sub>	Total abs. error	Total relative error (in %)
(eqn. 3-1a)	c <sub>a</sub>	0.86 cal/q/c	0.02	$\left[ \frac{1-x'}{p_s} p_b \right] \Delta c_a$	0.0107		
	c <sub>o</sub>	0.60 cal/q/c	0.02	$\left[ \frac{q'}{p_s} p_b \right] \Delta c_o$	0.00012		
	a'	0.0055	0.0007	$\left[ \frac{c_o p_b}{p_s} - \frac{c_a p_b}{p_s} \right] \Delta a'$	0.00030		
	p <sub>b</sub>	1.42 q/cm <sup>2</sup>	0.1	$\left[ \frac{c_a(1-a')}{p_s} + \frac{c_o a'}{p_s} \right] \Delta p_b$	0.0164	0.038	9.3
	p <sub>s</sub>	2.64 q/cm <sup>2</sup>	0.01	$\left[ -\frac{c_a(1-a')}{p_s^2} \right] \Delta p_s$	0.00061		
	p <sub>o</sub>	1.1 q/cm <sup>2</sup>	0.01	$\left[ -\frac{c_o a'}{p_s^2} \right] \Delta p_o$	0.000019		
C = 0.8103 $\frac{\text{cal}}{\text{cm}^2 \text{C}}$							
(eqn. 3-13)	t	0.0249	sec 0.0005	$\left[ \frac{(.0438) 2R' \log(\tau_2/\tau_1)}{(T_2-T_1)} \right] \Delta t$	0.000068		
	r	49.58	q/cm	$\left[ \frac{(.0438) R' \log(\tau_2/\tau_1)}{(T_2-T_1)} \right] \Delta r$	0.000017		
	T <sub>2</sub>	19.9	C	$\left[ \frac{(.0438) R' \log(\tau_2/\tau_1)}{(T_2-T_1)^2} \right] \Delta T_2$	0.000057	1.99x10 <sup>-6</sup>	11.7
	T <sub>1</sub>	19.0	C	$\left[ \frac{(.0438) R' \log(\tau_2/\tau_1)}{(T_2-T_1)^2} \right] \Delta T_1$	0.000057		
	t	400.0	sec	negligible			
	t	29.0	sec	negligible			
λ = 1.705x10 <sup>-3</sup> cal/cm sec C							
Q = $\frac{\sum_{i=1}^{i+1} C \frac{\Delta T}{\Delta x}}$	C	0.8104 $\frac{\text{cal}}{\text{cm}^2 \text{C}}$	0.038	$\left[ \frac{i+1}{i} C(\Delta T/\Delta x) \right] \Delta C$	0.0118		
	ΔT	0.1	C	$\left[ \frac{i+1}{i} C(\Delta x/\Delta x) \right] \Delta(\Delta T)$	0.0616		
	Δx	12.0	cm	$\left[ \frac{i+1}{i} C(\Delta T/\Delta x) \right] \Delta(\Delta x)$	0.0026	0.0756	61.8
	Δt	8.0	hr	$\left[ \frac{i+1}{i} C(\Delta T/\Delta t^2) \right] \Delta(\Delta t)$	0.00005		
Q = 0.1231 $\frac{\text{cal}}{\text{cm}^2 \text{hr}}$							
q = $\lambda \frac{T_{i+1} - T_i}{\Delta x}$	λ	6.138 $\frac{\text{cal}}{\text{cm hr C}}$	0.716	$\left[ \frac{T_{i+1} - T_i}{\Delta x} \right] \Delta \lambda$	0.0477		
	T <sub>i</sub>	20.0	C	$\left[ \frac{\lambda}{\Delta x} \right] \Delta T_i$	0.0256		
	T <sub>i+1</sub>	19.2	C	$\left[ -\frac{\lambda}{\Delta x} \right] \Delta T_{i+1}$	0.0256	0.107	26.1
	Δx	12.0	cm	$\lambda \left[ \frac{T_{i+1} - T_i}{(\Delta x)^2} \right] \Delta(\Delta x)$	0.0085		
q = 0.4092 $\frac{\text{cal}}{\text{cm}^2 \text{hr}}$							

\*Data from a depth of 60 cm from Site 2 during the August 13-14, 1976 measurement period

magnitude of the variables involved in the error analysis, representative data from some depth (60 cm in the examples shown in Table 3-4), where the time change in various physical properties is not very pronounced, were arbitrarily chosen. The purpose of this exercise is not to present a precise and detailed error analysis but to get a general feeling of the approximate maximum errors involved in this type of field calculation.

One should not be discouraged by the error analysis shown above because any other field method would most likely result in similar, if not greater, uncertainties (Flühler et al., 1976). The maximum error analysis can be used as a criterion for selecting the best field method from others available. Such a selection was done, for example, by Hanks and Jacobs (1971) who showed that the calorimetric (or temperature integral) method for estimating soil heat flux resulted in a smaller relative error than the heat flux meter approach or the combination of heat flux meter and calorimetric method.

## CHAPTER 4

### MODEL STUDIES

#### 4.1 Introduction

The purpose of this chapter is to apply the theoretical and experimental results of the previous chapters to model the simultaneous transport of water and heat in the subsurface. This modeling effort is not simply designed to reproduce flow mechanisms but is an integral part of the study of these mechanisms. It provides the vehicle for better understanding of the flow processes involved; it establishes the framework in which to collect the field data; it is the device to test the adequacy of any existing theories through sensitivity analysis and it provides the means for prediction of non-isothermal flow processes and thus for their control.

#### 4.2. The Mathematical Model

The first step in a quantitative modeling effort of the simultaneous heat and mass transfer in porous media is the development of a mathematical model. Such a model consists of the system of coupled, non-linear, second-order, parabolic partial differential equations developed in

Chapter 2 (2-54 and 2-67) and presented below in one-dimensional form:

$$F \frac{\partial \psi}{\partial t} = \frac{\partial (K_{\psi} \frac{\partial \psi}{\partial z})}{\partial z} + \frac{\partial (D_T \frac{\partial T}{\partial z})}{\partial z} - \frac{\partial K}{\partial z} \quad (4-1a)$$

$$C \frac{\partial T}{\partial t} = \frac{\partial (\lambda \frac{\partial T}{\partial z})}{\partial z} + \frac{\partial (D_L \frac{\partial \psi}{\partial z})}{\partial z} - c_w \frac{\partial T}{\partial z} \quad (4-1b)$$

where,

$$F = \frac{\partial \theta}{\partial \psi} \text{ in the unsaturated zone}$$

$$= S_s \text{ in the saturated zone}$$

$$K_{\psi} = K + K_{\psi v}$$

$$D_T = D_{TL} + D_{Tv}$$

$$C = 0.46x_{mm} + 0.60x_s + \theta$$

$$D_L = L' K_{\psi v} \quad (4-1c)$$

$$q_w/\rho = -K_{\psi} \frac{\partial \psi}{\partial z} - D_T \frac{\partial T}{\partial z} + K_i \quad (4-1d)$$

Because the flow of heat and water is treated as a coupled phenomenon, it is necessary to specify initial and boundary conditions at the same boundaries for both equations (4-1a,b). Therefore, I used the following type of initial and boundary conditions associated with (4-1a,b).

$$\text{Initial Conditions } T(z,t) = T(z) @ t=0, z \in (0,L) \quad (4-2a)$$

$$\psi(z,t) = \psi(z) @ t=0, z \in (0,L) \quad (4-2b)$$

$$\text{Top Boundary Conditions } T(0,t) = T(t) @ t>0, z=0 \quad (4-3a)$$

$$q_w/\rho(0,t) = \pm E(t) \quad (4-3b)$$

specified evaporation or  
infiltration rate

$$\text{Bottom Boundary Conditions } \partial T/\partial z|_{z=L} = 0 \quad (4-3c)$$

$$q_w/\rho(L,t) = \pm w(t) \quad (4-3d)$$

specified water flux entering  
or leaving the system

The solution of (4-1a,b), with the initial and boundary conditions (4-2) and (4-3) respectively, form a mathematical basis for describing the spatial and temporal distribution of temperature and pressure head, as well as all relevant fluxes and transport coefficients in porous media. The form of the present mathematical model is more general than the one used by Philip and de Vries (1957) in that the pressure head is used as the dependent variable instead of the volumetric water content  $\theta$ . Because  $\psi$  is a continuous function of position and time, its values are identical on both sides of an internal boundary separating two different types of porous media, which is not the case with  $\theta$ -values. For this reason, the  $\psi$ -based equations are applicable to layered and heterogeneous porous media, parts of which are completely saturated, while the  $\theta$ -based approach is limited to homogeneous and unsaturated porous media (Corey, 1977). However, one disadvantage of the  $\psi$ -based approach, which is avoided in the  $\theta$ -based formulation, is the strong non-linearity of  $F$  in (4-1a), especially in the vicinity of

very sharp wetting fronts.

#### 4.3 The Numerical Approach

The complexity of the system of coupled non-linear partial differential equations (2-54) and (2-67) suggests that analytical solutions are not possible. Numerical techniques provide the most practical means for obtaining a solution to the (4-1) system of partial differential equations. Because the direction of heat and moisture flow is predominantly unidirectional, I chose to solve the one-dimensional form of the coupled equations. Besides reducing the complications of the modeling effort, the one-dimensional form also reduces the amount of experimental data required and thus the uncertainty associated with their calculation. The latter situation holds especially with regard to determining transport coefficients for non-homogeneous porous media. However, once a one-dimensional solution to the relevant system of partial differential equations is established, the extension to two or three dimensional situations should be feasible.

The system of equations (4-1) may be solved using a variety of numerical methods, the most common of which are the finite-difference (Forsythe and Wasow, 1960; Richtmyer and Morton, 1967; Smith, 1969; Mitchell, 1969; von Rosenberg, 1969; Remson et al., 1971) and finite element methods (Zienkiewicz, 1971; Desai and Abel, 1972; Sagerlind,

1976; Pinder and Gray, 1977). Although the recently popular finite element methods are more advantageous for two- or three-dimensional problems, especially if complex geometries are involved, at present they show little or no advantage over the better known finite difference techniques for non-linear transient one-dimensional problems (Emery and Carson, 1971; Mercer and Faust, 1976).

The finite difference approach was followed here. The derivatives in the coupled equations (4-1) and in the corresponding initial and boundary conditions (4-2) and (4-3) were replaced by finite difference approximations at discrete points of the solution domain. The resulting system of non-linear algebraic equations are solved for  $\psi$  and  $T$ . The water characteristic input function was utilized to obtain the corresponding  $\theta$  values. Figure 4-1 shows a schematic diagram of the one-dimensional model chosen to represent continuous water and heat flow from the ground surface to a point beneath the water table. The subsurface profile is discretized using the equidistant finite difference nodes shown in Fig. 4-1.

#### 4.4 Numerical Solution

Although explicit methods for solving finite difference equations are simple and straightforward, the severe restrictions on mesh size and time increments that are sometimes necessary make this method rather unsuitable for

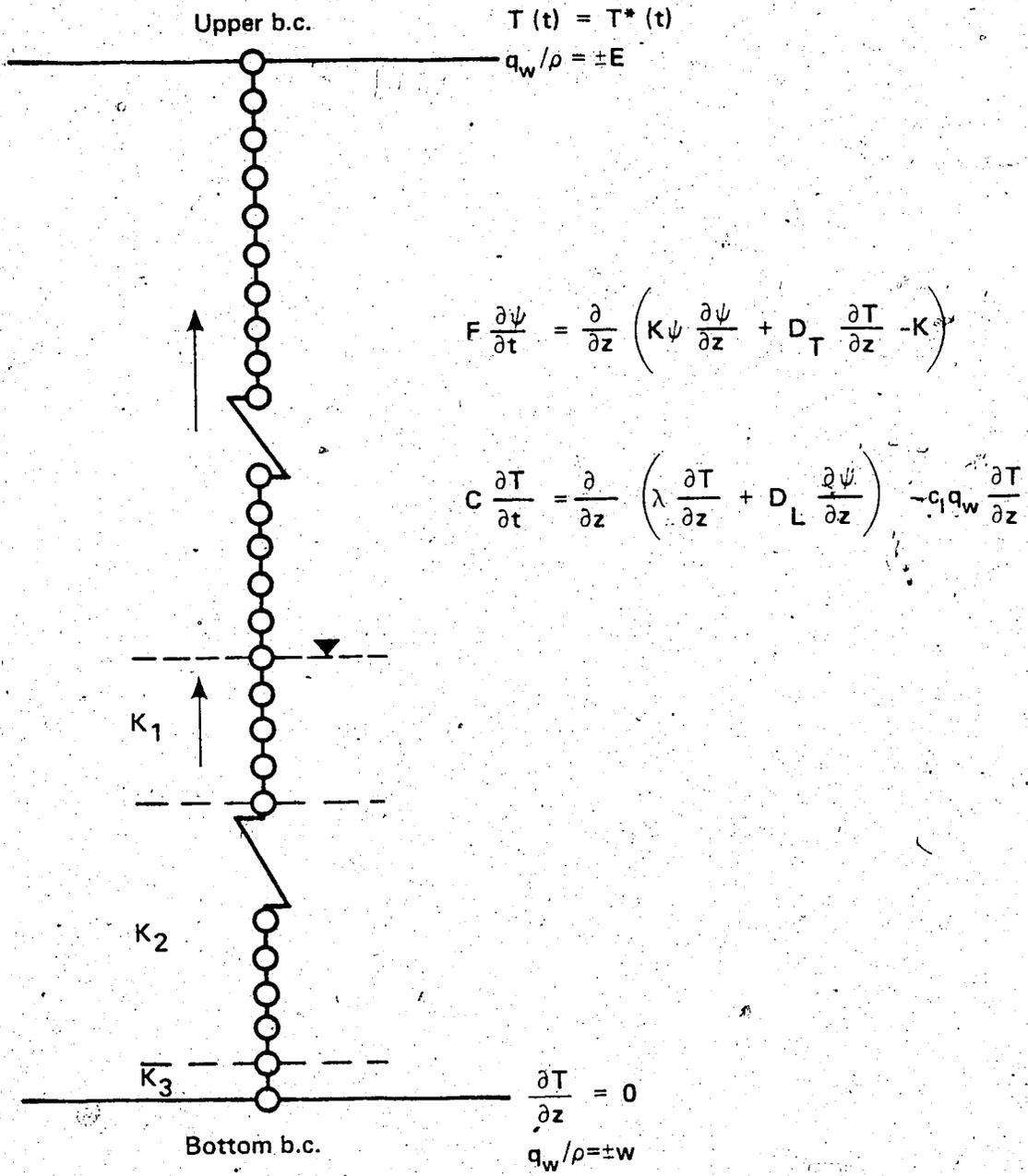


Figure 4-1. One-dimensional coupled transient mathematical model

practical applications. Thus, I have adopted an implicit method which is less restrictive but numerically more complicated because it involves the solution of a system of algebraic equations at each time step. Specifically, a form of the Crank-Nicholson implicit method (Richtmyer and Morton, 1967) was followed (Appendix D). This implicit scheme converges with a smaller discretization error,  $O\{(\Delta t)^2 + (\Delta z)^2\}$ , compared to the error  $O\{(\Delta t) + (\Delta z)^2\}$  of the backward-difference implicit method. The resulting set of simultaneous non-linear algebraic equations using the space-time network of Fig. 4-2 is as follows

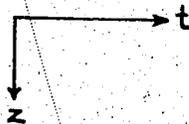
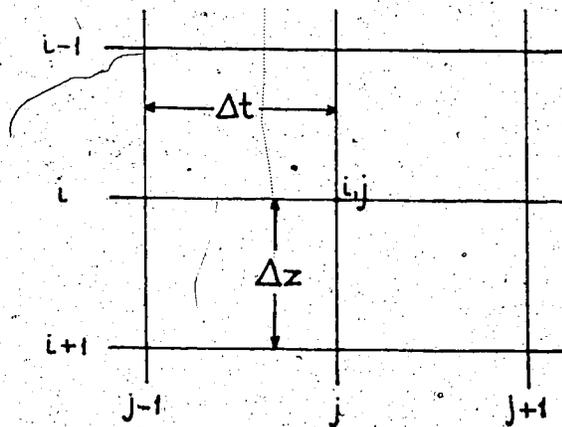


Figure 4-2

$$-A_i^j \psi_{i-1}^j + B_i^j \psi_i^j - C_i^j \psi_{i+1}^j - \bar{A}_i^j T_{i-1}^j + \bar{B}_i^j T_i^j - \bar{C}_i^j T_{i+1}^j = H_i^j \quad (4-4a)$$

$$-A_i^j T_{i-1}^j + B_i^j T_i^j - C_i^j T_{i+1}^j - \bar{A}_i^j \psi_{i-1}^j + \bar{B}_i^j \psi_i^j - \bar{C}_i^j \psi_{i+1}^j = H_i^j \quad (4-4b)$$

where

$$A_i = K \psi_{i-1/2}^{j-1/2} \quad (4-4c)$$

$$B_i = 2F_i^{j-1/2} / r + K \psi_{i+1/2}^{j-1/2} + K \psi_{i-1/2}^{j-1/2} \quad (4-4d)$$

$$C_i = K \psi_{i+1/2}^{j-1/2} \quad (4-4e)$$

$$r = \Delta t / (\Delta z)^2 \quad (4-4f)$$

$$\bar{A}_i = D_{T_{i-1/2}}^{j-1/2} \quad (4-4g)$$

$$\bar{B}_i = D_{T_{i+1/2}}^{j-1/2} + D_{T_{i-1/2}}^{j-1/2} \quad (4-4h)$$

$$\bar{C}_i = D_{T_{i+1/2}}^{j-1/2} \quad (4-4i)$$

$$H_i = K \psi_{i+1/2}^{j-1/2} (\psi_{i+1}^{j-1} - \psi_i^{j-1}) + K \psi_{i-1/2}^{j-1/2} (\psi_{i-1}^{j-1} - \psi_i^{j-1}) + D_{T_{i+1/2}}^{j-1/2} (T_{i+1}^{j-1} - T_i^{j-1}) + D_{T_{i-1/2}}^{j-1/2} (T_{i-1}^{j-1} - T_i^{j-1}) + (K_{i-1/2}^{j-1/2} - K_{i+1/2}^{j-1/2}) 2\Delta z + (2F_i^{j-1/2} / r) \quad (4-4j)$$

$$A_i^j = \lambda_{i-1/2}^{j-1/2} + c_{Li}^{j-1/2} q_{wi}^{j-1/2} \Delta z / 2 \quad (4-4k)$$

$$B_i^j = 2C_i^{j-1/2} / r + \lambda_{i+1/2}^{j-1/2} + \lambda_{i-1/2}^{j-1/2} \quad (4-4l)$$

$$C_i^j = \lambda_{i+1/2}^{j-1/2} - c_{Li}^{j-1/2} q_{wi}^{j-1/2} \Delta z / 2 \quad (4-4m)$$

$$\bar{A}_i^j = D_{L_{i-1/2}}^{j-1/2} \quad (4-4n)$$

$$\bar{B}_i^j = D_{L_{i+1/2}}^{j-1/2} + D_{L_{i-1/2}}^{j-1/2} \quad (4-4o)$$

$$\bar{C}_i^j = D_{L_{i+1/2}}^{j-1/2} \quad (4-4p)$$

$$H^j = \lambda_{i+1/2}^{j-1/2} (T_{i+1}^{j-1} - T_i^{j-1}) + \lambda_{i-1/2}^{j-1/2} (T_{i-1}^{j-1} - T_i^{j-1}) + D_{L_{i+1/2}}^{j-1/2} (\psi_{i+1}^{j-1} - \psi_i^{j-1}) + D_{L_{i-1/2}}^{j-1/2} (\psi_{i-1}^{j-1} - \psi_i^{j-1}) + c_{Li}^{j-1/2} q_{wi}^{j-1/2} \Delta z (T_{i-1}^{j-1} - T_{i+1}^{j-1}) / 2 + (2C_i^{j-1/2} / r) T_i^{j-1} \quad (4-4q)$$

$$X_{i+1/2}^{j-1/2} = (X_i^{j-1} + X_{i+1}^{j-1} + X_{i+1}^j + X_i^j) / 4 \quad (4-4r)$$

$$X_{i-1/2}^{j-1/2} = (X_i^j + X_{i-1}^j + X_{i-1}^{j-1} + X_i^{j-1}) / 4 \quad (4-4s)$$

$$Y_i^{j-1/2} = (Y_i^{j-1} - Y_i^j) / 2 \quad (4-4T)$$

(The reader is referred to Appendix D for the forms that (4-4) takes at the top and bottom boundaries of the solution domain.)

The system of equations (4-4) may be represented in matrix form as follows, where brackets indicate square matrices and braces denote column matrices:

$$\begin{aligned} [G]\{\psi\} + [F]\{T\} &= \{H\} \\ [E]\{\psi\} + [D]\{T\} &= \{H'\} \end{aligned} \quad (4-5a)$$

or

$$\begin{bmatrix} G & F \\ E & D \end{bmatrix} \begin{Bmatrix} \psi \\ T \end{Bmatrix} = \begin{Bmatrix} H \\ H' \end{Bmatrix} \quad (4-5b)$$

Each of the matrices G, F, E, D above represents a tridiagonal, diagonally dominant square matrix. Thus the system (4-5) has the following form

$$\begin{bmatrix} [G] & [F] \\ [E] & [D] \end{bmatrix} \begin{Bmatrix} \psi \\ T \end{Bmatrix} = \begin{Bmatrix} H_i \\ H_i' \end{Bmatrix}$$

(4-5c)

This system of algebraic equations is non-linear because the coefficient matrices  $G$ ,  $F$ ,  $E$ ,  $D$  depend on values of  $\psi_i^j$  and  $T_i^j$ , which are unknown at the time the solution to (4-4) or (4-5) is sought. In order to remove this non-linearity, an iteration process was used in which initial estimates of the  $\psi_i^j$  and  $T_i^j$  values at each point in the solution domain were made and subsequently used to determine those coefficient matrices.

#### 4.5. Solution of Linear Algebraic Systems and Convergence Requirements

At this point let us briefly examine systems of linear algebraic equations of the form

$$[A]\{x\} = \{b\} \quad (4-6)$$

where  $[A]$  is an  $n \times n$  constant matrix;

$\{x\}$  is a column vector of unknown variables; and  
 $\{b\}$  is a constant column vector.

Such a system may be obtained, for example, from linearization of (4-5b) by assuming the coefficient matrices to be constant. Numerical methods for solving linear systems, such as (4-6), may be divided into two types (Forsythe and Moler, 1967; Conte and de Boor, 1972): direct and iterative. The direct methods, exemplified by the Gaussian elimination method, will yield the exact solution for any non-singular system of equations in a finite number of arithmetic operations in the absence of round-off or other computation errors. However, errors arising from round-off, instability and loss of significance may lead to poor or useless results. The iterative methods, on the other hand, start with an initial approximation and may converge to the solution of the system of equations, by applying a suitable algorithm. The iterative methods, although approximate even if the process converges, are marked by their simplicity and relative insensitivity to the growth of round-off errors. Many systems of equations arising in practice result, after discretization, in coefficient matrices that are sparse; that is, they contain a high proportion of zeros. For example, (4-5c) is such a sparse system. Iterative methods, if they work, are ideally suited for the solution of sparse matrices, especially if their order is very large; elimination methods usually produce a triangular system that is no longer sparse (Dorn and

McCracken, 1972).

The matrix, A may be partitioned into three separate matrices:

$$A = L+D+U \quad (4-7)$$

where

L is a strictly lower triangular matrix whose entries are the entries of A below the main diagonal;

D is a diagonal matrix consisting of the diagonal entries of A; and

U is a strictly upper diagonal matrix whose entries are the entries of A above the main diagonal.

(4-6) may now be written as

$$[L+D+U]\{x\} = \{b\} \quad (4-8)$$

which gives rise to the following well-known Jacobi (4-9), Gauss-Seidel (4-10) and successive over-relaxation (4-11) iterative schemes for the solution of systems of linear equations (Varga, 1962)

$$x^{i+1} = D^{-1}[b - (L+U)x^i] \quad (4-9)$$

$$x^{i+1} = (L+D)^{-1}[b - Ux^i] \quad (4-10)$$

$$x^{i+1} = (\omega L+D)^{-1}[\omega b + \{(1-\omega)D - \omega U\}x^i] \quad (4-11)$$

where  $\omega$  is a relaxation factor which lies between 1 and 2, and  $i$  is an iteration index. Note that (4-11) reduces to (4-10) when  $\omega = 1$ . The matrices  $M = -D^{-1}(L+U)$  from (4-9),  $M = -(L+D)^{-1}U$  from (4-10) and  $M = (\omega L+D)^{-1}\{(1-\omega)D - \omega U\}$  from (4-11) are defined as the Jacobi, Gauss-Seidel and successive over-relaxation iteration matrices, respectively. Using the above definitions of the iteration matrices, each

of the previous three iterative methods (4-9 to 4-11) have the general linear form

$$x^{L+1} = Mx^L + b \quad (4-12)$$

A necessary and sufficient condition for convergence of such a linear iterative scheme is that the spectral radius of the iteration matrix  $M$  --  $\rho(M)$  -- that is, the largest eigenvalue in absolute value of the iteration matrix  $M$ , be less than unity (Varga, 1962). By Gerschgorin's theorem (Varga, 1962; Conte and de Boor, 1972), the spectral radius of the iteration matrix  $M$  is less than unity if  $|a_{ii}| > \sum_{j=1, j \neq i}^n |a_{ij}|$  for all  $i = 1, 2, \dots, n$ , where  $a_{ii}$  are the diagonal entries of matrix  $A$ ; that is, if the matrix  $A$  is a diagonally dominant matrix.

#### 4.6 Solution of Non-linear Algebraic Systems

There are no completely general methods for solving arbitrary systems of non-linear equations. Existence and/or uniqueness of such solutions is a largely unanswered question. (Rall, 1973). In addition to the complexity of the programming required, there is no guarantee of convergence of the iterations. However, the fact that a system of partial differential equations may be non-linear does not preclude its solution by one of the basic methods presented above in relation to linear algebraic systems. The aim of any finite difference representation is to approximate the non-linear partial differential equation by an algebraic equation which is linear in its unknowns. Remson et al.

(1971) describe some linearization methods for several non-linear problems in subsurface hydrology. Although predictive-corrective schemes (Douglas and Jones, 1963) or three-level schemes (Lees, 1966; Mitchell, 1969) are effective linearization methods, a Picard-type iteration (Remson et al., 1971; Whisler and Klute, 1965) was used here with the objective of keeping the numerical solution scheme as simple as possible. This simplicity criterion is also the reason for using a uniform grid throughout the studied profile. The linearization scheme used -- together with the main steps of the numerical procedure -- are indicated in the following block diagram (Fig. 4-3).

Attempts to solve the system of equations (4-5) directly using matrix inversion techniques failed because the matrices  $[D - EG^{-1}F]$  or  $[G - FD^{-1}E]$  -- resulting from solving the first or second of the equations (4-5) for  $\psi$  or  $T$  and replacing the result into the second or first equation respectively -- could not be inverted because they were algorithmically singular matrices. Therefore, the following Gauss-Seidel iteration scheme was used to solve the system of equations (4-5):

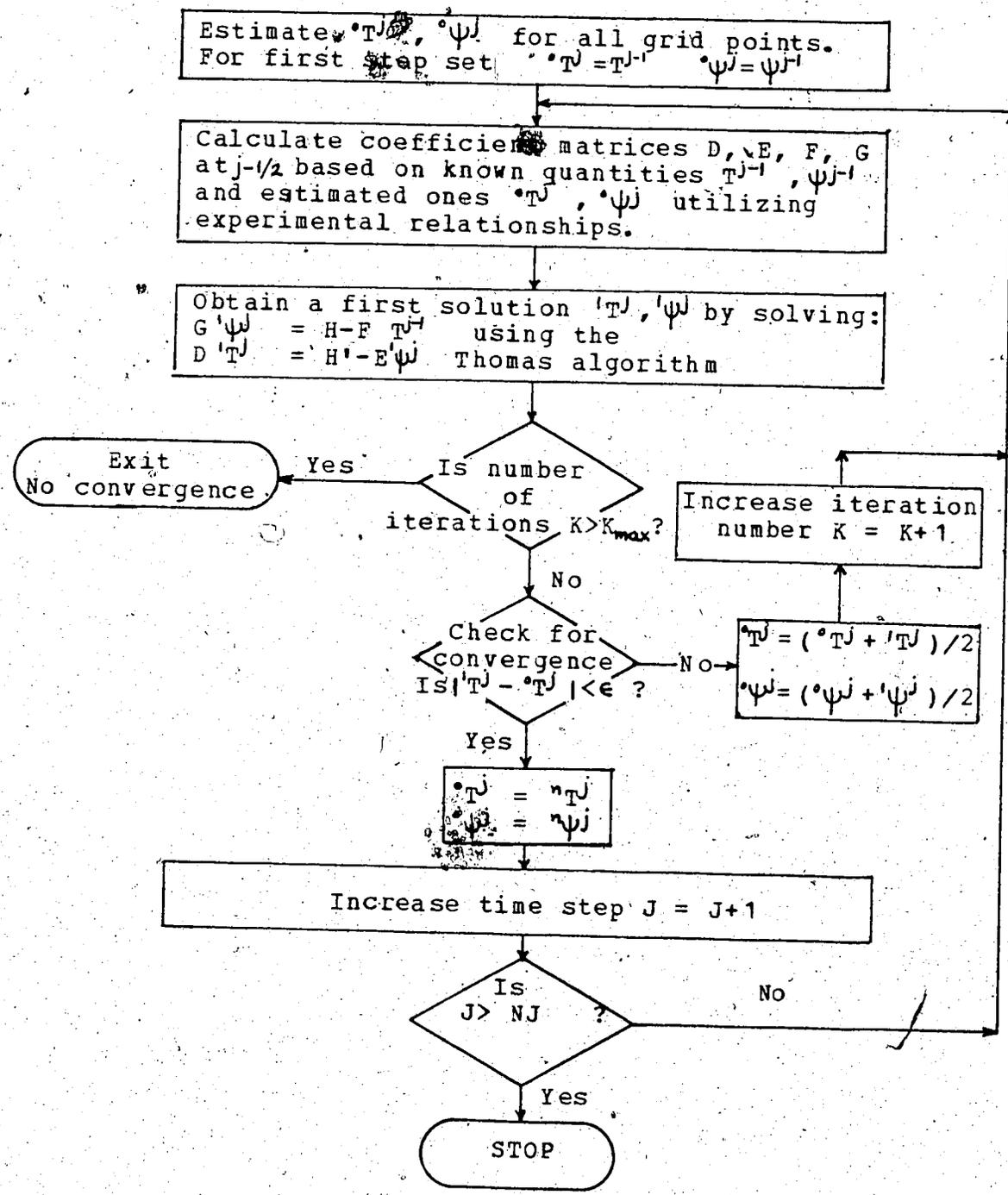


Figure 4-3

$$\begin{bmatrix} G & F \\ E & D \end{bmatrix} \begin{Bmatrix} \psi \\ T \end{Bmatrix} = \begin{Bmatrix} H \\ H' \end{Bmatrix} \xrightarrow[\text{Seidel}]{\text{Gauss}} \quad (4-13a)$$

$$\begin{bmatrix} G & 0 \\ E & D \end{bmatrix} \begin{Bmatrix} \psi^j \\ T \end{Bmatrix} = \begin{Bmatrix} H \\ H' \end{Bmatrix} - \begin{bmatrix} 0 & F \\ 0 & 0 \end{bmatrix} \begin{Bmatrix} \psi \\ T \end{Bmatrix}^{j-1} \longrightarrow \quad (4-13b)$$

$$\begin{array}{l} G \psi^j = H - F T^{j-1} \longrightarrow \psi^j \\ D T^j = H' - E \psi^j \longrightarrow T^j \end{array} \quad \text{Thomas algorithm} \quad (4-13c)$$

As  $G$  and  $D$  are diagonally dominant tridiagonal matrices, the Thomas algorithm (Carnahan et al., 1969; von Rosenberg, 1969) was used to solve the system of equations (4-13b). This scheme proved to be very fast in converging to a solution. Convergence usually took place within one or two iterations. Thus there was no need to use the successive over-relaxation technique.

#### 4.7 Computer Simulation Program

A listing of the FORTRAN IV computer program used to solve the system of equations (4-5) is presented in Appendix E. All calculations were carried out on the AMDAHL 470V/6 computer of the University of Alberta Computing Services. A brief discussion of some of the features of the computer program follows.

The subsurface profile studied (564 cm deep) was uniformly discretized using 48 nodes ( $i = 2, \dots, 49$ ) of

grid size  $\Delta z = 12$  cm. The initial water table position was at 300 cm below the surface node  $i = 2$ . The general direction of flow was upwards. A time step of 0.5 hr was chosen by a limited trial and error procedure. In most of the early runs, a time step of  $\Delta t = 0.2857$  hr was used. The entire subsurface profile was assumed to be homogeneous with respect to the thermal conductivity, which in turn was considered a function of water content only. However, with regard to hydraulic conductivity, the saturated domain of the subsurface profile was treated as a heterogeneous medium while the unsaturated domain was treated as homogeneous. In accordance with saturated porous media flow theory (Scott, 1963), saturated hydraulic conductivity between adjacent layers was taken as the harmonic mean of the hydraulic conductivities of the two layers (Fig. 4-4).

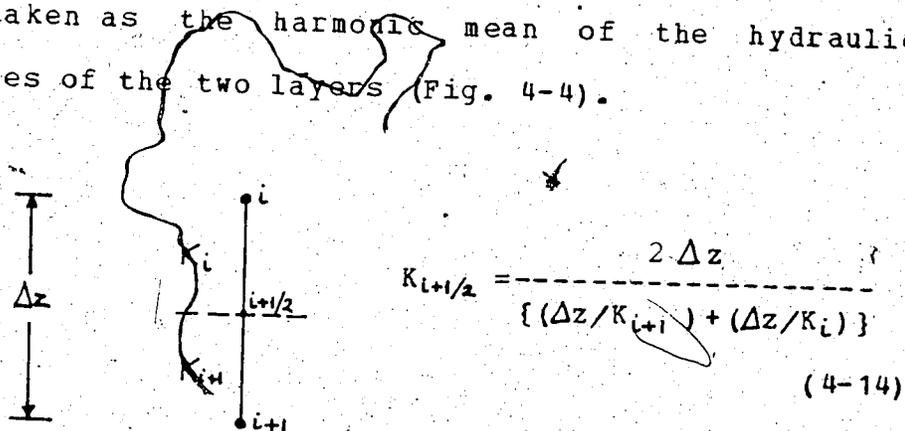


Figure 4-4

The saturated zone was divided into three layers (Fig. 4-1) with field-measured hydraulic conductivities of  $K = 1.256$  cm/hr, for the first layer;  $K = 0.687$  cm/hr for the second, and  $K = 0.054$  cm/hr for the bottom layer, which indicated the

presence of a loamy lens at that position. Hydraulic conductivities were corrected for the effects of temperature on density and viscosity using the following relationship:

$$K(T) = K(T_{ref}) \left( \frac{\mu}{\rho} \right)_{T_{ref}} \left( \frac{\rho}{\mu} \right)_T \quad (4-1)$$

where the reference temperature  $T_{ref}$  was 10C for the saturated zone and  $T_{ref} = 20C$  for the unsaturated zone.

The porous medium was assumed to possess a constant porosity value  $\phi = 0.41$  and elastic storage properties that can be effectively represented by the specific storage  $S_s$ . The specific storage was assigned a constant value ( $S_s = 2 \times 10^{-3} \text{ cm}^{-1}$ ) for the saturated region -- which is an acceptable approximation when the changes in water table elevation occur slowly (McWhorter and Sunada, 1977) -- and zero for the unsaturated zone. In effect, the unsaturated porous medium was assumed to be incompressible.

The top boundary conditions consist of a soil surface temperature specification for the heat flux equation and a prescribed water flux (infiltration or evaporation) for the pressure head equation. The surface temperature may be specified as a sinusoidal wave or as piecewise functions joining measured data. In the case of evaporation condition the user does not have to specify an evaporation flux relation because it is calculated in the program. The evaporation flux is calculated by using the water balance equation (3-21) with the input flux calculated using the non-isothermal flux equation (2-38), and utilizing the water

contents of the current and previous time steps to calculate the time change of moisture content for the top mesh layer.

The bottom boundary water flux was, given a range of expected values based on direct or indirect observations of the hydraulic gradient and conductivity of the bottom material. The value assigned to the bottom boundary flux was  $w = 0.07$  cm/hr downward. The sign convention followed was negative for upward flow and positive for downward flow. The bottom boundary for the heat flux equation was a zero temperature gradient specification. This gradient was approximated by a forward difference scheme, in contrast to the central difference schemes used generally throughout the computer program to approximate spatial derivatives.

As a convergence criterion, a tolerance of  $\epsilon = 0.25$  or  $0.3C$  was used for the computer runs with a  $\Delta t = 0.2857$  hr and  $\epsilon = 0.5C$  for those with a  $\Delta t = 0.5$  hr between temperatures calculated during two successive time steps, excluding the surface temperatures. Therefore, if the condition  $|T_i^j - T_i^{j-1}| \leq \epsilon$  was satisfied, the computed solution was accepted as valid; otherwise, an iteration cycle was activated (Fig. 4-3). A similar convergence criterion could have been established for the  $\psi$ -values. However, judging from the results obtained using only the temperature convergence criterion, such a condition was not considered necessary because the pressure head values may change considerably in a time step, especially during

infiltration into a dry soil. The numerical scheme I used proved to be very fast in converging to the above requirements with only one or two iterations. If the number of iterations exceeded a prescribed number  $K_{max}$  without convergence, the procedure was stopped with appropriate messages printed (Fig. 4-3). The computer simulation was also stopped and a warning message printed if the value of the bottom node became negative.

Because of the banded nature of the square matrices  $D$ ,  $E$ ,  $F$ ,  $G$  (4-5c) with one upper and one lower diagonal, these matrices were stored row-wise (band storage mode) so that the zero elements were compressed out of the matrices. Thus, the above  $n \times n$  matrices were reduced to  $n \times 3$  matrices with the diagonal elements falling into the second column. Equation (4-5) shows an example of the band storage mode used to minimize computer memory requirements.

$  \begin{array}{cccccc}  a_{11} & a_{12} & 0 & 0 & 0 & 0 \\  a_{21} & a_{22} & a_{23} & 0 & 0 & 0 \\  0 & a_{31} & a_{33} & a_{34} & 0 & 0 \\  0 & & a_{43} & a_{44} & a_{45} & 0 \\  0 & & & a_{54} & a_{55} & a_{55} \\  & & 0 & 0 & a_{65} & a_{66}  \end{array}  $	$\xrightarrow{\text{stored as}}$	$  \begin{array}{ccc}  0 & a_{11} & a_{12} \\  a_{21} & a_{22} & a_{23} \\  a_{32} & a_{33} & a_{34} \\  a_{43} & a_{44} & a_{45} \\  a_{54} & a_{55} & a_{56} \\  a_{65} & a_{66} & 0  \end{array}  $
$[n \times n]$		$[n \times 3]$ (4-16)

The simulation program can be controlled by the user in the following ways. By setting the computer input parameter

KODE1 equal to 1 or 0, the bottom boundary condition can be specified as recharge or discharge. By setting KODE5 equal to 0 or 1, the top boundary can be specified as evaporation or infiltration. In a similar way, by putting KODE4 equal to 0 or 1, the user may specify a problem either in an uncoupled (isothermal) or coupled (non-isothermal) transient (unsteady) form. KODE2 =  $i$ , where  $i = 1, 2, \dots, NJ$ . ( $NJ$  = number of time steps) specifies the number of time steps that may be skipped before the result is printed.

At the beginning of the programming effort, balance equations were used to derive the hydraulic conductivity functions. The water flux was calculated from the measured time change of water content and the known water flux at the bottom of the top mesh layer. A similar balance equation was also used to calculate the heat flux from the measured time change of the soil heat content with the bottom heat flux calculated from the thermal conductivity and temperature gradient. However, these schemes, especially the latter one, resulted in numerical oscillations and inaccuracies. Therefore, the field approach proposed in Chapter 2 was not implemented in the present computer program.

As a consequence of the above development, the transport coefficients involved in the system of equations (4-1) were estimated analytically as shown in Chapter 2. In order to increase the accuracy of such calculations, I used double precision arithmetic throughout the program. Because

of uncertainties surrounding the  $D_{Tl}$  coefficient for saturated conditions mentioned in Chapter 2 (p. 29), and in order to simplify the numerical calculations somewhat, the thermal diffusion coefficient  $D_T$  was assumed equal to zero under saturated conditions. This assumption does not seem unreasonable in view of the small temperature gradients observed in the saturated zone under study, and of its small thickness; also the limited number of relevant data in the saturated zone severely limited direct use of the quantity  $\partial\psi/\partial T$  (2-31) by introducing considerable errors.

The ratio  $\zeta$  of the average temperature gradient in air-filled pores to the overall temperature gradient, which appears in the expression of  $D_{Tv}$  coefficient (2-18), has to be specified. The following values were adopted from data provided by Philip and de Vries (1957) and Rose (1968a, b). For  $T \leq 25C$ ,  $\zeta = 1.8$ , and for  $T > 25C$ ,  $\zeta = 1.3$ . It should be noted that a conservative point of view was adopted in choosing the  $\zeta$  values and in incorporating Rose's  $\xi$  coefficient -- the liquid-assisted vapor enhancement factor -- into the pore geometry factor  $f$ . The computer program provides for both  $\psi$ -based and  $\theta$ -based equations discussed in previous chapters.

Experimentally determined input data to the simulation model include:

-- initial distribution of temperature and pressure head with depth (usually supplied as graphically smoothed

- curves);
- time distribution of surface temperatures. (As mentioned in Chapter 3, the measured soil temperatures at a depth of less than 1 cm were taken as surface temperatures);
  - characteristic function(s) --  $\psi$  vs  $\theta$  ;
  - hydraulic conductivity function(s) --  $K$  vs  $\theta$  (this function may be optional because the user may decide to use the water balance equation for calculating  $K$  built into the model);
  - thermal conductivity-water content relationship --  $\lambda$  vs  $\theta$ ;
  - distribution of volumetric percentages of organic matter and mineral matter with depth.

The data from the characteristic and hydraulic conductivity functions, from the thermal conductivity-water content relation, and from a series of table look-up data sets appearing in the program -- such as the relationships  $\mu$  vs  $T$ ,  $\rho$  vs  $T$ ,  $L$  vs  $T$ ,  $p_v^s$  vs  $T$ ,  $c_t$  vs  $T$  and  $D_a$  vs  $T$  -- were calculated using the cubic spline interpolation (Ahlberg et al., 1967; Conte and de Boor, 1972). This interpolation method provided a relatively simple, continuous and smooth curve through all points of interest. Thus, values at some unknown points can be evaluated and many common operations, such as differentiation and integration, can be easily performed.

The output of the program consists of a list of some

physical parameters for the system, such as the section length studied, the gas constant, the specific storage value, and others; numerical information, such as the maximum simulation time, the size and number of time and space increments, the maximum number of allowable iterations, and others; a list of top boundary time-temperature distribution and initial depth distribution of  $\psi$ ,  $\theta$  and  $T$ ; the calculated temperature; pressure head and moisture distribution, as well as all transport coefficients and heat and water fluxes.

As the above discussion may suggest, this simulation model is general and flexible. It can handle any type of boundary conditions, heterogeneities, saturated-unsaturated regions, isothermal and non-isothermal environments, transient and steady-state systems.

#### 4.8 Program Verification

The overall error of a simulation result may be considered as the sum of errors introduced by the numerical finite difference analog and/or errors introduced by possible inadequacies of the theoretical framework in describing the particular phenomena. Although the validity of the uncoupled (isothermal) equations is supported by a considerable body of literature, the correspondence of the coupled non-isothermal equations to the physical processes has not been well established. Such uncertainties are mainly

due to the relative scarcity of studies verifying the validity of the non-isothermal coupled models, especially under field conditions. As I will point out in the final chapter, considerable research is still needed to verify several aspects of such systems. However, this study and others (Rose, 1968a, b, c; Jackson et al., 1974, 1975) support its general validity. Therefore, I will assume that errors in the solution are introduced by the numerical algorithm used in the present study and not by the mathematical model.

Because numerical techniques introduce instabilities, truncation and round-off errors in approximating the solution, it is necessary to check the solution with experimental data and/or a theoretical (analytical) solution. Therefore, the uncoupled equations of heat and water with constant coefficients -- for which analytical solutions are available -- were considered for this purpose in order to give an indirect check on the validity of the coupled equations.

A limited number of analytical solutions are available for the complete heat transport equation. However, no truly analytical solutions for the moisture equation are available (Guymon and Luthin, 1974). Kirkham and Powers (1972) summarize some of Philip's (1969) approximate solution techniques of uncoupled moisture problems. Therefore, in order to check the validity of the numerical method, the

transient uncoupled heat equation with constant coefficients was solved using the same computer model. The results were compared with the analytical solutions described, for example, in Carslaw and Jaeger (1959) or in Ingersoll et al., (1954). Specifically, the following heat conduction problem was considered:

$$C \partial T / \partial t = \partial (\lambda \partial T / \partial z) / \partial z = \lambda (\partial^2 T / \partial z^2) \quad (4-17a)$$

$$\partial T / \partial t = (\lambda / C) \partial^2 T / \partial z^2 = \alpha \partial^2 T / \partial z^2 \quad (4-17b)$$

where  $\alpha$  is the thermal diffusivity ( $\text{cm}^2/\text{hr}$ ) with the following boundary and initial conditions:

$$T = 0\text{C} \text{ @ } z = 0$$

$$T = 0\text{C} \text{ @ } z = L \quad (4-17c)$$

$$T = T_0 = 10\text{C} \text{ @ } t = 0$$

The analytical solution to the above problem is (Carslaw and Jaeger, 1959):

$$T = (4T_0/\pi) \sum_{n=0}^{\infty} \left( \frac{1}{2n+1} \right) e^{-\alpha(2n+1)^2 \pi^2 t / L^2} \sin \frac{(2n+1)\pi z}{L} \quad (4-18a)$$

or

$$T = (4T_0/\pi) \left\{ e^{-\pi^2 \alpha t / L^2} \sin \frac{\pi z}{L} + \frac{1}{3} e^{-9\pi^2 \alpha t / L^2} \sin \frac{3\pi z}{L} + \frac{1}{5} e^{-25\pi^2 \alpha t / L^2} \sin \frac{5\pi z}{L} + \dots \right\} \quad (4-18b)$$

Using the following representative input data,  $\alpha = \lambda / C = 8/0.5 = 16 \text{ cm}^2/\text{hr}$  and  $L = 564 \text{ cm}$ , one finds that for  $t = 24 \text{ hr}$  and  $z = 36 \text{ cm}$ , for example, the analytical solution -- using the terms shown in (4-18b) -- is  $T(z=36, t=24) = 8.07\text{C}$ , while the numerical solution obtained using the present program with a time step  $\Delta t = 0.2857 \text{ hr}$  was  $T(z=36, t=24) = 8.05\text{C}$ . The agreement between the two is, therefore, excellent (relative error  $\approx 0.25\%$ ) suggesting that the uncoupled transport equations are solved correctly. Figure

4-5 shows the initial and simulated, transient temperature-depth distribution for the conduction problem (4-17) considered here.

The simulation results were also compared with observed field data. Figures 4-6 and 4-7 compare field and simulated results. In all those figures the input depth distribution of temperature or moisture in the early afternoon of August 13th, 1976 at Site 2 are shown with the continuous curves. If one keeps in mind that in the field the unsaturated domain included some discontinuous clay loam lenses but that the simulation model assumed a homogeneous unsaturated zone, the simulated results are in satisfactory agreement with the observed data.

The present modeling study does not represent an exhaustive numerical treatment. Because of the inherent complexity of the numerical problem and the amount of storage and computing time required, the number of cases that could be run economically were somewhat limited. The maximum time for any one simulation trial was one week. The difference equations (4-4) become the original differential equations (4-1) as  $\Delta z$  tends to  $dz$  and  $\Delta t$  to  $dt$ . Therefore, the accuracy of the finite difference approximation is a function of the fineness of the time and spatial grids used in the solution, subject to computational limitations, such as truncation and round-off errors. However, in order to use the available computer funds most efficiently, rather coarse

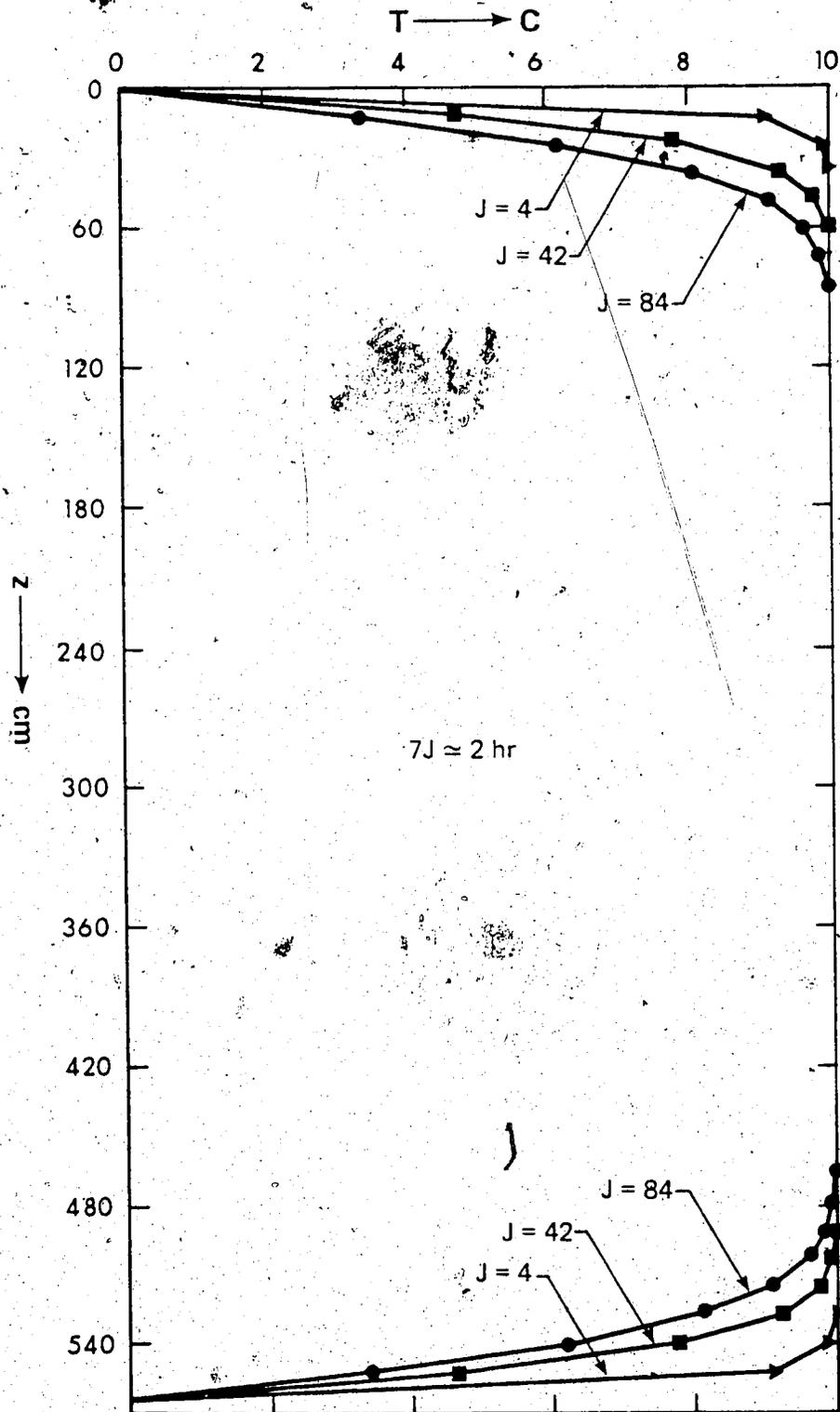


Figure 4-5. Time distribution of temperature for the conduction problem

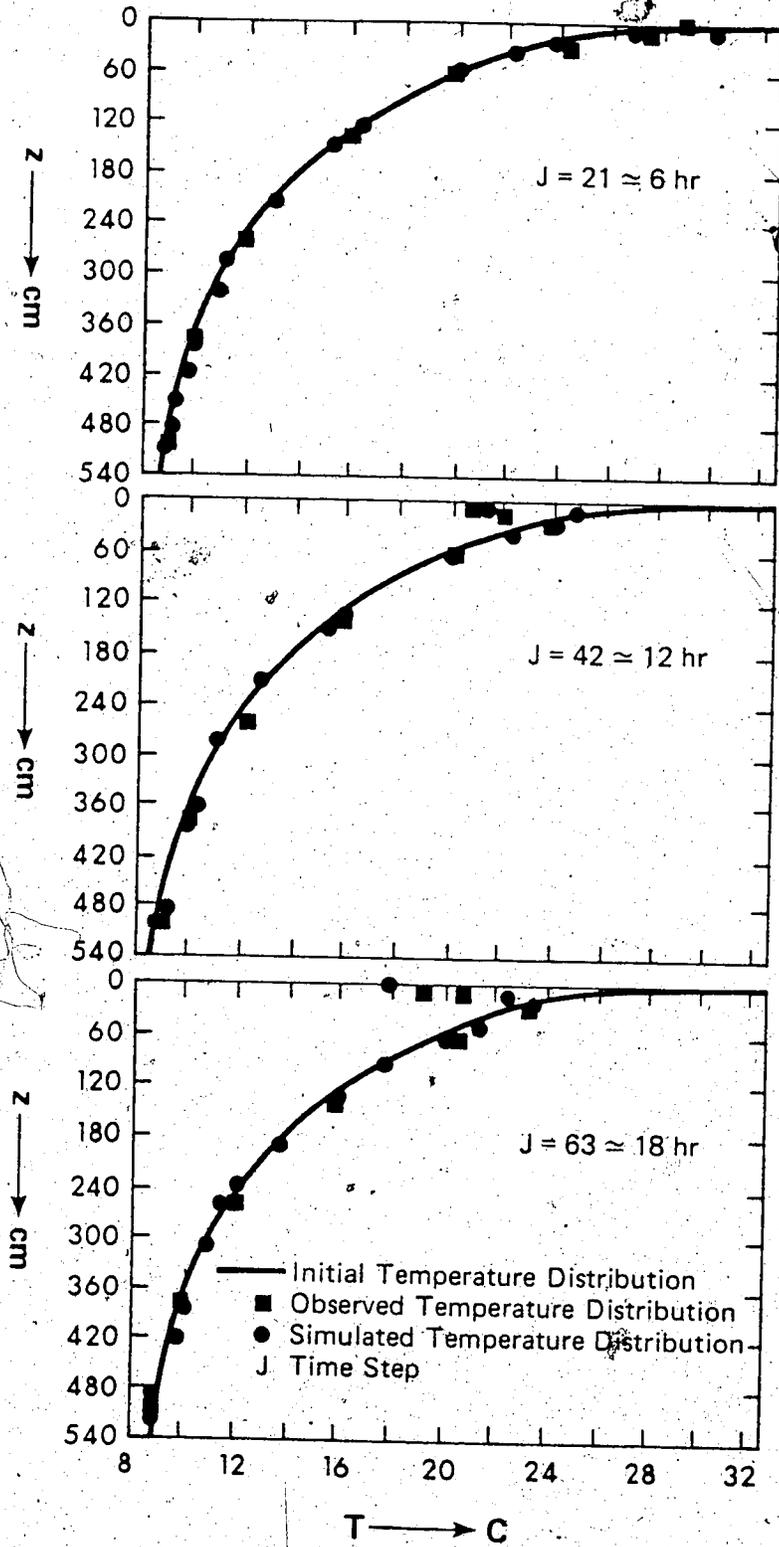


Figure 4-6. Comparison of observed and simulated temperature distributions

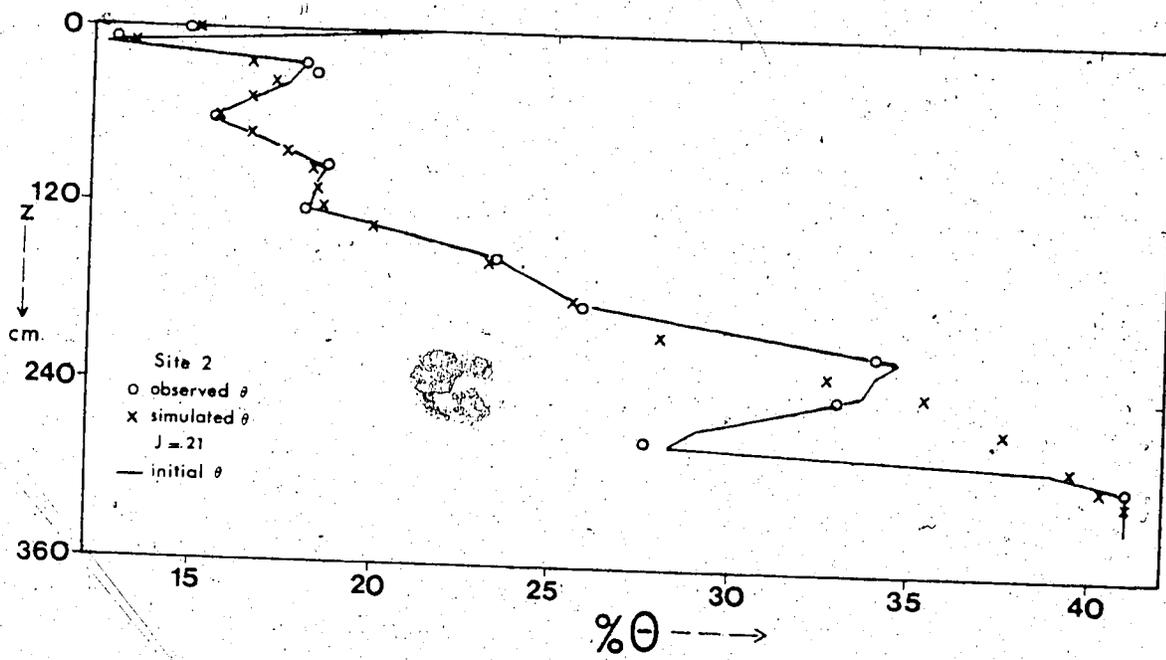


Figure 4-7. Comparison of observed and simulated moisture distributions

grid systems were used to reduce the storage and time requirements. A computer simulation run of 168 hr (one week) with a time step of 0.5 hr used approximately 25 sec of CPU time in the University's fast AMDAHL computer; while, the 24 hr runs with a time step of 0.2875 hr (with some minor later modifications) used approximately 12 to 13 sec.

Owing to the non-linear nature of the present coupled problem, caution should be exercised in using abrupt imposed boundary changes. It may only be possible to handle these by significant reductions in the time step. However, abrupt change may lead to more serious problems such as the divergence of the solution. For better and faster results, the input data sets should be representative, continuously varying and smoothed.

#### 4.9 Results and Discussion

A limited number of simulation problems were solved using the computer simulation program described above. In every case, both the isothermal (uncoupled) and non-isothermal (coupled) models were used in order to evaluate possible coupling effects. Three different initial conditions were used in studying the drying or evaporation problem. These initial conditions are shown in Fig. 4-8; the corresponding computer runs are referred to as Run 1, Run 2 and Run 3. The upper boundary temperature-time distributions used for these simulations are shown in Fig. 4-9. Table 4-1

summarizes the conditions for each run. A list of some physical parameters and numerical information for these simulation runs are shown in Table 4-2.

Using the initial conditions for Run 1 (wet condition with field observed but smoothed data) and for Run 2 (dry condition) indicated above, no appreciable changes in the temperature field occurred by coupling or uncoupling the system of equations (4-1) for short time simulations. However, significant differences were observed in the evaporation and moisture fluxes as indicated in Tables 4-3 and 4-4.

It should be noted in those tables that the evaporation and moisture fluxes computed from the uncoupled equations are higher than the ones computed from the coupled equations, and that the difference is greater when the water contents are at intermediate levels (Run 1). This situation holds true as long as the normal temperature gradients prevail in the soil; that is, when the higher temperatures are at the top and decrease with depth, in opposition to the potential gradients observed at the field sites. Thus, a small flow is set up opposite the potential gradient to slow the drying rate. However, during the diurnal cycle, when temperature gradients are reversed, the opposite holds true, as shown in Tables 4-5 and 4-6.

Figures 4-10 and 4-11 indicate a much faster decrease of  $K_{\psi}$  with decreasing water content than the one of  $D_T$

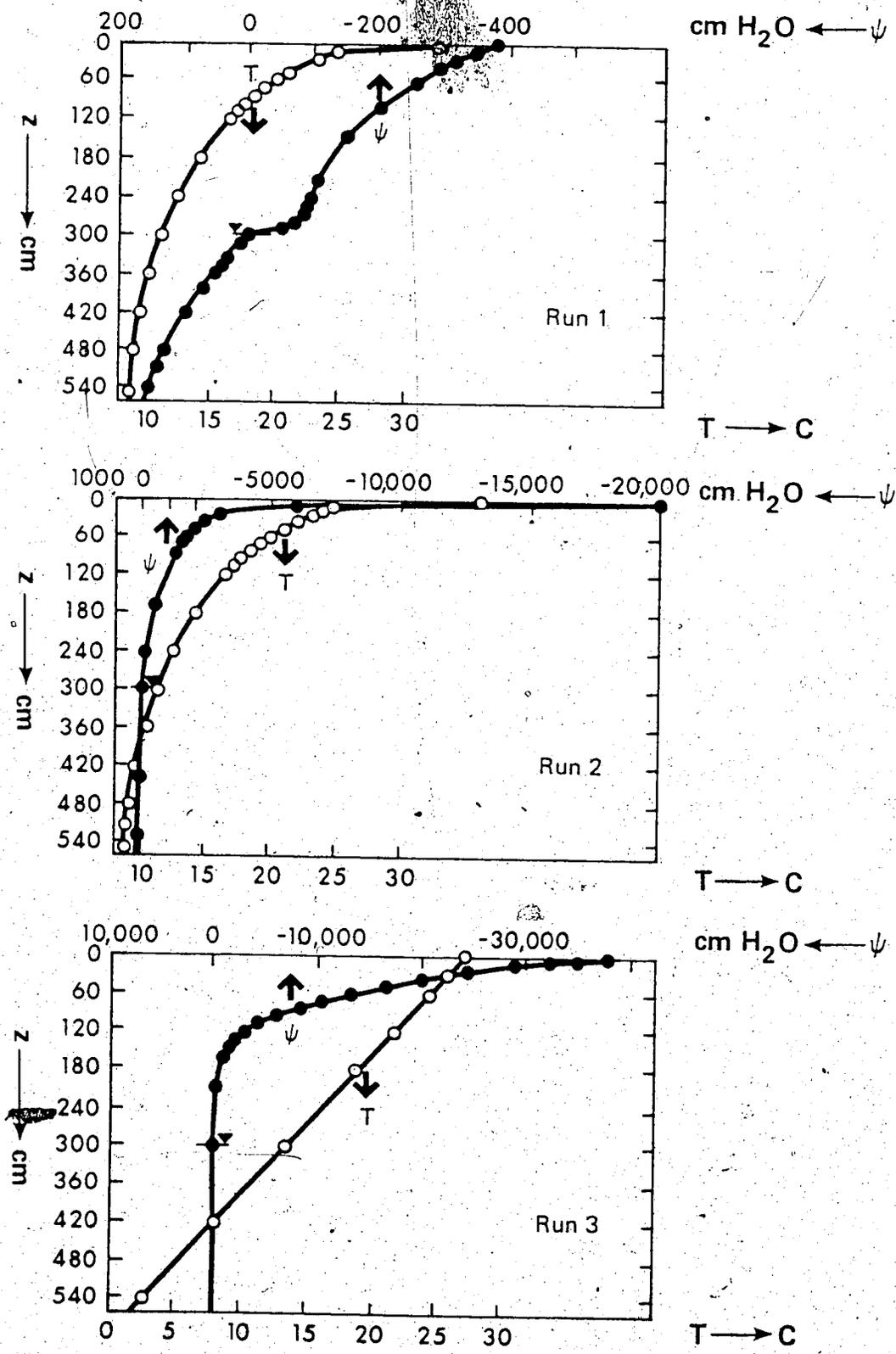


Figure 4-8. Initial conditions for case simulation runs

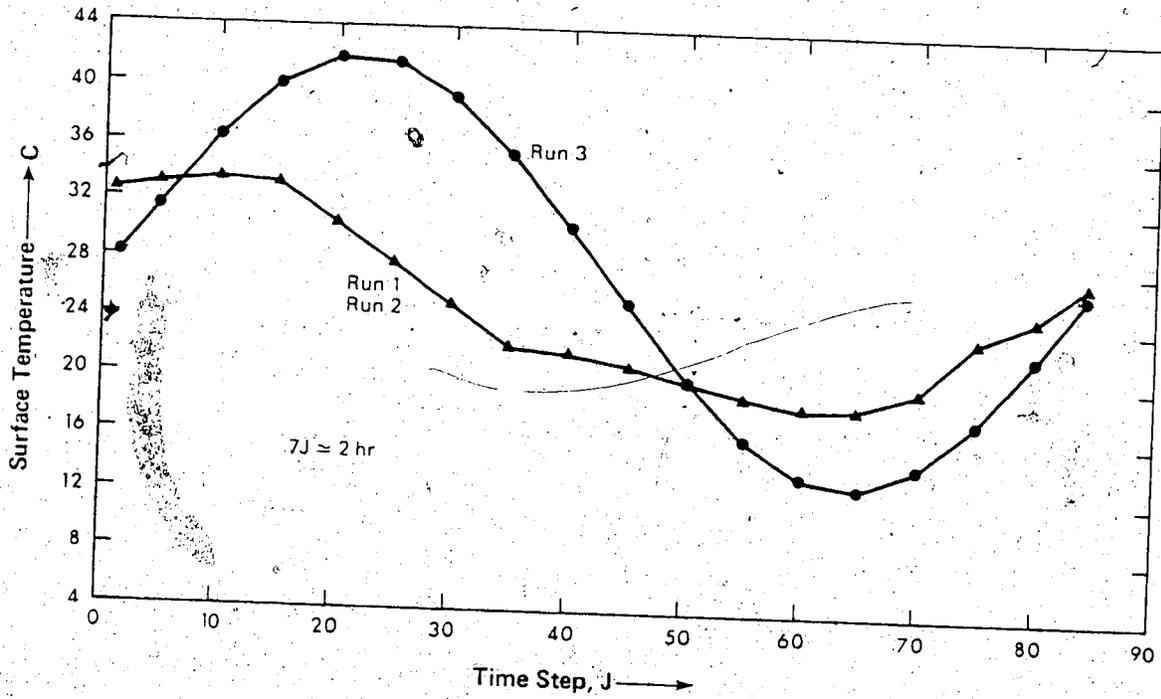


Figure 4-9. Upper boundary time distribution of temperature for case simulation runs.

TABLE 4-1

Conditions for case simulation runs

Run	Moisture conditions	$\psi(z)$ data	T(z) data	T(t) data
1	wet	observed-smoothed	observed-smoothed	observed
2	dry	simulated	observed-smoothed	observed
3	very dry	simulated	simulated	simulated

TABLE 4-2

Sample output information from simulation runs

-----  
 LIST OF PHYSICAL PARAMETERS FOR THE SYSTEM

GAS CONSTANT (ERG/DEG.C-MOL) 83143200.0  
 MOLECULAR WT. OF WATER ( GM/MOL ) 18.0  
 SPECIFIC STORAGE(CM\*\*2) 0.2000000D-02  
 SECTION LENGTH ( CM ) 564.0  
 ACCELERATION OF GRAVITY (CM/SEC\*\*2) 980.665  
 REFERENCE TEMP. (DEG.C) 10.000  
 WATER DENSITY AT REF.TEMP. (GM/CC) 0.99973  
 WATER VISCOSITY AT REF.TEMP. (GM/CM-HR) 47.052

NUMERICAL INFORMATION

MAXIMUM SIMULATION TIME (HR) 24.00000  
 SIZE OF TIME INCREMENT (HR) 0.2857143  
 NUMBER OF TIME INCREMENTS 84  
 NUMBER OF SPACE NODES 49  
 SIZE OF SPACE INCREMENTS ( CM ) 12.000  
 EPSILON 0.3000  
 MAXIMUM NUMBER OF ITERATIONS 10

TABLE 4-3

Comparison of evaporation fluxes calculated using the coupled and uncoupled equations for Runs 1 and 2. Soil temperatures decreasing with depth.

Initial conditions	Time step J*	Coupled EV**	Uncoupled EV	(EV uncoupled / EV coupled)
Run 1	15	-0.7415x10 <sup>-3</sup>	-0.1551x10 <sup>-2</sup>	2.09
	16	-0.7935x10 <sup>-3</sup>	-0.1552x10 <sup>-2</sup>	1.96
	17	-0.8638x10 <sup>-3</sup>	-0.1553x10 <sup>-2</sup>	1.80
	18	-0.9408x10 <sup>-3</sup>	-0.1553x10 <sup>-2</sup>	1.65
	19	-0.1019x10 <sup>-2</sup>	-0.1553x10 <sup>-2</sup>	1.52
	20	-0.1095x10 <sup>-2</sup>	-0.1552x10 <sup>-2</sup>	1.42
	21	-0.1169x10 <sup>-2</sup>	-0.1551x10 <sup>-2</sup>	1.33
Run 2	15	-0.7366x10 <sup>-2</sup>	-0.7752x10 <sup>-2</sup>	1.05
	16	-0.7412x10 <sup>-2</sup>	-0.7776x10 <sup>-2</sup>	1.05
	17	-0.7464x10 <sup>-2</sup>	-0.7798x10 <sup>-2</sup>	1.04
	18	-0.7518x10 <sup>-2</sup>	-0.7817x10 <sup>-2</sup>	1.04
	19	-0.7571x10 <sup>-2</sup>	-0.7833x10 <sup>-2</sup>	1.03
	20	-0.7622x10 <sup>-2</sup>	-0.7847x10 <sup>-2</sup>	1.03
	21	-0.7669x10 <sup>-2</sup>	-0.7857x10 <sup>-2</sup>	1.02

\*7J = 2 hr

\*\*EV = evaporation flux in cm/hr

TABLE 4-4

Comparison of moisture fluxes calculated using the coupled and uncoupled equations for Runs 1 and 2. Soil temperatures decreasing with depth.

Initial conditions		Node Depth		Coupled $q_w/\rho\theta$ J=21		Uncoupled $q_w/\rho\theta$ J=21		$\frac{q_w/\rho}{ coupled}$	
		(cm)		(cm/hr)		(cm/hr)			
Run 1	2	0	-0.1169x10 <sup>-2</sup>	-0.1551x10 <sup>-2</sup>	1.33				
	3	12	-0.1099x10 <sup>-2</sup>	-0.1485x10 <sup>-2</sup>	1.35				
	4	24	-0.9351x10 <sup>-3</sup>	-0.1303x10 <sup>-2</sup>	1.39				
	5	36	-0.8335x10 <sup>-3</sup>	-0.1050x10 <sup>-2</sup>	1.26				
	6	48	-0.6808x10 <sup>-3</sup>	-0.841x10 <sup>-3</sup>	1.24				
Run 2	2	0	-0.4869x10 <sup>-2</sup>	-0.7857x10 <sup>-2</sup>	1.02				
	3	12	-0.4761x10 <sup>-2</sup>	-0.4899x10 <sup>-2</sup>	1.03				
	4	24	-0.1245x10 <sup>-2</sup>	-0.1387x10 <sup>-2</sup>	1.11				
	5	36	-0.5071x10 <sup>-3</sup>	-0.5844x10 <sup>-3</sup>	1.15				
	6	48	-0.2699x10 <sup>-3</sup>	-0.3208x10 <sup>-3</sup>	1.19				

TABLE 4-5

Comparison of evaporation fluxes calculated using the coupled and uncoupled equations for Runs 1 and 2. Soil temperatures increasing with depth.

Initial conditions	Time Step J*	Coupled E <sub>y</sub> **	Uncoupled E <sub>v</sub>	$\frac{E_v \text{ uncoupled}}{E_v \text{ coupled}}$
Run 1	64	-0.1830x10 <sup>-2</sup>	-0.1366x10 <sup>-2</sup>	0.746
	65	-0.1805x10 <sup>-2</sup>	-0.1362x10 <sup>-2</sup>	0.755
	66	-0.1770x10 <sup>-2</sup>	-0.1359x10 <sup>-2</sup>	0.768
	67	-0.1773x10 <sup>-2</sup>	-0.1357x10 <sup>-2</sup>	0.765
	68	-0.1694x10 <sup>-2</sup>	-0.1354x10 <sup>-2</sup>	0.799
	69	-0.1656x10 <sup>-2</sup>	-0.1352x10 <sup>-2</sup>	0.816
	70	-0.1620x10 <sup>-2</sup>	-0.1350x10 <sup>-2</sup>	0.833
Run 2	37	-0.7689x10 <sup>-2</sup>	-0.7619x10 <sup>-2</sup>	0.991
	38	-0.7836x10 <sup>-2</sup>	-0.7585x10 <sup>-2</sup>	0.968
	39	-0.7800x10 <sup>-2</sup>	-0.7550x10 <sup>-2</sup>	0.968
	40	-0.7262x10 <sup>-2</sup>	-0.7514x10 <sup>-2</sup>	0.968
	41	-0.7722x10 <sup>-2</sup>	-0.7477x10 <sup>-2</sup>	0.968
	42	-0.7681x10 <sup>-2</sup>	-0.7440x10 <sup>-2</sup>	0.969

\*7J - 2 hr

\*\*E<sub>v</sub> = evaporation flux in cm/hr

TABLE 4-6

Comparison of moisture fluxes calculated using the coupled and uncoupled equations for Runs 1 and 2. Soil temperatures increasing with depth.

Initial conditions	Node	Depth (cm)	Coupled $q_w/\rho$ (cm/hr)		Uncoupled $q_w/\rho$ (cm/hr)		$\frac{q_w/\rho \text{ unc.}}{q_w/\rho \text{ coupled}}$
			(cm/hr)	(cm/hr)	(cm/hr)	(cm/hr)	
Run 1 (J* = 70)	2	0	-0.1620x10 <sup>-2</sup>	-0.1350x10 <sup>-2</sup>	-0.1350x10 <sup>-2</sup>	0.833	
	3	12	-0.1522x10 <sup>-2</sup>	-0.1310x10 <sup>-2</sup>	-0.1310x10 <sup>-2</sup>	0.861	
	4	24	-0.1306x10 <sup>-2</sup>	-0.1229x10 <sup>-2</sup>	-0.1229x10 <sup>-2</sup>	0.941	
Run 2 (J* = 42)	2	0	-0.7681x10 <sup>-2</sup>	-0.7440x10 <sup>-2</sup>	-0.7440x10 <sup>-2</sup>	0.969	
	3	12	-0.4626x10 <sup>-2</sup>	-0.4560x10 <sup>-2</sup>	-0.4560x10 <sup>-2</sup>	0.986	

\*7J - 2-hr

(p. 160 and thereafter). These figures, in conjunction with the moisture flux equation (2-38)<sup>1</sup>, show that the drier the soil becomes the more dominant the second term B in (4-19) becomes. Therefore, under very dry conditions and with the temperature decreasing with depth, the positive (downward) term B in (4-19) exceeds the negative (upward) term A in magnitude. As a consequence, evaporation becomes positive; that is, a condensation effect results. This situation was simulated by imposing the initial and top boundary conditions of Run 3 (Figs. 4-8 and 4-9), consisting of a highly negative  $\psi$  distribution with depth, coupled with high surface temperatures and a constant initial temperature gradient of 0.55  $^{\circ}\text{C}/\text{cm}$  throughout. A sample of simulated results are shown in Tables 4-7 and 4-8.

The transport coefficients used in this model differ from the familiar form of Philip and de Vries' (1957) coefficients in that they are derived from the more general  $\psi$ -based equations. As can be seen in Fig. 4-10, the model-calculated  $K_{\psi}$  values (2-17) are extremely small. However, in the range of water contents where the soil relative humidity  $h$  is below 100%, the considerable increase of the pressure head gradient  $\partial\psi/\partial z$  will cause the product  $(K_{\psi} \partial\psi/\partial z)$  appearing in (4-1) to rise to a maximum value

<sup>1</sup>In one-dimensional form, this equation becomes

$$q_w/e = \underbrace{-K_{\psi} \partial\psi/\partial z}_A - \underbrace{D_T \partial T/\partial z}_B + \underbrace{K_i}_C \quad (4-19)$$

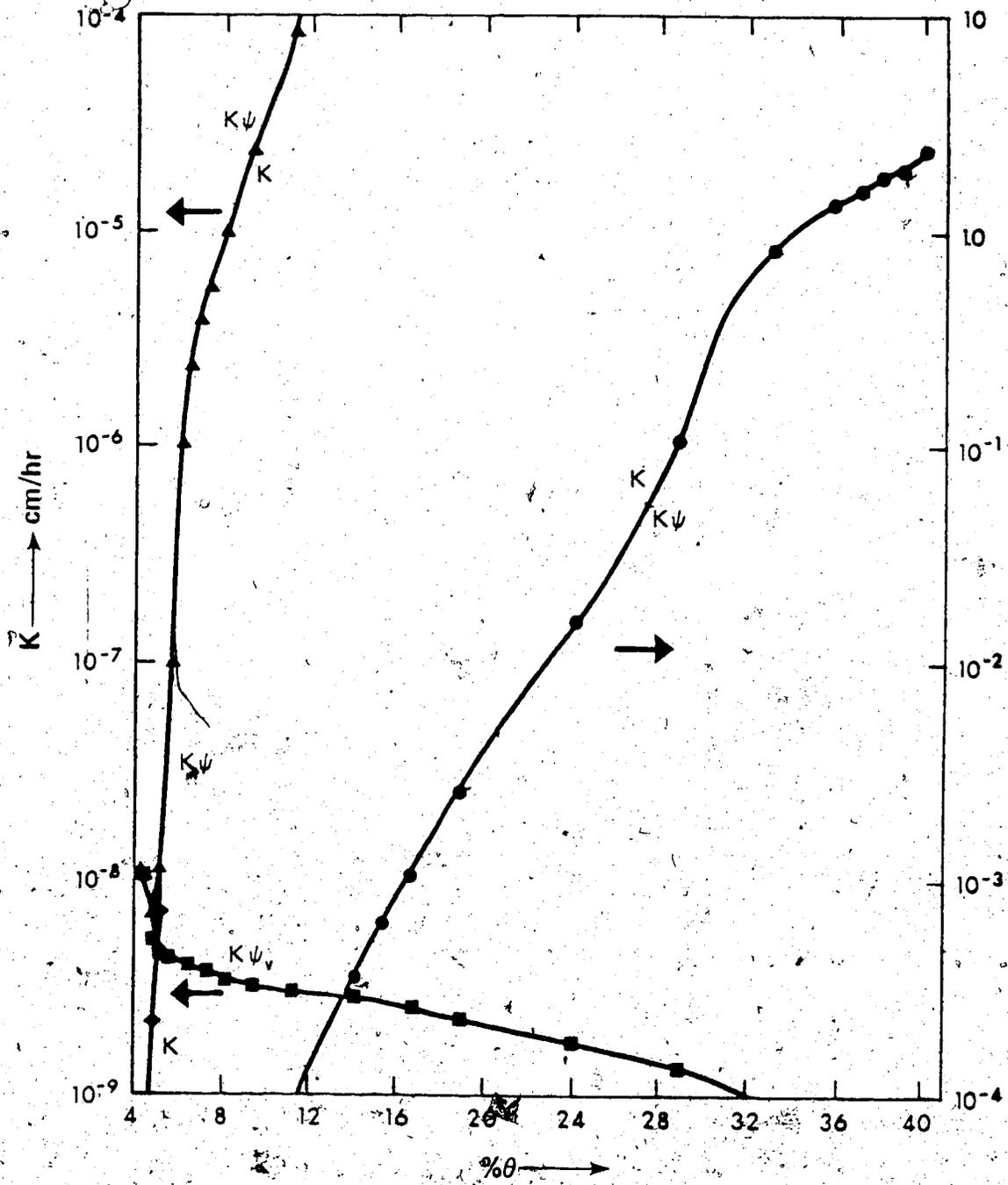


Figure 4-10. Total water (hydraulic) conductivity function  $K_\psi(\theta)$

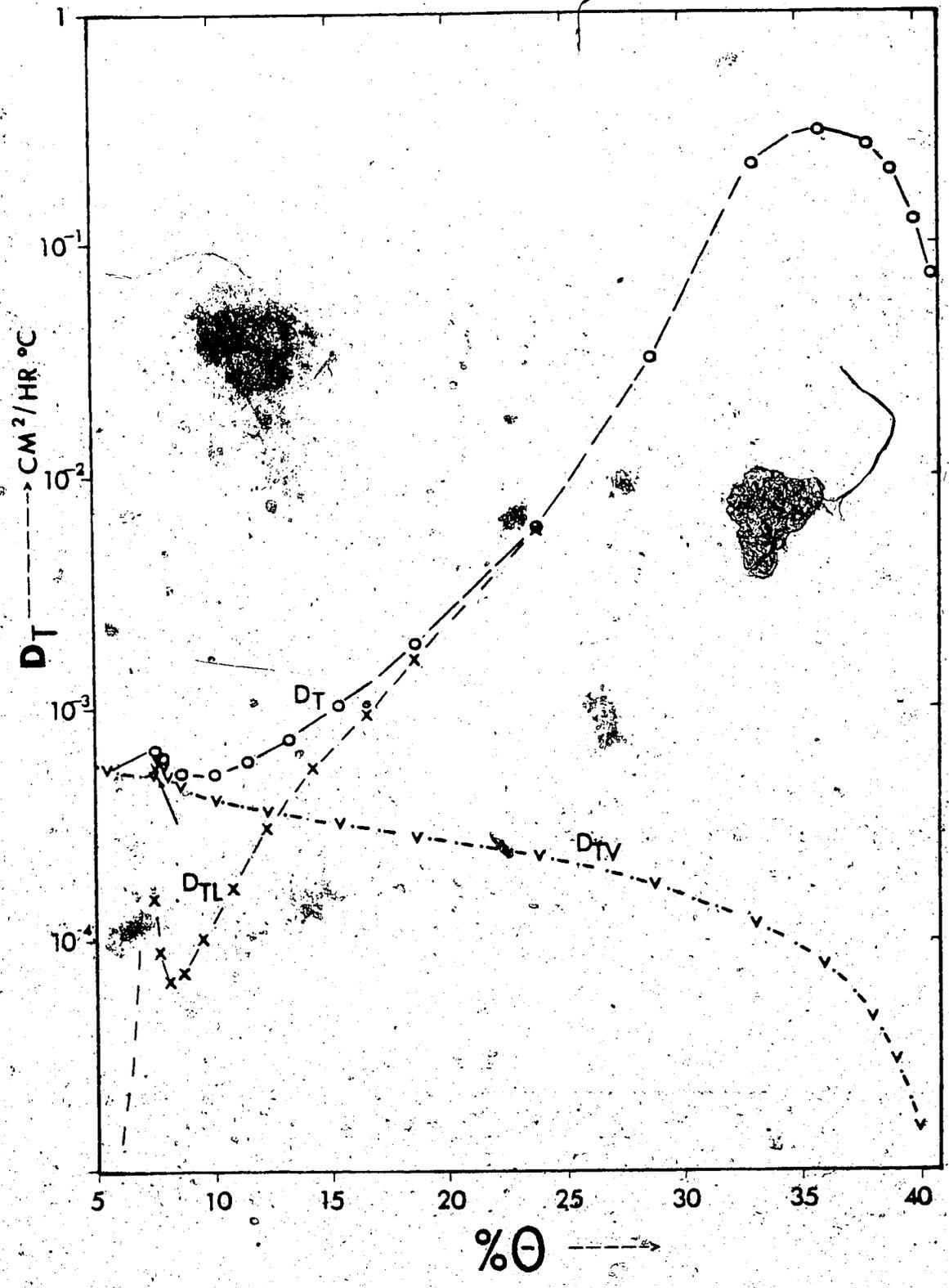


Figure 4-11. Thermal diffusivity function  $D_T(\theta)$

TABLE 4-7

Comparison of evaporation fluxes calculated using the coupled and uncoupled equations for Run 3

Time step, J*	Coupled EV**	Uncoupled EV
3	0.3596x10 <sup>-4</sup>	-0.1212x10 <sup>-5</sup>
4	0.4794x10 <sup>-4</sup>	-0.1311x10 <sup>-5</sup>
5	0.4829x10 <sup>-4</sup>	-0.1384x10 <sup>-5</sup>
6	0.3893x10 <sup>-4</sup>	-0.1440x10 <sup>-5</sup>
7	0.2115x10 <sup>-4</sup>	-0.1482x10 <sup>-5</sup>

\*J = 2 hr

\*\*EV = evaporation flux in cm/hr

TABLE 4-8

Comparison of moisture fluxes calculated using the coupled and uncoupled equations for Run 3

Node Depth (cm)	Coupled $q_w^*/\rho$ @ J = 7	$q_v^{**}/\rho$ @ J=7***	Uncoupled $q_w/\rho$ @ J = 7
2	0.2115x10 <sup>-4</sup>	0.2828x10 <sup>-3</sup>	-0.1482x10 <sup>-5</sup>
3	0.1536x10 <sup>-3</sup>	0.1545x10 <sup>-3</sup>	-0.9405x10 <sup>-6</sup>
4	0.2159x10 <sup>-4</sup>	0.2402x10 <sup>-4</sup>	-0.2474x10 <sup>-5</sup>
5	-0.1124x10 <sup>-4</sup>	0.1997x10 <sup>-4</sup>	-0.3152x10 <sup>-4</sup>
6	-0.2718x10 <sup>-3</sup>	0.1955x10 <sup>-4</sup>	-0.2941x10 <sup>-3</sup>

\* $q_w/\rho$  = moisture flux in cm/hr  
 \*\* $q_v/\rho$  = vapor flux in cm/hr  
 \*\*\*7J = 2 hr

before eventually falling to zero as  $\theta$ , and therefore  $h$ , approach zero. Notice in Fig. 4-10 that  $K_{\psi_v}$  dominates over  $K$  at very low moisture contents.

The thermal diffusion coefficients calculated from the model are shown in Fig. 4-11. The  $D_{TV}$  coefficient increases continuously with decreasing moisture content and becomes the dominant thermal diffusion coefficient at low moisture contents, as can be seen in the figure. The break in slope in the  $D_{TV} - \theta$  curve (marked by an arrow in the figure) is due to the break-up of the  $\zeta$ -values used in this program (p. 141). As mentioned before, there is some uncertainty in the determination of  $D_{TL}$  coefficient, as proposed by the Philip and de Vries surface tension model (p. 29). Values of the  $D_{TL}$  coefficient computed from (2-37) were compared with the values obtained by the Philip and de Vries model (2-35) and were found 37% to 41% larger than the latter, as shown in Table 4-9. My approximation seems to be a better one in view of the fact that experimentally measured values of  $D$  were up to twice (Wilkinson and Klute, 1962) or more as large (Jury and Miller, 1974) as those computed by the Philip and de Vries model. The  $D_{TL}$  coefficient (Fig. 4-11) increases with increasing water content, before starting to rapidly decrease near saturation.

An explanation of this  $D_{TL}$  coefficient pattern is as follows (Joshua and de Jong, 1973). Most of the observed deviations of water flux in porous media from Darcy's law

TABLE 4-9

Comparison of  $D_{Tl}$  values computed using the presently proposed model and Philip and de Vries's for Run 1

$\theta$	$D_{Tl}$	$2D_{Tl}^*$ (Ph. & de V.)	$\frac{10 D_{Tl}}{2 D_{Tl}}$
0.1579	$1.023 \times 10^{-3}$	$6.417 \times 10^{-4}$	1.59
0.1631	$1.081 \times 10^{-3}$	$6.711 \times 10^{-4}$	1.61
0.1679	$1.180 \times 10^{-3}$	$7.283 \times 10^{-4}$	1.62
0.2360	$5.868 \times 10^{-3}$	$3.529 \times 10^{-3}$	1.66
0.2945	$4.396 \times 10^{-2}$	$2.625 \times 10^{-2}$	1.67
0.3796	$2.746 \times 10^{-1}$	$1.633 \times 10^{-1}$	1.68
0.4069	$7.900 \times 10^{-2}$	$4.692 \times 10^{-2}$	1.68

\*J = 21  
 \*\* $D_{Tl}$ :  $cm^2/hr/C$

are attributed to interactions between the water and the porous medium (Swartzendruber, 1969). This interaction is proportional to the area of contact between the porous medium and liquid water and increases as the medium pore sizes decrease. Hence, as the water content in the soil decreases, the proportion of water flow that occurs in the smaller pores increases and thus soil-water interaction increases. In general, coupling phenomena are also pronounced when interaction between the fluid and the porous medium occurs. This phenomenon can be demonstrated by the increase in thermally induced water flow which occurs with increasing soil dryness, a case presented in this thesis. When soil-water flow takes place at high water contents, a large proportion of this flow occurs through the larger pores, thereby minimizing the effect of soil-water interaction. Therefore, the decrease in  $D_{Tc}$  at high water contents may be attributed to low soil-water interaction. However, at very low water contents, when vapor flow becomes of importance, the largest proportion of vapor flow would occur in the large air-filled pores; thus, little coupling between heat and moisture can be expected.

Birksen (1969) tried to apply the above observations to saturated clay suspensions. He reasoned that by decreasing the water content of these saturated clay suspensions by increasing the compaction pressure, the temperature gradients would become more effective than hydraulic gradients in causing water to move within compacted

sediments. Although he observed an increase in thermally induced flow with increasing compaction pressure, the amount of such flow in his experiments was generally less than that reported for liquid water in unsaturated soils at comparable water contents. This result was attributed to the influence of the vapor phase which is absent under saturated conditions.

The calculated secondary maximum in the  $D_{TL} - \theta$  relationship (Fig. 4-11) at the low water content range is due to the faster relative increase of  $|\ln h|$  with decreasing water content compared to a slower relative decrease of  $K$  in that range of water contents (2-37). Data to check the physical significance of this observation are not available.

The transport coefficient  $D_L$  (4-1c) appearing in (4-1b) is usually extremely small in magnitude. As can be seen in Fig. 4-12, it increases significantly at low moisture contents. This increase -- combined with a large increase in the pressure head gradient  $\partial\psi/\partial z$  -- will cause this latent heat flux component ( $D_L \partial\psi/\partial z$ ) appearing in (4-1b) to reach a maximum value before eventually falling to zero as  $\theta$  approaches zero.

The temperature field in the simulation runs presented here was not appreciably influenced by coupling or uncoupling because in the range of water contents over which most of the simulations were run, that is, above 5% by

TABLE 4-10  
 Comparison of conductive and convective heat flux  
 components for Run 3

$\theta$	$ QCD ^{**}$	$ QCV ^{***}$	$\%( QCV/QCD )$
0.0610	$1.236 \times 10^{-1}$	$1.551 \times 10^{-4}$	0.12
0.0762	$1.355 \times 10^{-1}$	$4.722 \times 10^{-4}$	0.35
0.0929	$1.632 \times 10^{-1}$	$6.605 \times 10^{-4}$	0.41
0.1124	$1.754 \times 10^{-1}$	$1.194 \times 10^{-3}$	0.68
0.1886	$5.701 \times 10^{-1}$	$1.566 \times 10^{-2}$	2.75
0.2410	$5.966 \times 10^{-1}$	$2.513 \times 10^{-2}$	4.21
0.2882	$3.768 \times 10^{-1}$	$2.524 \times 10^{-2}$	6.70
0.3311	$3.894 \times 10^{-1}$	$3.436 \times 10^{-2}$	8.82
0.3701	$6.896 \times 10^{-1}$	$3.728 \times 10^{-2}$	5.41
0.3904	$9.568 \times 10^{-1}$	$3.533 \times 10^{-2}$	3.69

\*  $J_0 = 21$   
 $**|QCD| = |\lambda \frac{\partial T}{\partial z}|$  (cal/cm<sup>2</sup>/hr)  
 $***|QCV| = |c_1 \rho_w \frac{\Delta T}{\Delta t}|$  (cal/cm<sup>2</sup>/hr)  $\Delta T = |T_{i+1} - T_i|$

volume, the conductive term of the heat flux equation (2-58) was dominant over the latent and convective terms of the total heat flux. Under very dry conditions, however, the latent heat term of the heat flux equation (2-58) becomes increasingly important. At the same time, the conductive term decreases rapidly. It should be noted that the convective term of the heat flux equation (the third term of 2-58) -- which is usually neglected in non-isothermal studies -- becomes increasingly important at higher water contents, as shown in Table 4-10.

As can be seen in Figs. 4-10, 4-11 and 4-12 shown above, the computed transport coefficients are extremely variable with changing water content. This non-linearity of the system (4-1) prevents characterization by constant coefficients. It should also be noticed that when the volumetric water content becomes less than about 5%, thermally driven moisture is larger than the potential gradient flow (Fig. 4-10) for the Taber sites.

The hydraulic conductivity-water content relationship used in any water flow model exerts a significant influence on the simulation results because the calculated water fluxes and several transport coefficients depend on this relationship. For the present study, conductivity functions for two different depths of Site 2 were experimentally determined (Figs. 3-25, C-14). Both hydraulic conductivity functions were input to the computer simulation model to

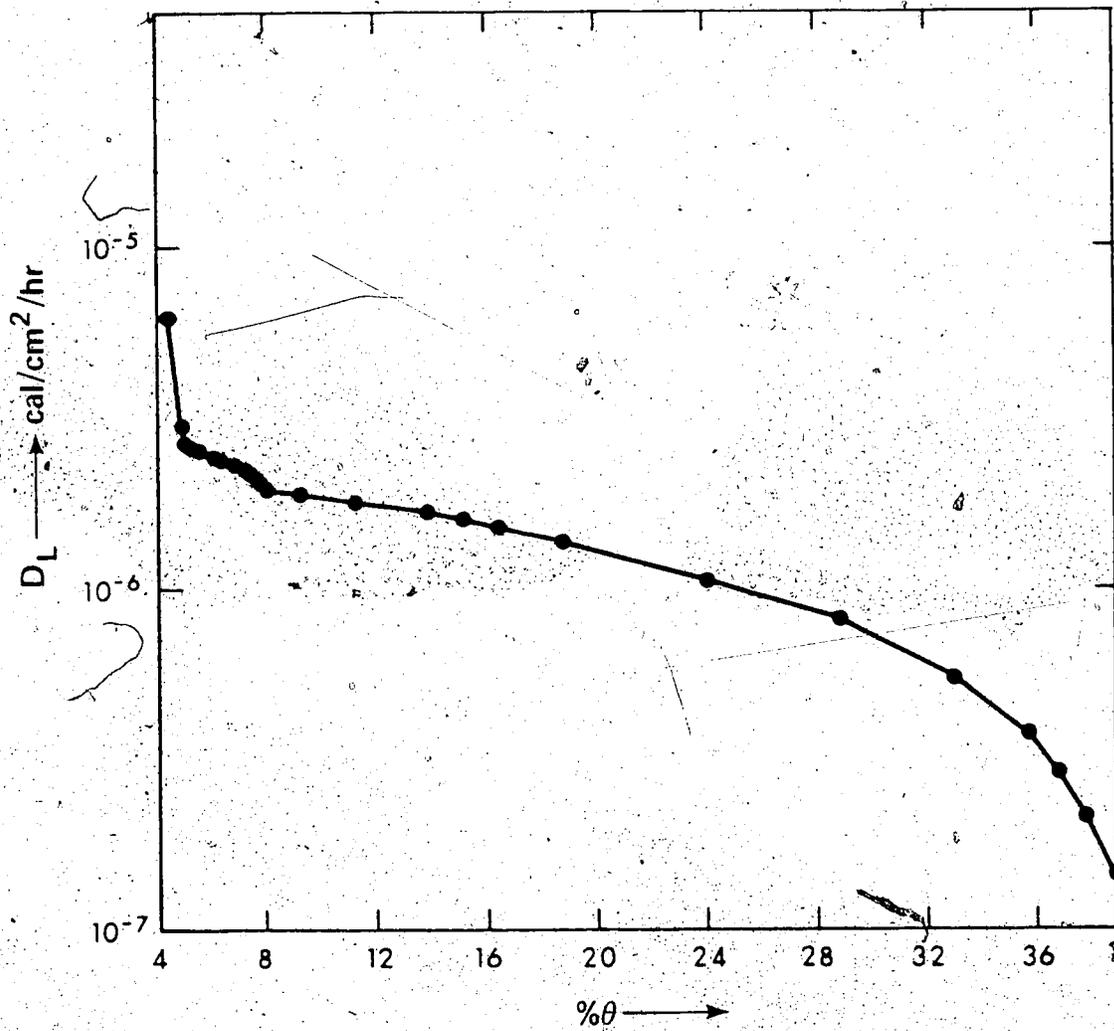


Figure 4-12.  $D_L(\theta)$  coefficient function

determine which one resulted in a better agreement between observed and simulated results. I found that the hydraulic conductivity function of the surface -20 cm of soil resulted in a comparatively better match between observed and simulated data and was thus considered more representative of the whole unsaturated profile.

Figure 4-13 shows the sinusoidal input surface temperature-time distribution together with the model calculated temperature distribution at depths of 12 and 24 cm. A decrease in amplitude of the temperature wave and a time lag with increasing depth are apparent in that figure. The calculated evaporation flux-time distribution is also shown. A pattern similar to the temperature distribution is also observed with the heat flux distribution calculated by the model, as shown in Fig. 4-14. The time distribution of the pressure head in the vicinity of the water table for the same drying conditions (Run 2) is shown in Fig. 4-15, where the gradual decrease in the water table depth with time is apparent.

The evaporation rate-time distribution under a diurnal varying environment resulted in a series of diurnal evaporation phases, as shown in Fig. 4-16, which tended to damp down in time as the surface zone desiccation progressed to greater depths. Such a pattern was actually measured in the field by Kimball and Jackson (1971). In simulating this evaporation pattern, a sinusoidal surface

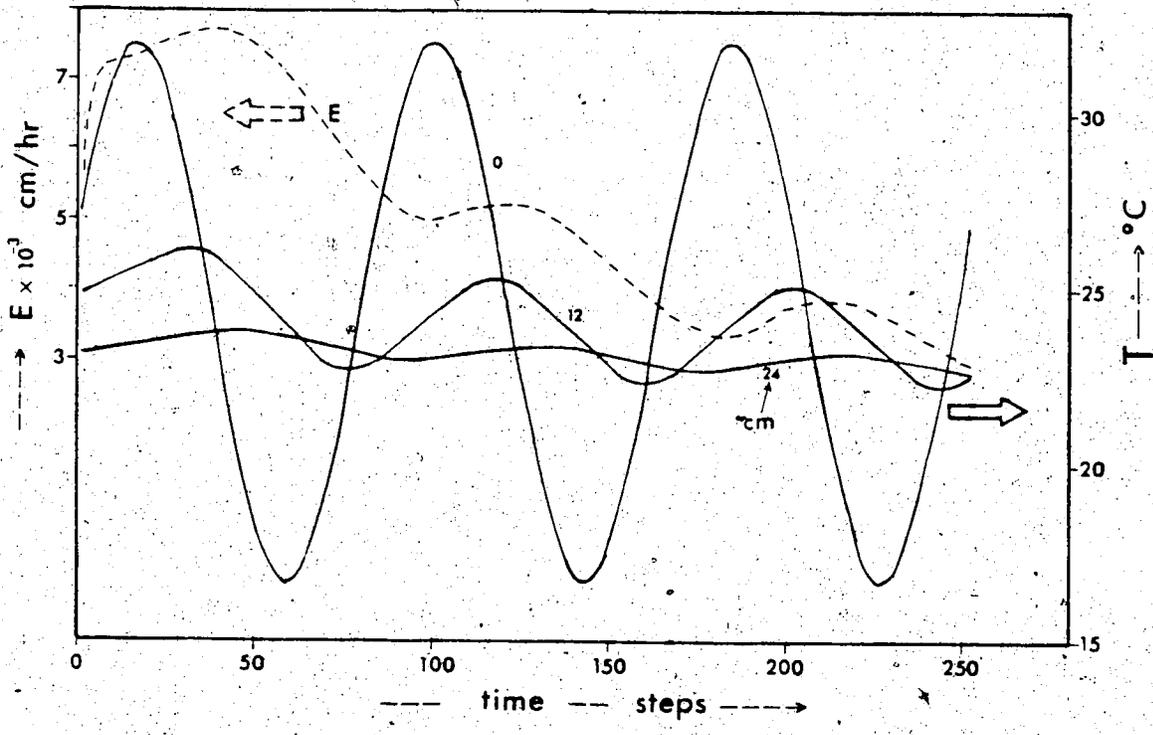


Figure 4-13. Time distribution of evaporation flux and temperatures at various depths

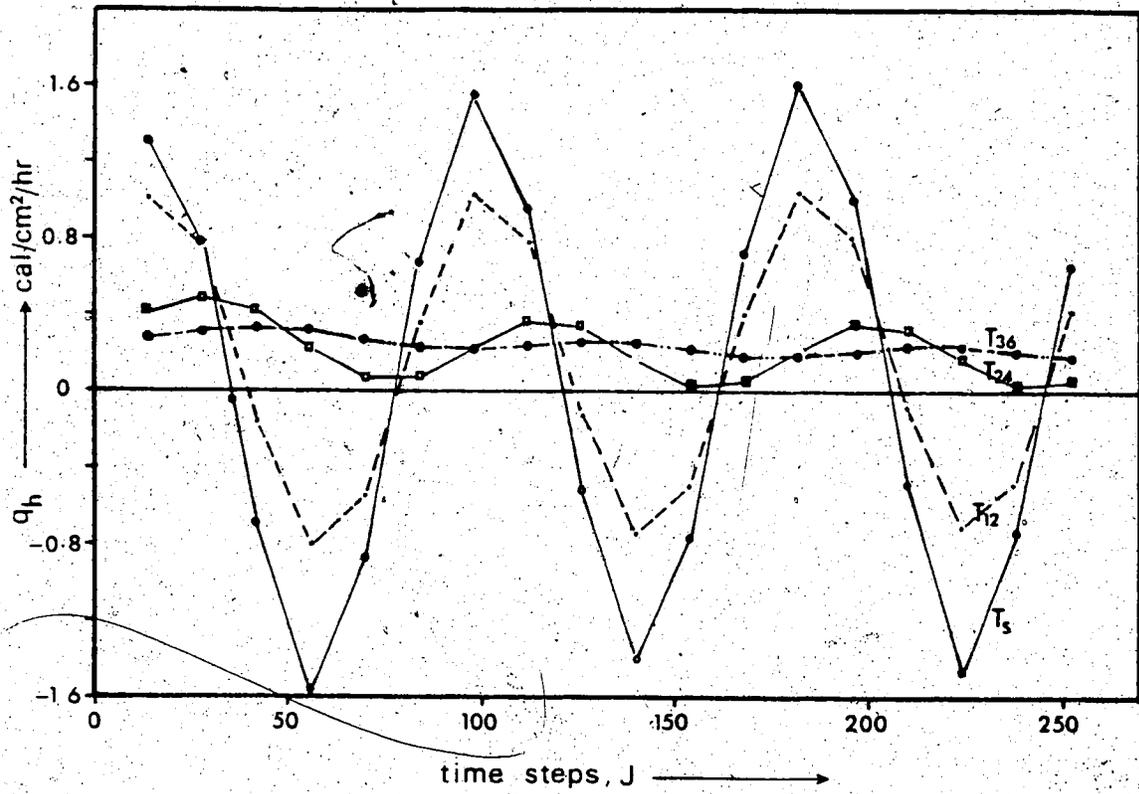


Figure 4-14. Time distribution of heat fluxes at various depths

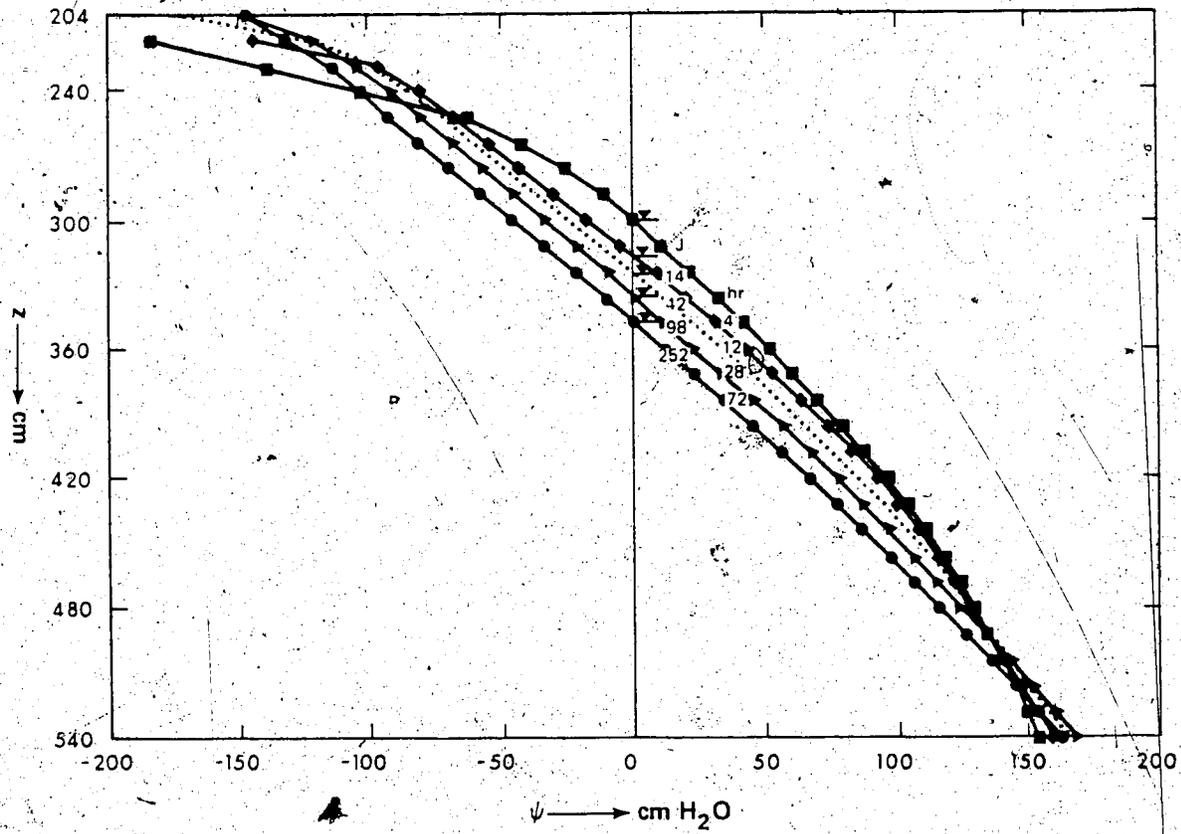


Figure 4-15. Time distribution of pressure head in the vicinity of the water table.

temperature distribution similar to the one shown in Fig. 4-13 and the initial conditions for Run 2 (Fig. 4-8) were applied. It should be noticed that after the third day of evaporative drying, a stable evaporation rate-time wave pattern was observed. The time distribution of the water flux at 12 cm depth is also indicated in Figure 4-16. This distribution exhibits a similar diurnal cycle but with smaller fluctuations decreasing progressively in the deeper layers.

Although special emphasis was placed on the drying problem, the infiltration problem could also be handled by the present simulation model. An example of a wetting situation is given in Fig. 4-17, where the time-depth pressure head profiles under a constant infiltration rate of 0.09 cm/hr are shown.

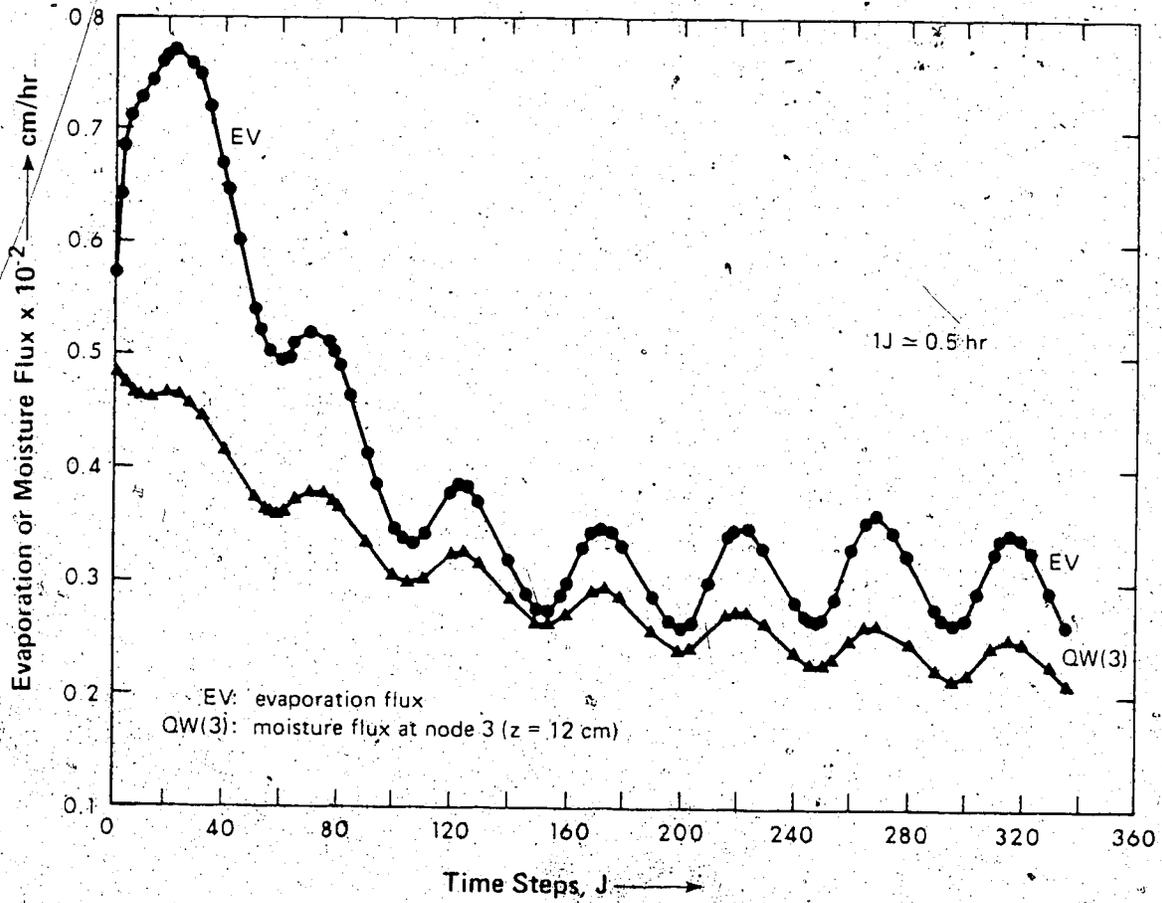


Figure 4-16. Cyclic evaporation distribution

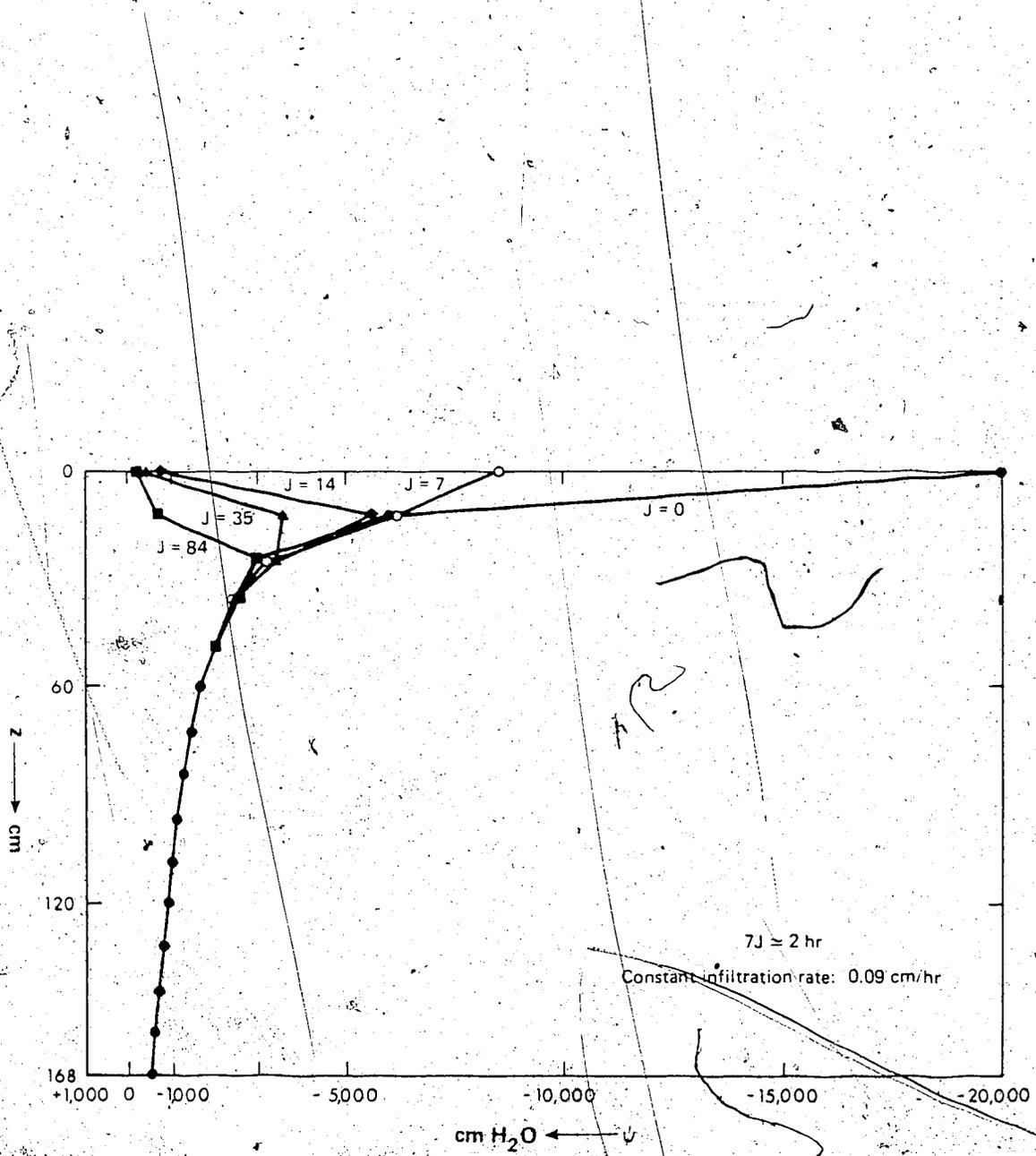


Figure 4-17. Pressure head distribution during infiltration

## CHAPTER 5

### CONCLUDING COMMENTS AND RECOMMENDATIONS

The present study has demonstrated the feasibility of applying and modeling the non-isothermal flow theory to a field situation. Comprehensive field and laboratory data collected here are generally unavailable in a single study. It is hoped that the present work partly overcomes the deficiency caused by a lack of necessary data for the application and modeling of non-isothermal theories, and for comparisons of theoretical and model results with experimental data. The simplified procedures for field applications of non-isothermal theory developed here (Section 2.8) are as accurate as the available analytical models and are suggested for field applications in suitable environments.

This work showed that the mechanistic, Philip and de Vries-type of non-isothermal theory can be modified and extended to saturated conditions. These developments involved the introduction of a new approach for the calculation of liquid thermal diffusion coefficients based on local vapor-liquid equilibration in porous media (2-37); also of procedures for calculating the various transport coefficients based on calculating ratios of these

coefficients and combining these ratios with a detailed heat flux equation (Section 2.8). Several problems involving the application of the proposed field methodology became apparent, such as the inadequacies of the thermocouple psychrometers used in the field, the insensitivity of some instruments to small changes in field parameters, the very small magnitude of various transport coefficients involved in non-isothermal flow studies, and others (Section 3.8).

A comparative study of the mechanistic and irreversible thermodynamics approach to coupled problems indicated that the latter has not yet advanced beyond carefully controlled laboratory conditions. The present study verified, at least in a general sense, the mechanistic non-isothermal theory under field conditions. It is apparent that precise and accurate measurements of heat and water fluxes are essential to test the validity of non-isothermal equations.

This work showed how field equipment can be improved or modified to meet the particular needs of the researcher. For example, in order to meet the challenge of the field experimentation, novel procedures for design and construction of field equipment were developed with respect to thermal conductivity probes, piezometers and the various combinations of data recording devices. Thus, a new design for installing and recovering the thermal conductivity probes was implemented; also, minor modifications in the construction of thermal conductivity probes were carried

out. Another modification which proved to be very useful was the addition of a stainless steel screen to the bottom of the non-slotted piezometers.

This study was the first to demonstrate the possibilities for using a unified unsaturated-saturated approach to non-isothermal flow conditions. As a result, the scope or scale of applicability of the various non-isothermal transport parameters and equations -- which were previously restricted to the uppermost layer of the ground surface or small lab columns -- was extended to accommodate such an approach.

My research showed that it is possible to model the simultaneous flow of water and heat in unsaturated-saturated domains based on an adaptation of the Philip and de Vries model. I developed and tested this modification using measured field and laboratory data. I found the agreement between the transient numerical solution of the coupled equations under varying top boundary conditions and the field observed data satisfactory. The present model predicts soil temperatures, pressure heads and water contents as well as all relevant transport coefficients and fluxes. It is general enough to be applied to related problems of simultaneous heat and water transfer where a predictive capability is needed.

The influence of coupling on diurnal subsurface water and heat transfer can be determined by comparing the

non-isothermal and the isothermal solutions of the water and heat flow equations using the appropriate options built into the present simulation model. The results confirmed that coupling did not noticeably influence the temperature field but did affect the evaporation and subsurface moisture fluxes. Thus, depending on the direction of the temperature and pressure head gradients, the subsurface moisture fluxes might have been underestimated or overestimated significantly (up to -40% for cases studied here) using an isothermal model. The analysis of transport coefficients for the study area indicated that thermally induced moisture movement becomes dominant at very low moisture contents.

The non-isothermal theory can be used to calculate evaporation from the soil surface based on moisture and temperature profiles. Comparison of evaporation rates calculated using the coupled and uncoupled equations indicated that non-isothermal evaporation rates were higher or lower than the isothermal ones depending on the direction of the temperature and pressure head gradients. The magnitude of such differences was up to a factor of two for the cases studied here, depending on the soil moisture levels. Thus, for example, hourly evaporation estimates using an isothermal model could be overestimated by a factor of two.

A cyclic evaporation pattern was evident under diurnal conditions. As a consequence, the three stages of the

evaporation process (Lemon, 1956) under constant evaporativity (or evaporative demand of the atmosphere) lose their distinctness. At the end of a week-long simulation, such cyclic evaporation-time waves were still apparent.

Because of the predominance of the conductive heat transfer over all other modes of heat transport in the cases studied here and the generally small magnitude of the thermal diffusion coefficient compared to the hydraulic conductivity coefficient under wet soil conditions, the isothermal model may be used adequately to predict pressure head and temperature profiles on a short-term basis (greater than 24 hr). However, for long term simulations under extended drying conditions, the coupled model should be preferred in studying the long range seasonal influences on water transport, especially in view of the fact that measured values of the  $D_{Te}$  coefficient are much larger than model predicted ones (Jury and Miller, 1974).

Much remains to be done in order to consolidate and expand the applicability of coupled non-isothermal models. Further generalization of results obtained here will require the study of environments differing with respect to the porous materials and the ranges of pressure heads. More experimental information is needed on the thermal dependence of the pressure potential, particularly under saturated conditions. Quantification of such information would assist

in the effort to understand the physical flow processes occurring in geothermal areas. For the same reasons, the simple non-isothermal model extension to saturated conditions that I have proposed needs to be substantiated in suitable environments. More efficient experimental procedures are required in order to determine pore geometry factors ( $f$ ),  $\zeta$  or  $\xi$  coefficient values appearing in the transport coefficients of non-isothermal models. Comparisons of model-calculated parameters and experimentally measured ones in a broad range of conditions are required to establish their validity. Real world complications involving hysteretic phenomena, solute effects, deformable media and others remain to be considered in non-isothermal studies. Considerable research is still needed in order to develop and/or improve available numerical techniques for the efficient solution of strongly non-linear problems. At present, abrupt changes in model parameters and other conditions cannot be adequately handled in coupled non-linear problems.

The possibilities for a model technique to simulate a real phenomenon rests on the physical representativeness of the characteristic and conductivity functions because all calculated fluxes and coefficients strongly depend on these functions. Improved experimental techniques for the measurement of hydraulic and thermal properties of porous materials as well as of water potential measurements -- especially under high negative pressure heads -- are

required. It is hoped that as specific research perfects experimental measurements, the problem of obtaining reliable field measurements will diminish. In order to expand non-isothermal models from a local to a regional scale, the problem of the determination of hydraulic and thermal properties on a macroscale needs to be solved. Statistical techniques, based on a physical understanding of the processes involved, seem the appropriate method to handle this problem.

Even when all the previously mentioned sophisticated aspects of non-isothermal models are achieved, a model simple enough and accurate enough for practical uses must be the ultimate goal. In my opinion, such a model can be constructed by a combination of physical and statistical strategies: the physical one contributing to a better understanding of each mechanism influencing non-isothermal transfer, and the statistical one simplifying and generalizing the results of the former strategy.

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APPENDIX A

TEMPERATURE AND POTENTIAL EVAPORATION DISTRIBUTIONS

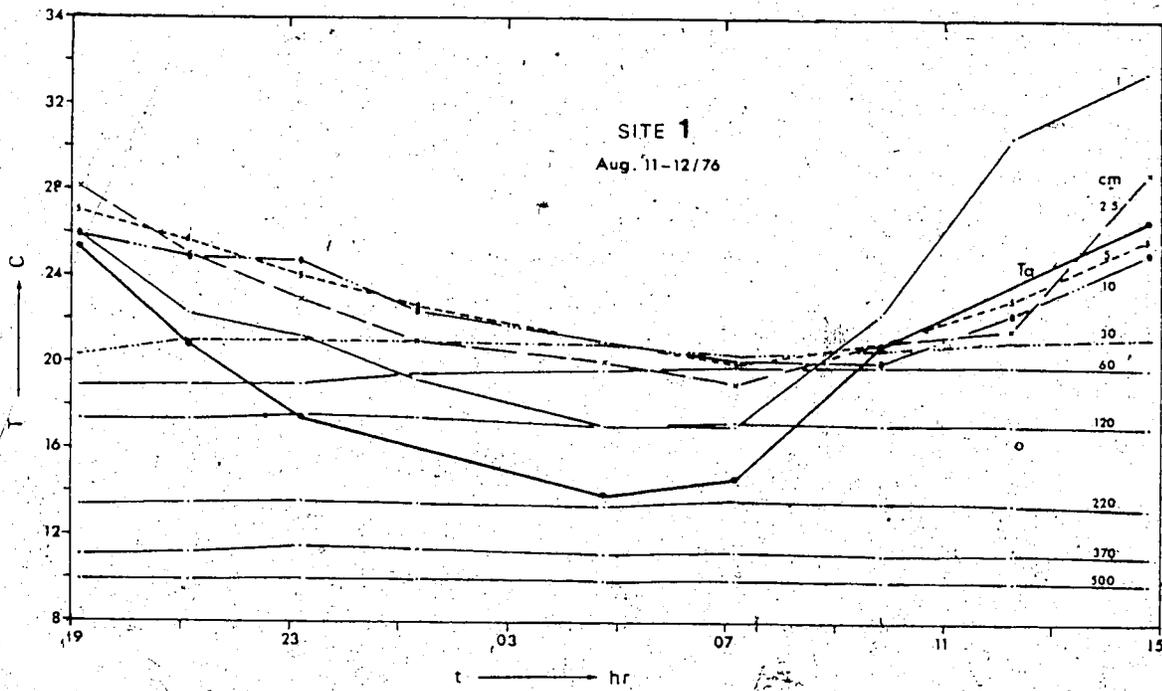


Figure A-1. Time-depth distribution of temperature at Site 1

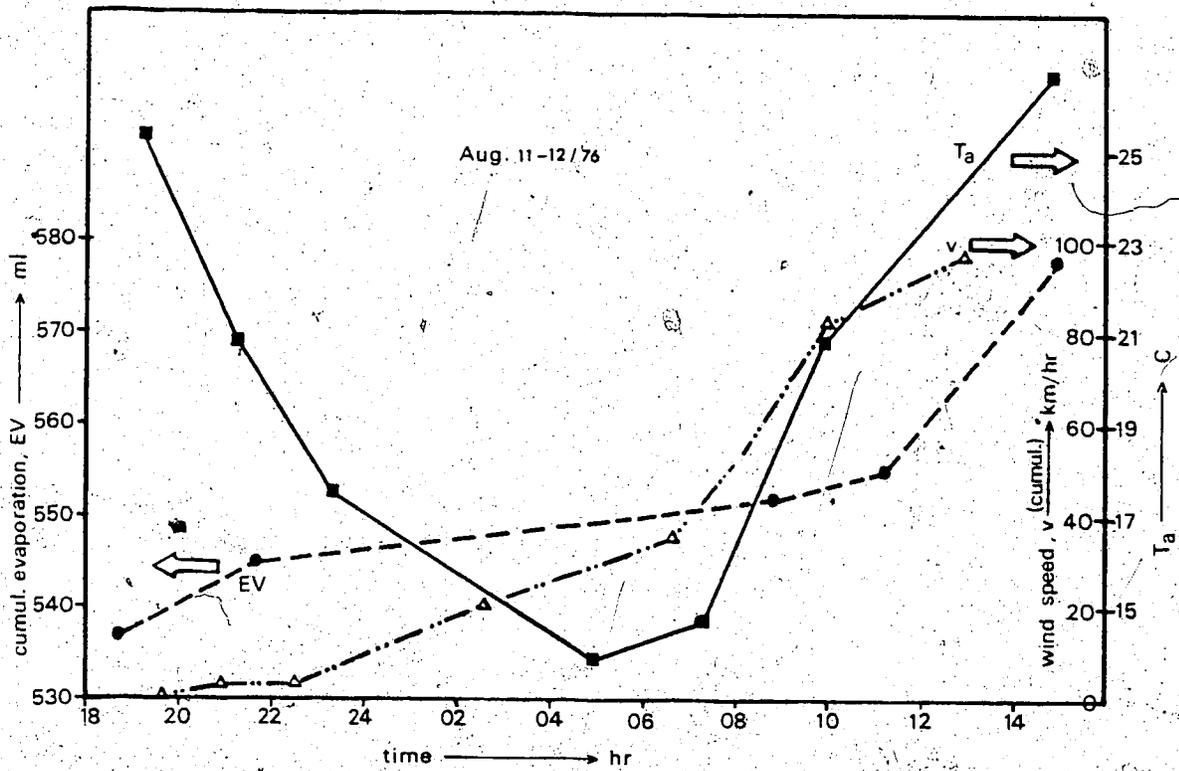


Figure A-2. Potential evaporation fluxes, air temperatures and wind speeds at the Taber sites during August 11-12/76

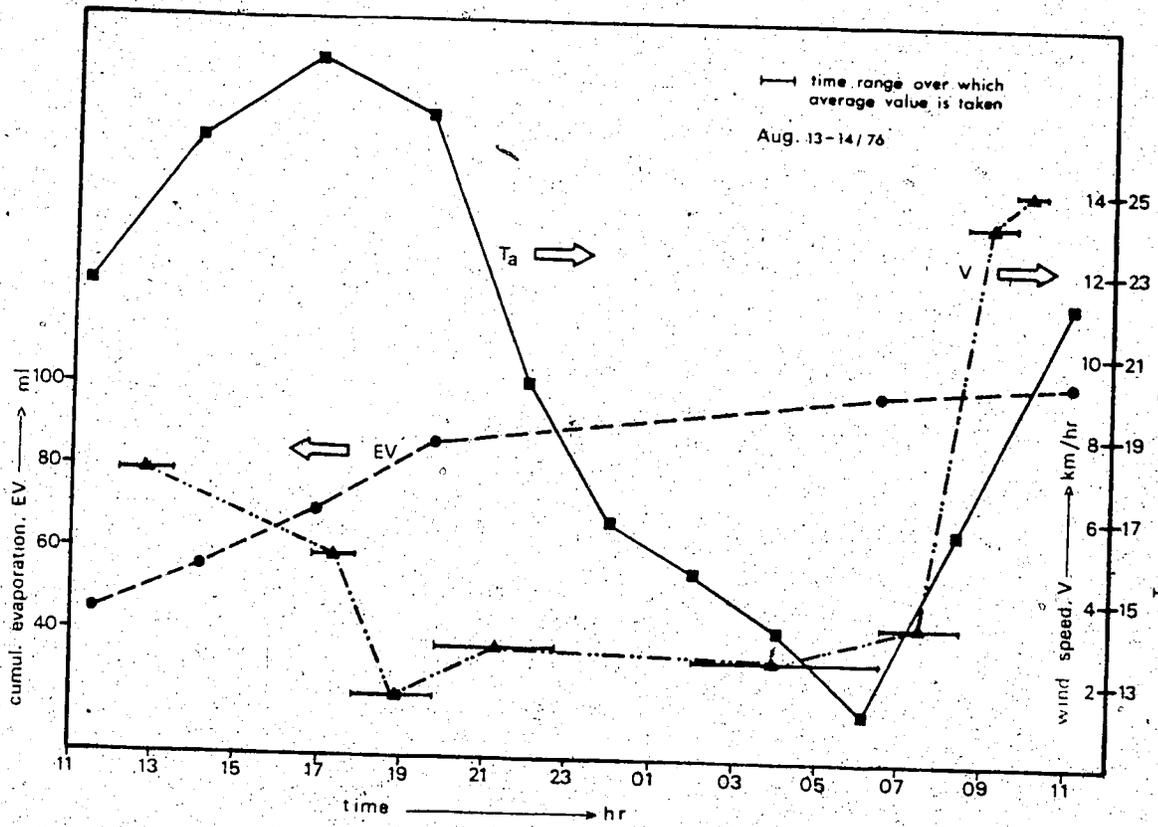


Figure A-3. Potential evaporation fluxes, air temperatures and wind speeds at the Taber sites during August 13-14/76

APPENDIX B

WATER CHARACTERISTIC CURVES- SITE 2

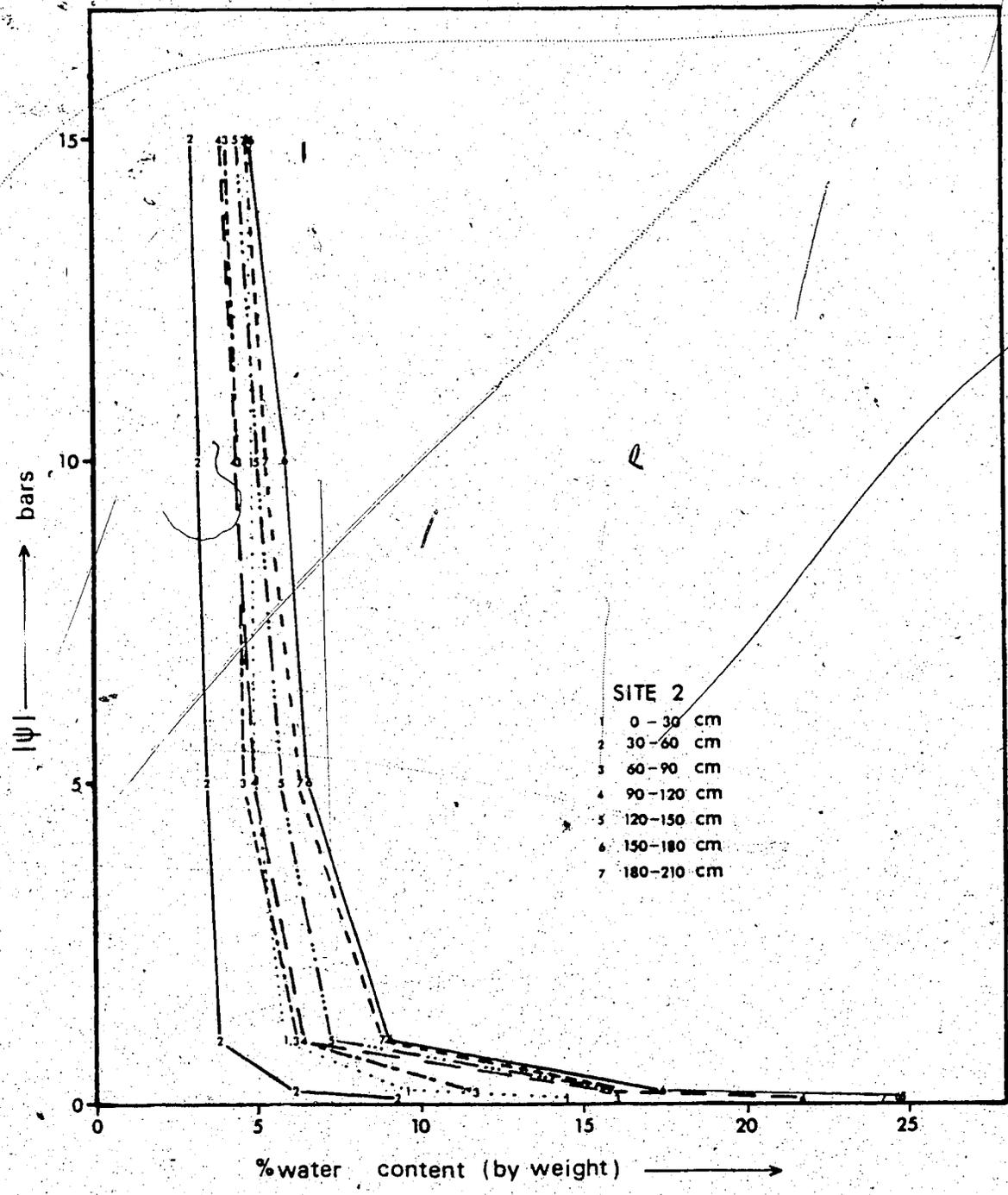


Figure B-1. Laboratory-determined water characteristic curves for Site 2.

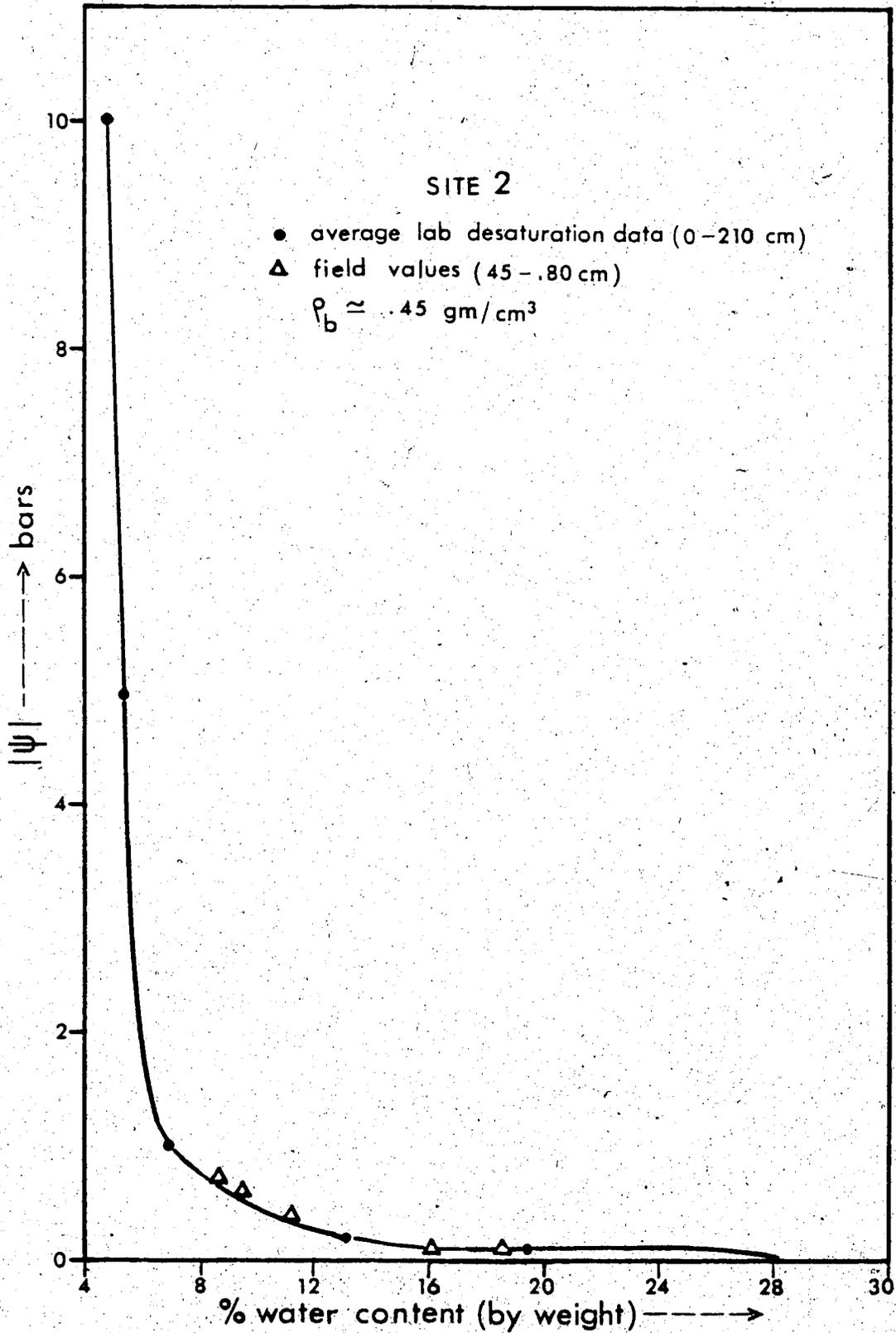


Figure B-2. Comparison of Laboratory and field-determined water characteristic data for Site 2

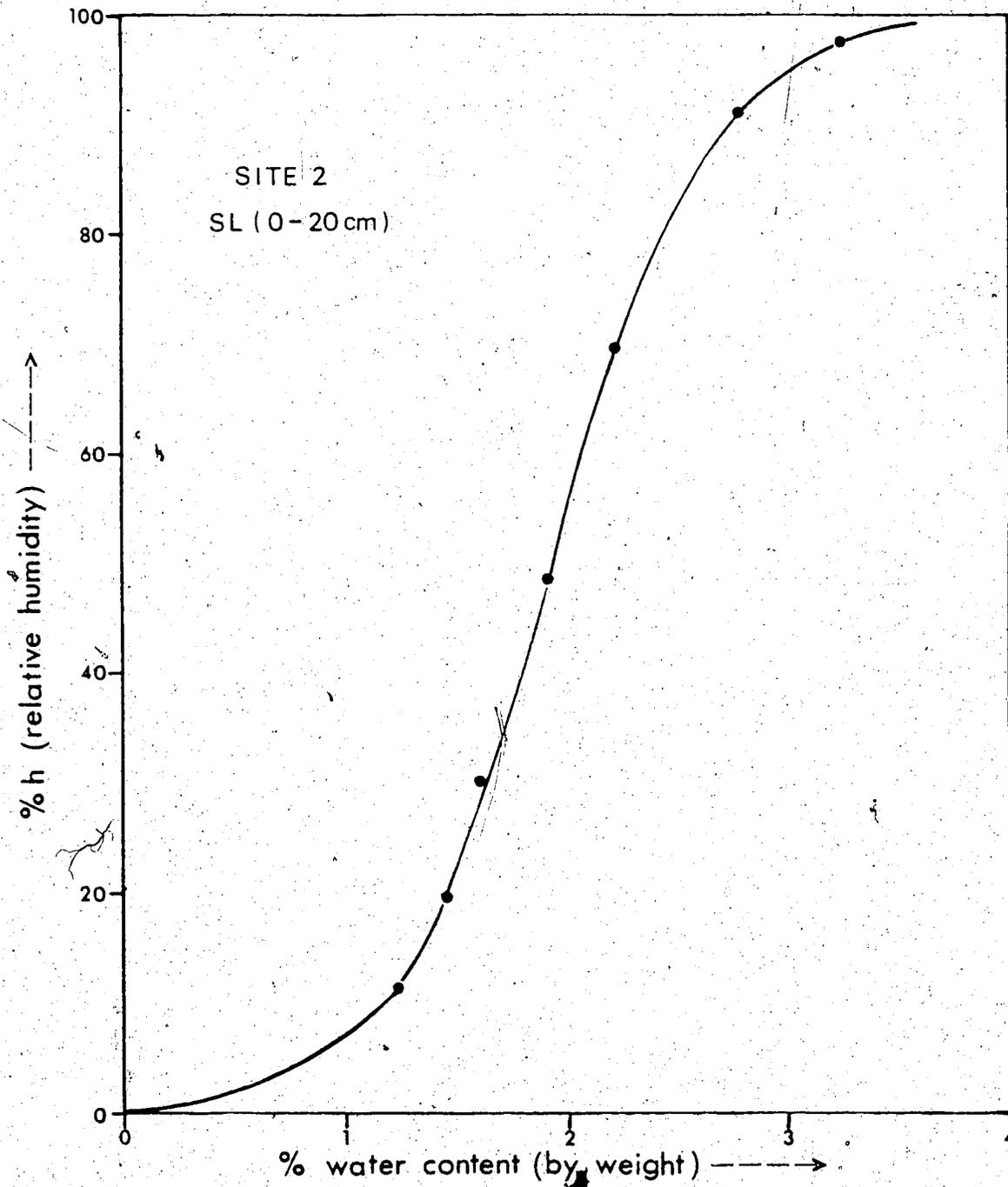


Figure B-3. Vapor equilibration experiments using acid solutions for Site 2 (0-20 cm)

APPENDIX C

HYDRAULIC PROPERTIES OF POROUS MATERIALS FROM THE TABER  
SITES

This Appendix includes the following relationships in graphical form as determined in the laboratory:

- 1)  $\psi$  vs  $\theta$  or  $S_w$
- 2)  $S_e$  vs  $\psi$
- 3)  $K_r$  vs  $\psi$
- 4)  $K$  vs  $\theta$

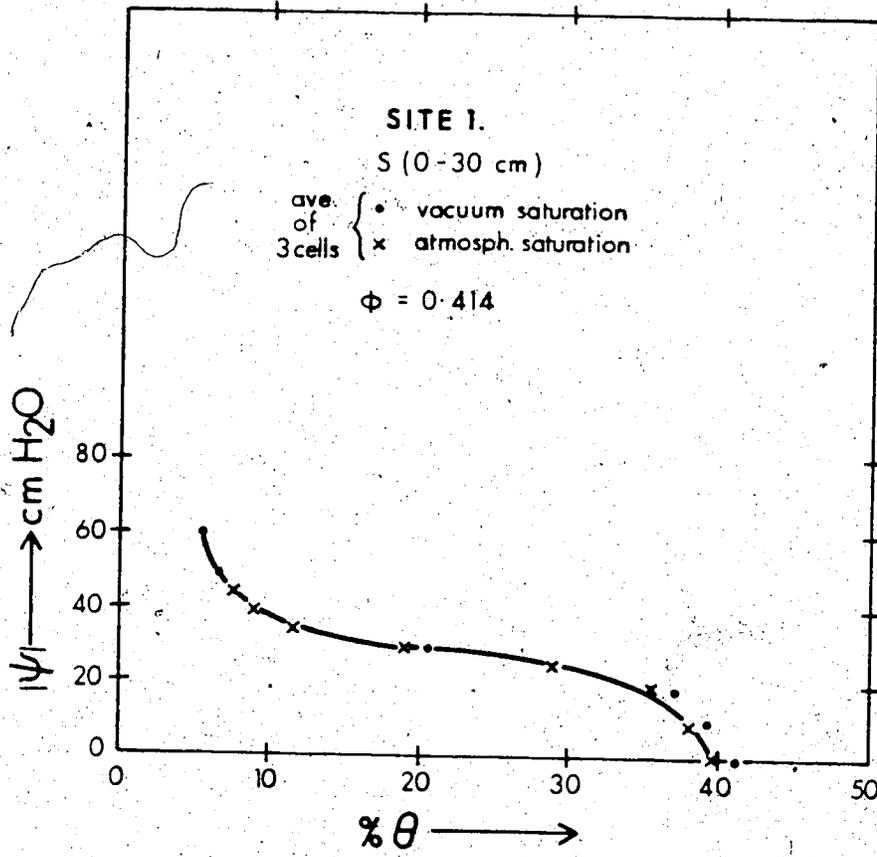


Figure C-1.  $\psi$  ( $\theta$ ) relationship for Site 1 (0-30 cm)

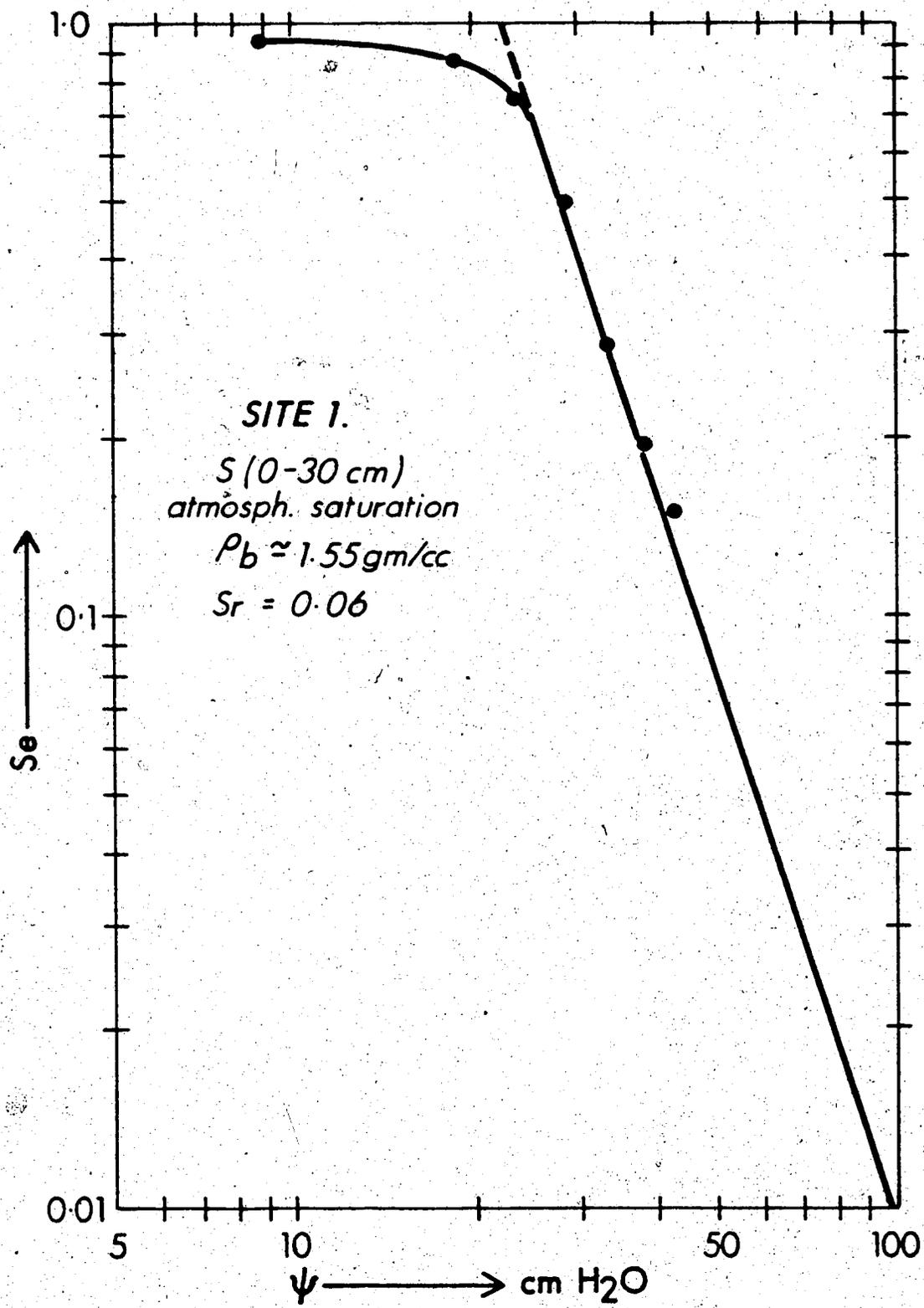


Figure C-2.  $S_e$  ( $\psi$ ) relationship for Site 1 (0-30 cm)

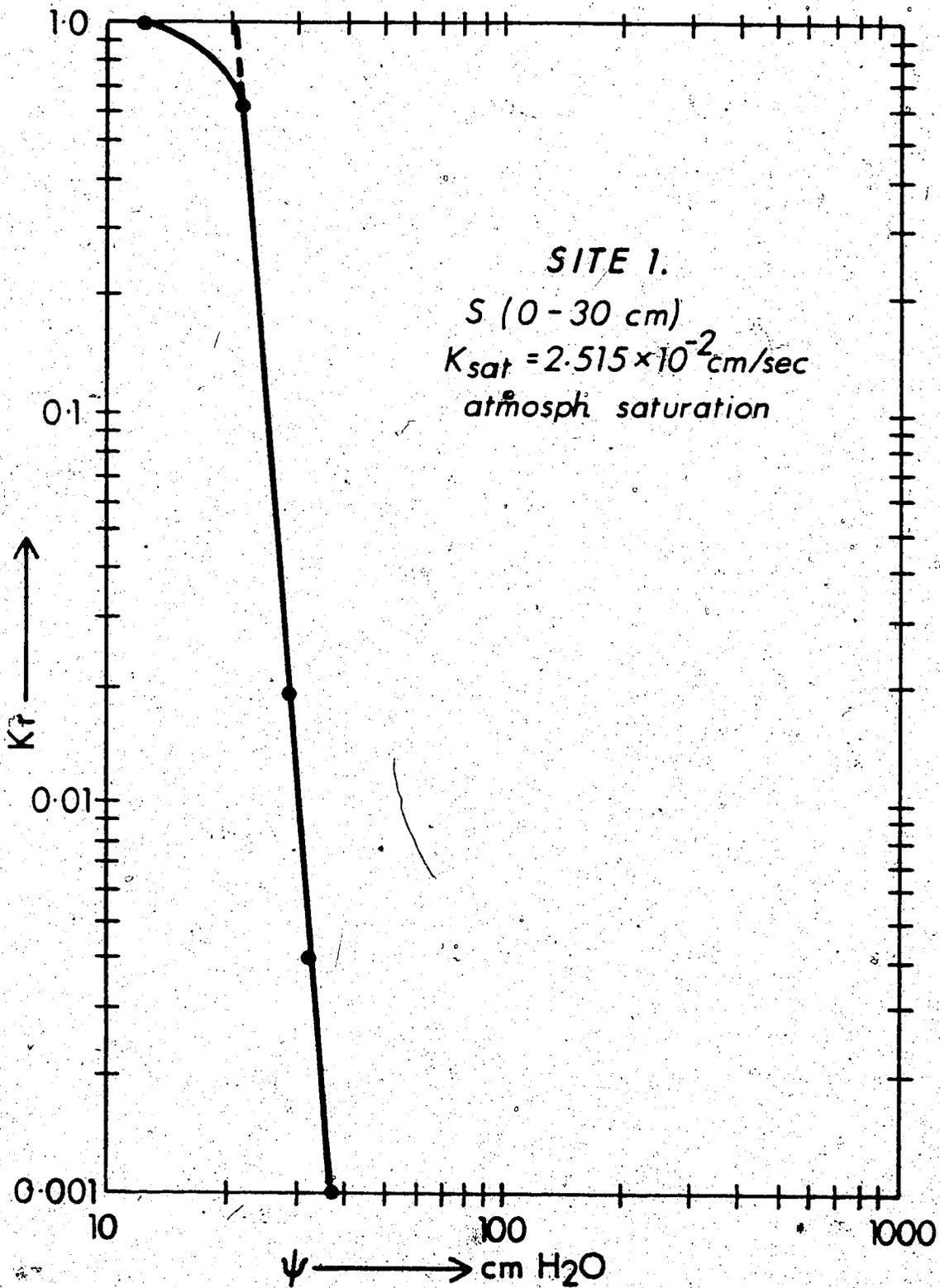


Figure C-3.  $K_r(\psi)$  relationship for Site 1 (0-30 cm)

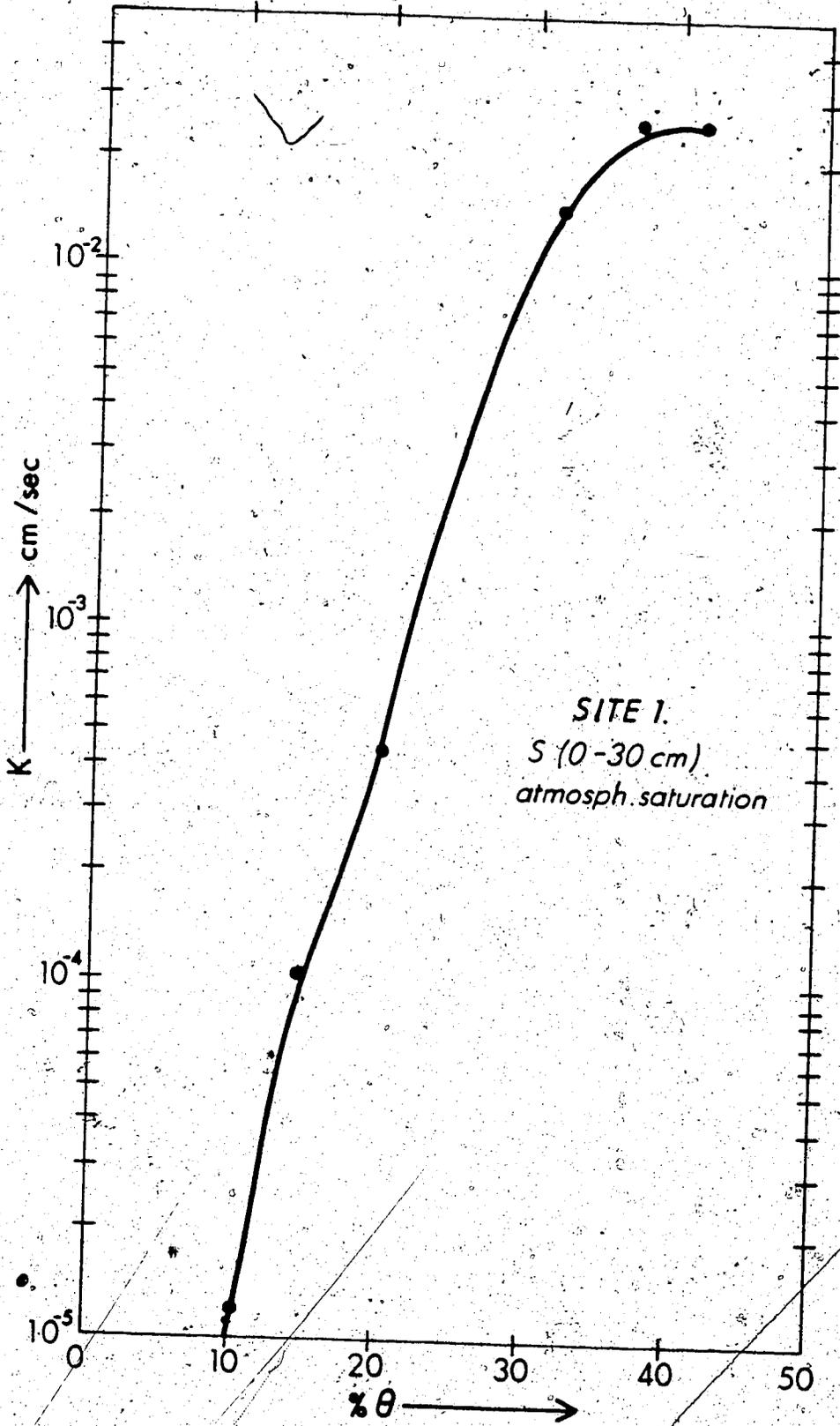


Figure C-4.  $K(\theta)$  relationship for Site 1 (0-30 cm)

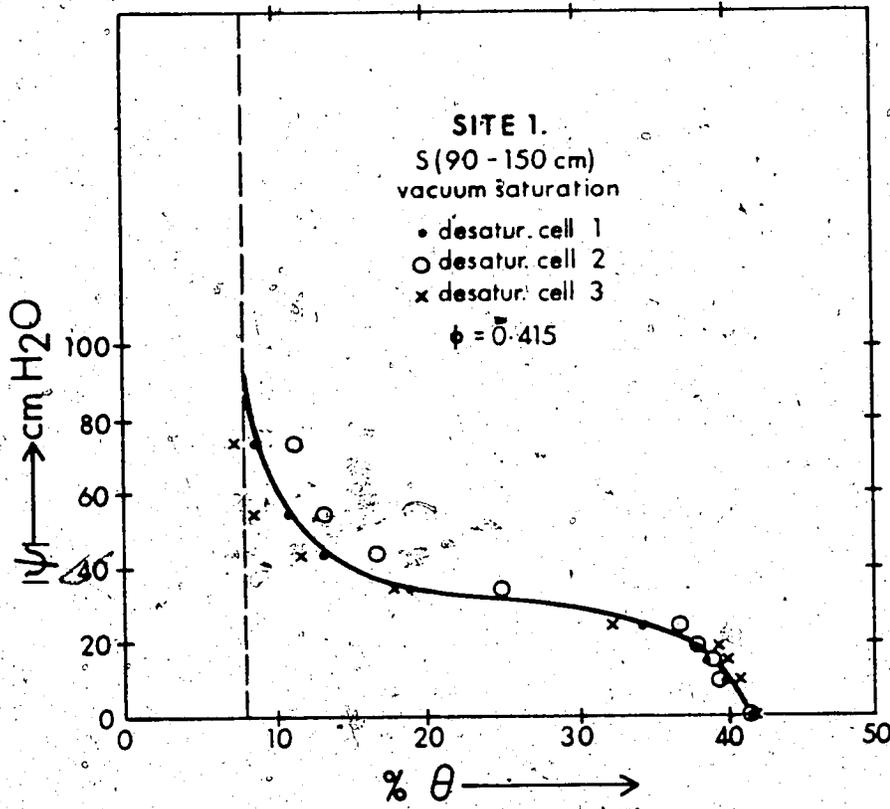


Figure C-5.  $\psi$  ( $\theta$ ) relationship for Site 1 (90-150 cm)

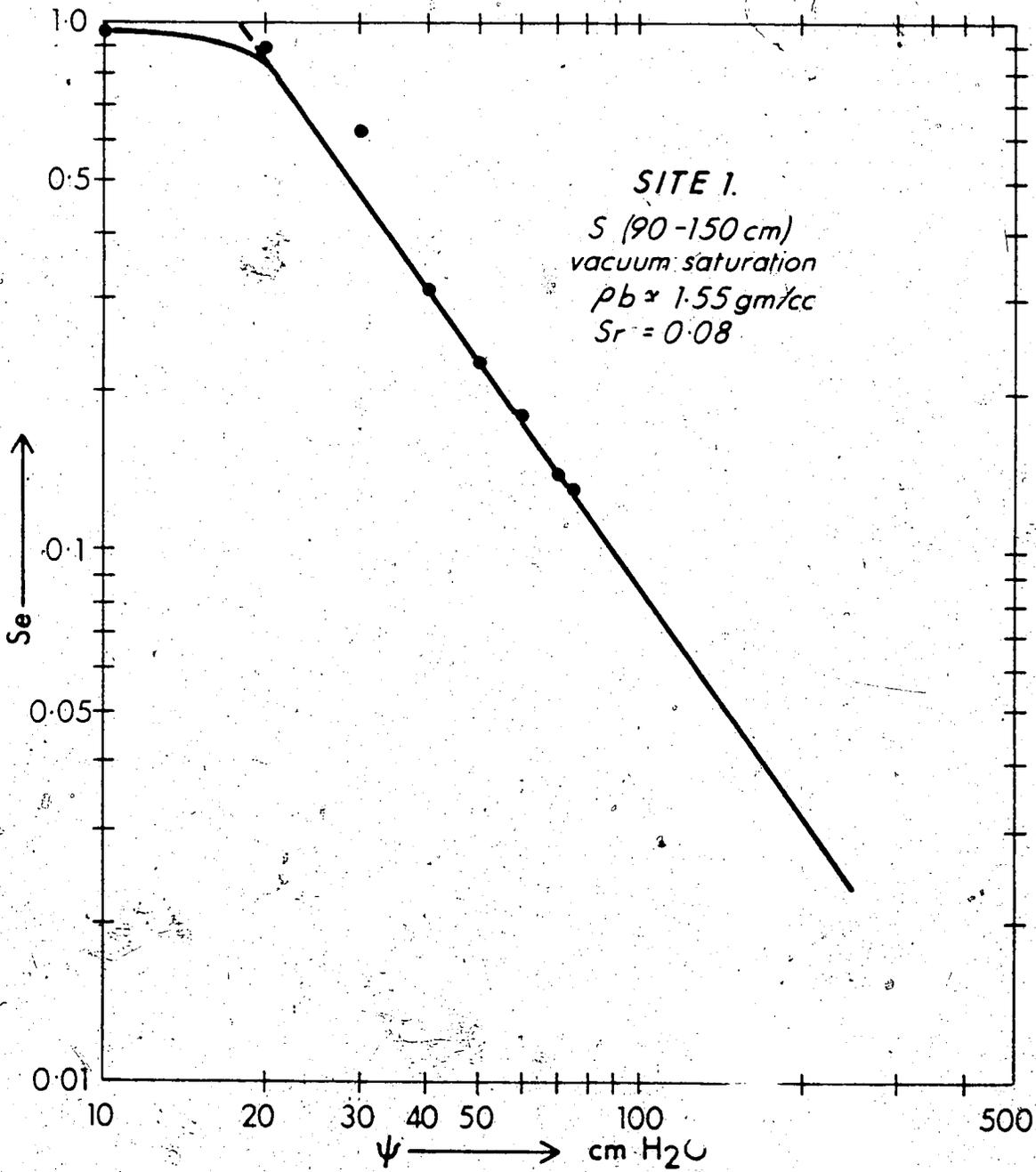


Figure C-6.  $S_e$  ( $\psi$ ) relationship for Site 1 (90-150 cm)

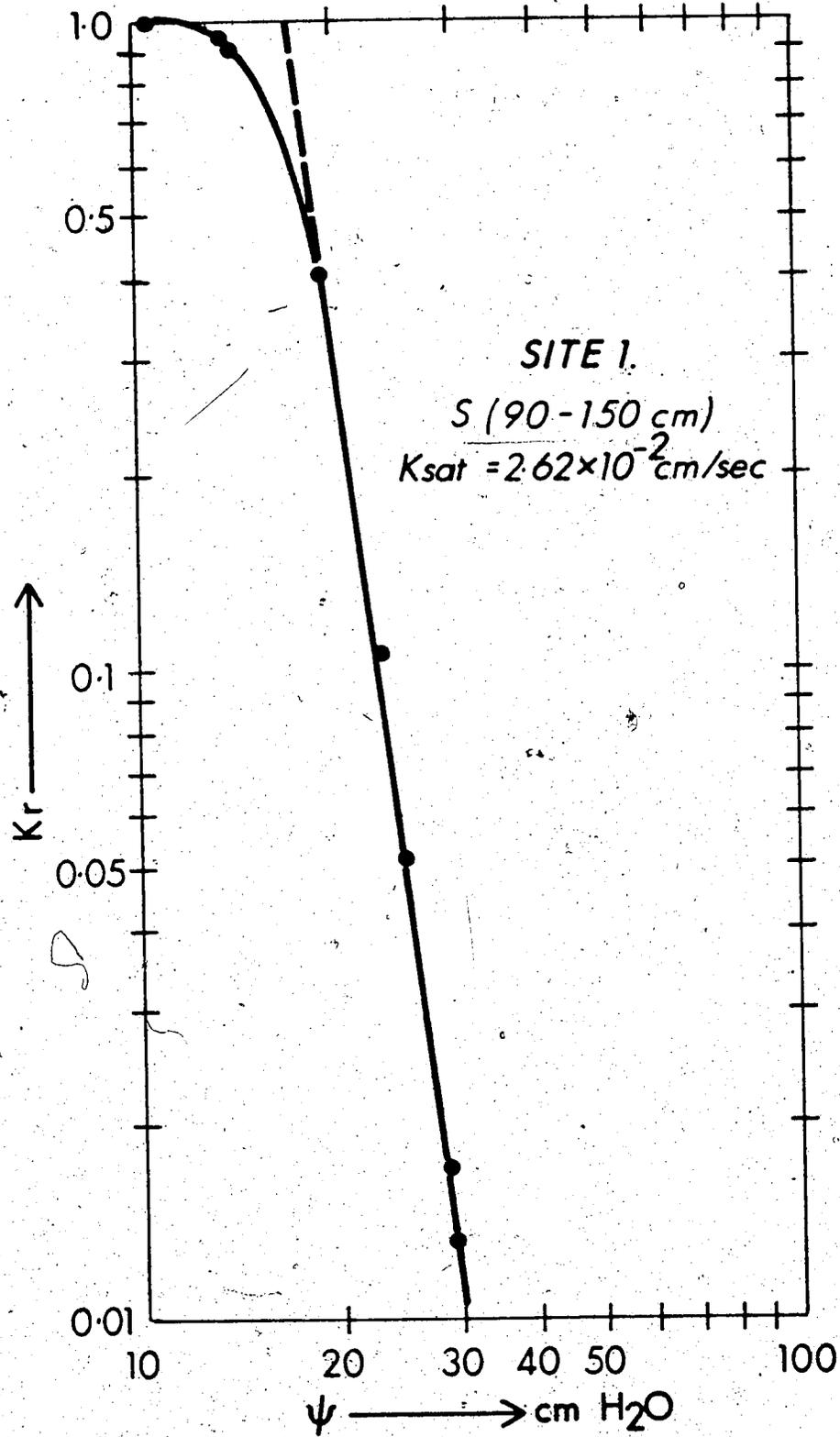


Figure C-7.  $K_r$  ( $\psi$ ) relationship for Site 1 (90- 150 cm)

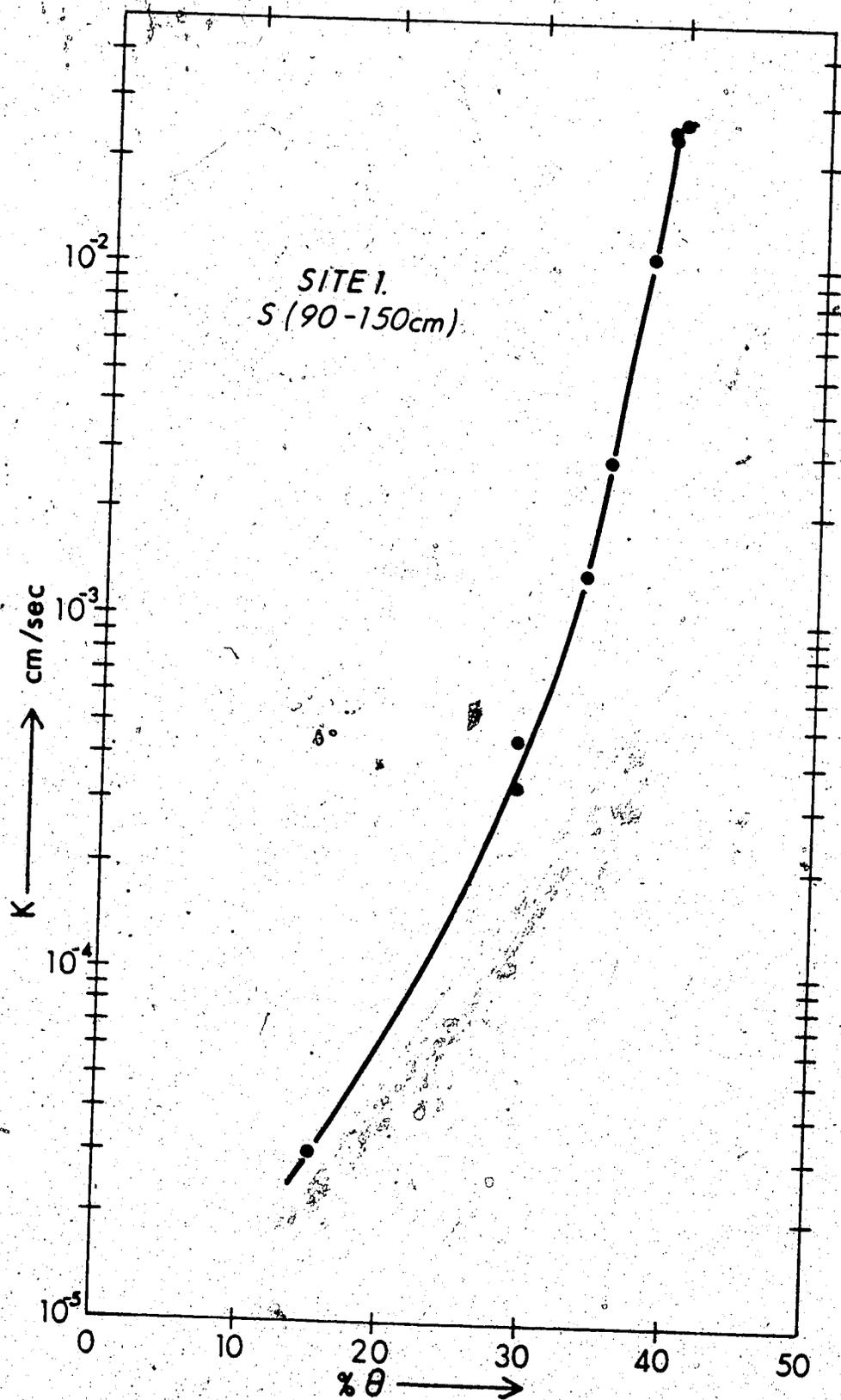


Figure C-8.  $K(\theta)$  relationship for Site 1 ( 90- 150 cm )

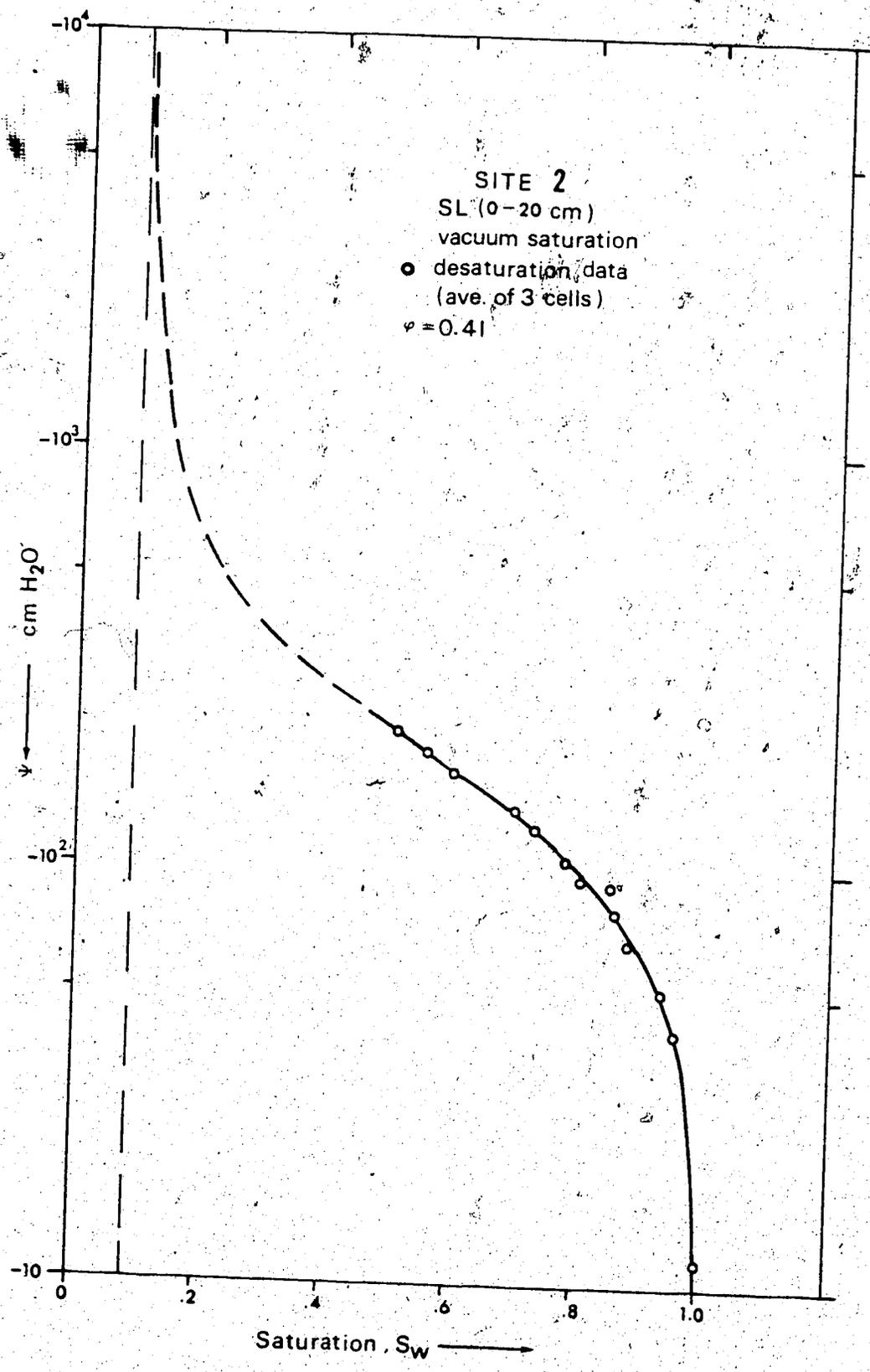


Figure C-9.  $\psi (S_w)$  relationship for Site 2 (0-20 cm)

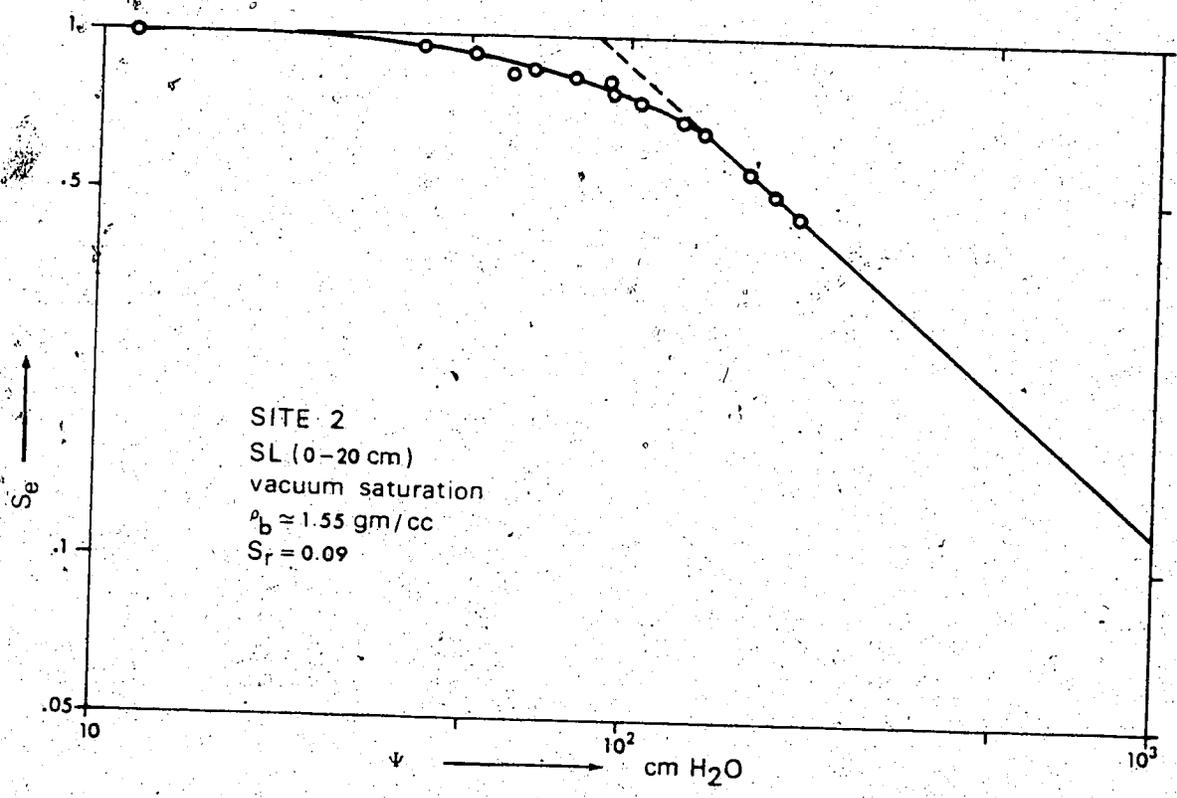


Figure C-10.  $S_e(\psi)$  relationship for Site 2 (0-20 cm)

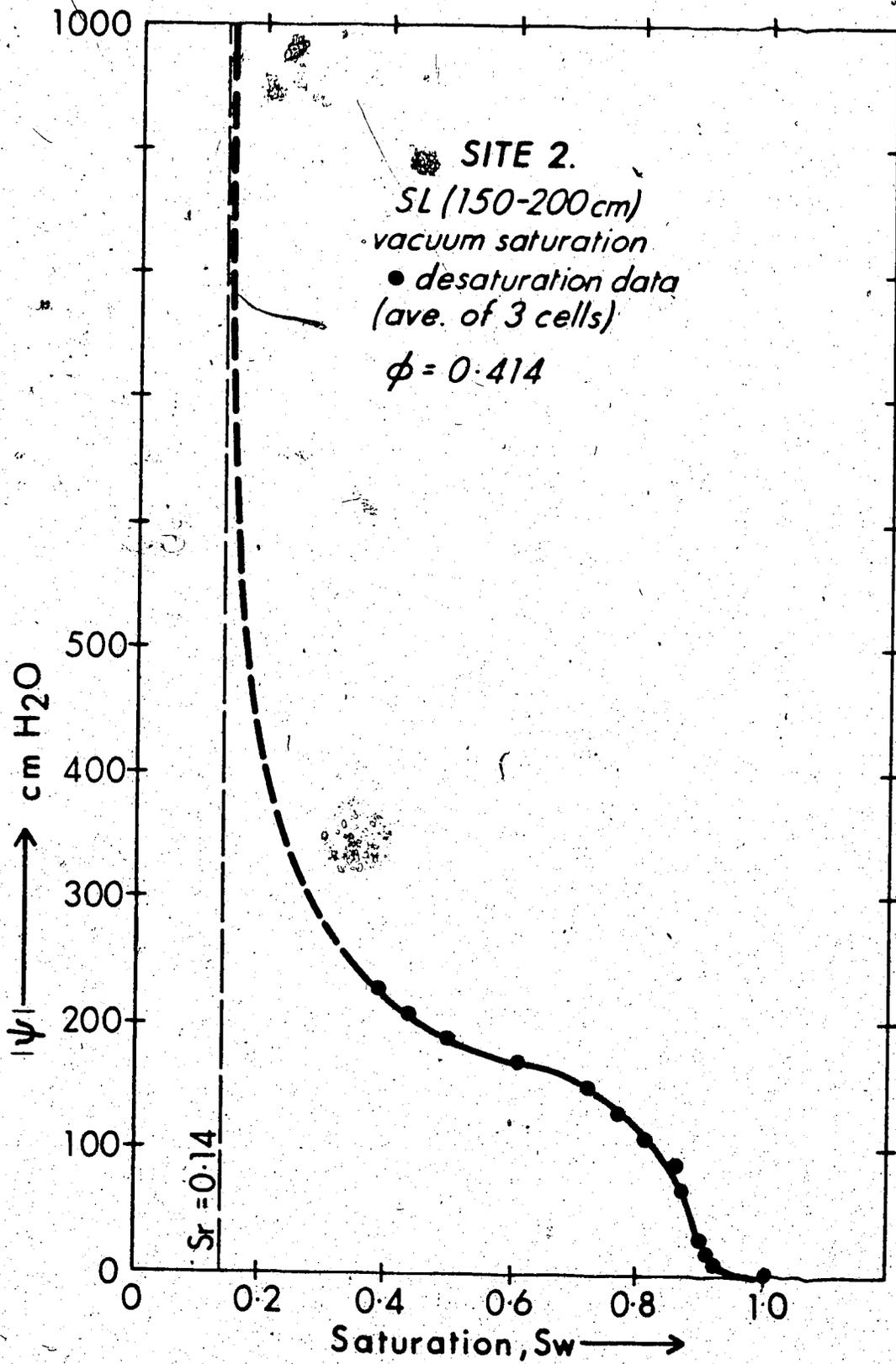


Figure C-11.  $\psi (S_w)$  relationship for Site 2 (150-200 cm)

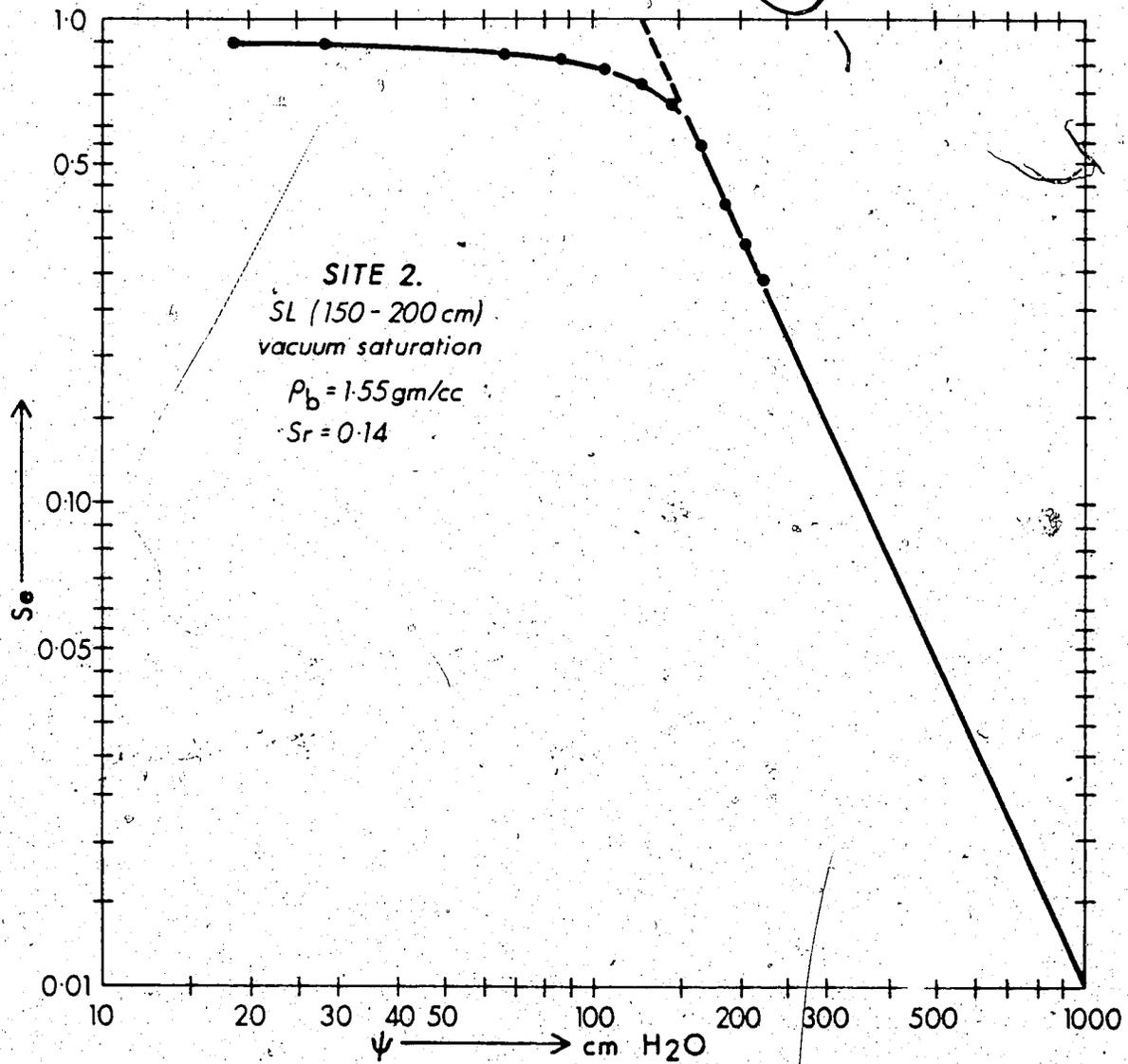


Figure C-12.  $S_e(\psi)$  relationship for Site 2 (150-200 cm)

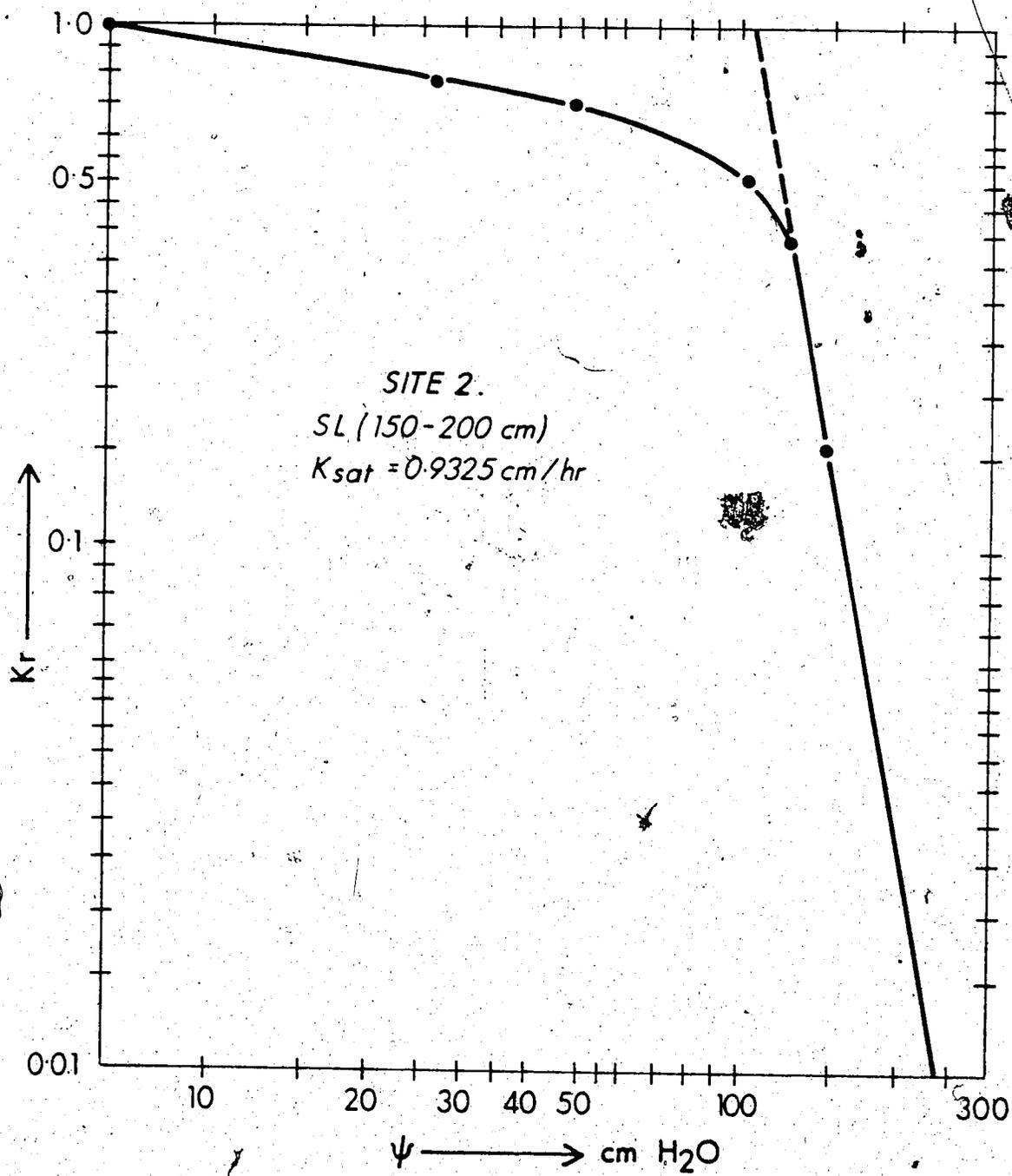


Figure C-13.  $K_r(\psi)$  relationship for Site 2 (150-200 cm)

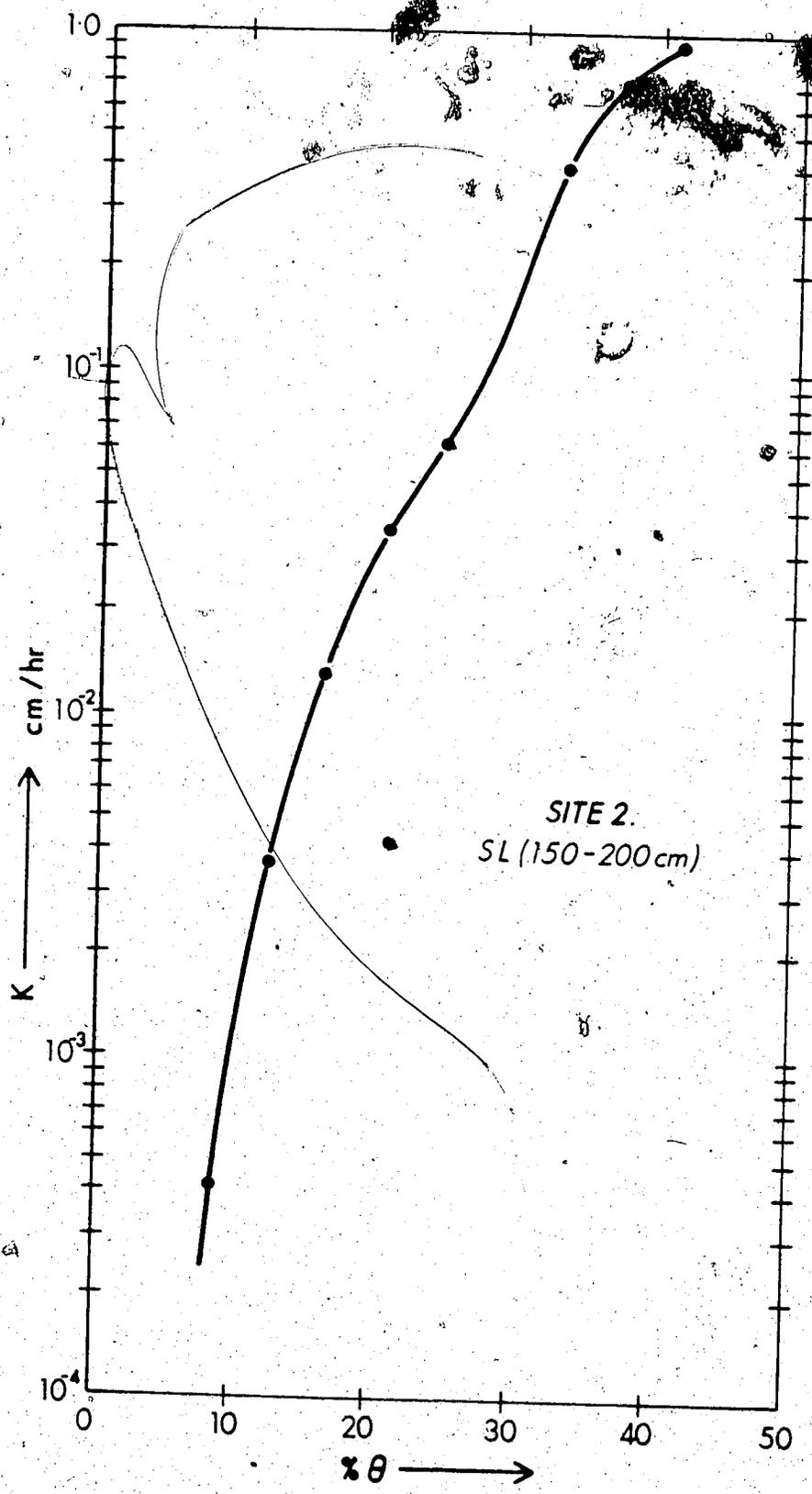


Figure C-14. K (θ) relationship for Site 2 (150-200 cm)

## APPENDIX D

### DERIVATION OF THE FINITE DIFFERENCE EQUATIONS OF THE ONE-DIMENSIONAL COUPLED NON-ISOTHERMAL FLOW USING A CRANK-NICHOLSON APPROXIMATION METHOD

The set of equations to be solved is (4-1) subject to the initial and the boundary conditions (4-2) and (4-3) respectively. The spatial and time domains are discretized using the grid of Fig. 4-2. The following modification of the Crank-Nicholson method of finite differencing (Richtmyer and Morton, 1967) is used to approximate the partial derivatives appearing in the above equations:

$$\begin{aligned} \partial(k \partial n / \partial z) / \partial z \approx & 0.5 [k_{i+1/2}^{j-1/2} (n_{i+1}^j + n_{i+1}^{j-1} - n_i^j - n_i^{j-1}) / (\Delta z)^2] \\ & + 0.5 [k_{i-1/2}^{j-1/2} (n_i^j + n_i^{j-1} - n_{i-1}^j - n_{i-1}^{j-1}) / (\Delta z)^2] \end{aligned} \quad (D-1)$$

$$\partial n / \partial t \approx (n_i^j - n_i^{j-1}) / \Delta t \quad (D-2)$$

$$\partial k / \partial z \approx (k_{i+1/2}^{j-1/2} - k_{i-1/2}^{j-1/2}) / \Delta z \quad (D-3)$$

where the terms  $k_{i+1/2}^{j-1/2}$ ,  $k_{i-1/2}^{j-1/2}$  are arbitrarily given by (4-4r) and (4-4s) respectively.

Using the above approximations to equations (4-1) they become

$$\begin{aligned}
 F_i^{j-1/2} (\psi_i^j - \psi_i^{j-1}) / \Delta t &= (1/\Delta z) [ K_{\psi_{i+1/2}}^{j-1/2} (\psi_{i+1}^j + \psi_{i+1}^{j-1} - \psi_i^j - \psi_i^{j-1}) / (2\Delta z) \\
 - K_{\psi_{i-1/2}}^{j-1/2} (\psi_i^j + \psi_i^{j-1} - \psi_{i-1}^j - \psi_{i-1}^{j-1}) / (2\Delta z) \\
 + D_{T_{i+1/2}}^{j-1/2} (T_{i+1}^j + T_{i+1}^{j-1} - T_i^j - T_i^{j-1}) / (2\Delta z) \\
 - D_{T_{i-1/2}}^{j-1/2} (T_i^j + T_i^{j-1} - T_{i-1}^j - T_{i-1}^{j-1}) / (2\Delta z) - (K_{i+1/2}^{j-1/2} - K_{i-1/2}^{j-1/2}) ] \quad (D-4)
 \end{aligned}$$

$$\begin{aligned}
 C_i^{j-1/2} (T_i^j - T_i^{j-1}) / \Delta t &= (1/\Delta z) [ \lambda_{i+1/2}^{j-1/2} (T_{i+1}^j - T_{i+1}^{j-1} - T_i^j - T_i^{j-1}) / (2\Delta z) \\
 - \lambda_{i-1/2}^{j-1/2} (T_i^j + T_i^{j-1} - T_{i-1}^j - T_{i-1}^{j-1}) / (2\Delta z) \\
 + D_{L_{i+1/2}}^{j-1/2} (\psi_{i+1}^j + \psi_{i+1}^{j-1} - \psi_i^j - \psi_i^{j-1}) / (2\Delta z) \\
 - D_{L_{i-1/2}}^{j-1/2} (\psi_i^j + \psi_i^{j-1} - \psi_{i-1}^j - \psi_{i-1}^{j-1}) / (2\Delta z) \\
 - C_{L_i}^{j-1/2} q_{w_i}^{j-1/2} (T_{i+1/2}^{j-1/2} - T_{i-1/2}^{j-1/2}) ] \quad (D-5)
 \end{aligned}$$

where the terms of the form  $k_i^{j-1/2}$  are given by (4-4t).

Rearranging terms and making use of (4-4f), the above equations become

$$\begin{aligned}
 -K_{\psi_{i-1/2}}^{j-1/2} \psi_{i-1}^j + (2F_i^{j-1/2} / \Gamma + K_{\psi_{i+1/2}}^{j-1/2} + K_{\psi_{i-1/2}}^{j-1/2}) \psi_i^j - K_{\psi_{i+1/2}}^{j-1/2} \psi_{i+1}^j \\
 - D_{T_{i-1/2}}^{j-1/2} T_{i-1}^j + (D_{T_{i+1/2}}^{j-1/2} + D_{T_{i-1/2}}^{j-1/2}) T_i^j - D_{T_{i+1/2}}^{j-1/2} T_{i+1}^j = \\
 K_{\psi_{i+1/2}}^{j-1/2} (\psi_{i+1}^{j-1} - \psi_i^{j-1}) + K_{\psi_{i-1/2}}^{j-1/2} (\psi_{i-1}^{j-1} - \psi_i^{j-1}) + D_{T_{i+1/2}}^{j-1/2} (T_{i+1}^{j-1} - T_i^{j-1}) \\
 + D_{T_{i-1/2}}^{j-1/2} (T_{i-1}^{j-1} - T_i^{j-1}) + 2\Delta z (K_{i+1/2}^{j-1/2} - K_{i-1/2}^{j-1/2}) + (2F_i^{j-1/2} / \Gamma) \psi_i^{j-1} \quad (D-6)
 \end{aligned}$$

$$\begin{aligned}
 -(\lambda_{i-1/2}^{j-1/2} - c_{L_i}^{j-1/2} q_{w_i}^{j-1/2} \Delta z / 2) T_{i-1}^j + (2C_i^{j-1/2} / \Gamma + \lambda_{i+1/2}^{j-1/2} + \lambda_{i-1/2}^{j-1/2}) T_i^j \\
 - (\lambda_{i+1/2}^{j-1/2} - c_{L_{i+1}}^{j-1/2} q_{w_{i+1}}^{j-1/2} \Delta z / 2) T_{i+1}^j - D_{L_{i-1/2}}^{j-1/2} \psi_{i-1}^j \\
 + (D_{L_{i-1/2}}^{j-1/2} + D_{L_{i+1/2}}^{j-1/2}) \psi_i^j + D_{L_{i+1/2}}^{j-1/2} \psi_{i+1}^j = \\
 \lambda_{i+1/2}^{j-1/2} (T_{i+1}^{j-1} - T_i^{j-1}) + \lambda_{i-1/2}^{j-1/2} (T_{i-1}^{j-1} - T_i^{j-1}) \\
 + D_{L_{i+1/2}}^{j-1/2} (\psi_{i+1}^{j-1} - \psi_i^{j-1}) + D_{L_{i-1/2}}^{j-1/2} (\psi_{i-1}^{j-1} - \psi_i^{j-1}) \\
 + c_{L_i}^{j-1/2} q_{w_i}^{j-1/2} (\Delta z / 2) (T_{i-1}^{j-1} - T_{i+1}^{j-1}) + (2C_i^{j-1/2} / \Gamma) T_i^{j-1} \quad (D-7)
 \end{aligned}$$

Using (4-4c) to (4-4g), the above equations become (4-4a) and (4-4b).

### Boundary Conditions

The top boundary condition for the pressure head equation is

$$q_w/\rho = \pm E = -K\psi \partial\psi/\partial z - D_T \partial T/\partial z + K_i \quad (D-8)$$

which, after discretization becomes

$$E_i = -K_{\psi_{i-1/2}}^{j-1/2} (\psi_i^j + \psi_i^{j-1} - \psi_{i-1}^j - \psi_{i-1}^{j-1}) / (2\Delta z) \\ - D_{T_{i-1/2}}^{j-1/2} (T_i^j + T_i^{j-1} - T_{i-1}^j - T_{i-1}^{j-1}) / (2\Delta z) + K_{i-1/2}^{j-1/2} \quad (D-9)$$

where  $i=2$  (top node) and the  $(i-1/2)$  subscripts are approximated by  $i$ . Examination of (D-4) indicates that the underlined terms actually constitute (D-9). Therefore, replacing the terms which are identical to (D-9) by term  $E$  in (D-4) results in

$$F_i^{j-1/2} (\psi_i^j - \psi_i^{j-1}) / \Delta t = (1/\Delta z) [ K_{\psi_{i+1/2}}^{j-1/2} (\psi_{i+1}^j + \psi_{i+1}^{j-1} - \psi_i^j - \psi_i^{j-1}) / (2\Delta z) \\ + D_{T_{i+1/2}}^{j-1/2} (T_{i+1}^j + T_{i+1}^{j-1} - T_i^j - T_i^{j-1}) / (2\Delta z) + E_i - K_{i+1/2}^{j-1/2} ] \quad (D-10)$$

which after some rearrangement becomes

$$(2F_i^{j-1/2} / \Gamma + K_{\psi_{i+1/2}}^{j-1/2}) \psi_i^j - K_{\psi_{i+1/2}}^{j-1/2} \psi_{i+1}^j + D_{T_{i+1/2}}^{j-1/2} T_i^j - D_{T_{i+1/2}}^{j-1/2} T_{i+1}^j = \\ (2F_i^{j-1/2} / \Gamma - K_{\psi_{i+1/2}}^{j-1/2}) \psi_i^{j-1} + K_{\psi_{i+1/2}}^{j-1/2} \psi_{i+1}^{j-1} - D_{T_{i+1/2}}^{j-1/2} T_i^{j-1} + D_{T_{i+1/2}}^{j-1/2} T_{i+1}^{j-1} \\ + 2\Delta z (E_i - K_{i+1/2}^{j-1/2}) \quad (D-11)$$

or, using (4-4c) to (4-4i)

$$(E_2 - A_2) \psi_2^j - C_2 \psi_3^j + (B_2 - A_2) T_2^j - C_2 T_3^j = H(2) \quad (D-12)$$

where  $H(2)$  is the right-hand-side of (D-11).

If (D-9) is solved for the terms underlined, with  $i=3$  (assuming that  $E|_{i=2} = E|_{i=3}$ ) and the result replaced in the heat flow equation (D-5), the following result is obtained:

$$\begin{aligned}
C_i^{j-1/2} (T_i^j - T_i^{j-1}) / \Delta t &= (1/\Delta z) [ \lambda_{i+1/2}^{j-1/2} (T_{i+1}^j + T_{i+1}^{j-1} - T_i^j - T_i^{j-1}) / (2\Delta z) \\
&- \lambda_{i-1/2}^{j-1/2} (T_i^j + T_i^{j-1} - T_{i-1}^j - T_{i-1}^{j-1}) / (2\Delta z) \\
&+ D_{L_{i+1/2}}^{j-1/2} (\psi_{i+1}^j + \psi_{i+1}^{j-1} - \psi_i^j - \psi_i^{j-1}) / (2\Delta z) - D_{L_{i-1/2}}^{j-1/2} K_{i-1/2}^{j-1/2} / K \psi_{i-1/2}^j \\
&+ D_{L_{i-1/2}}^{j-1/2} (D_{T_{i-1/2}}^{j-1/2} / K \psi_{i-1/2}^j) (T_i^j + T_i^{j-1} - T_{i-1}^j - T_{i-1}^{j-1}) / (2\Delta z) \\
&+ D_{L_{i-1/2}}^{j-1/2} E_i / K \psi_{i-1/2}^j ] \quad (D-13)
\end{aligned}$$

where  $(i-1) = 2$  (top node). After some rearrangement, the above equation becomes

$$\begin{aligned}
(2\lambda_{i+1/2}^{j-1/2} / \Gamma + \lambda_{i+1/2}^{j-1/2} + \lambda_{i-1/2}^{j-1/2} - D_{L_{i-1/2}}^{j-1/2} D_{T_{i-1/2}}^{j-1/2} / K \psi_{i-1/2}^j) T_i^j \\
- (\lambda_{i+1/2}^{j-1/2} - c_{L_i}^{j-1/2} q_w^{j-1/2} \Delta z / 2) T_{i+1}^j + D_{L_{i+1/2}}^{j-1/2} \psi_i^j - D_{L_{i+1/2}}^{j-1/2} \psi_{i+1}^j = \\
(2C_i^{j-1/2} / \Gamma) T_i^{j-1} + \lambda_{i+1/2}^{j-1/2} (T_{i+1}^{j-1} - T_i^{j-1}) + \lambda_{i-1/2}^{j-1/2} (T_i^{j-1} - T_{i-1}^{j-1}) \\
+ (D_{L_{i-1/2}}^{j-1/2} D_{T_{i-1/2}}^{j-1/2} / K \psi_{i-1/2}^j) (T_i^{j-1} - T_{i-1}^{j-1}) \\
+ D_{L_{i+1/2}}^{j-1/2} (\psi_{i+1}^{j-1} - \psi_i^{j-1}) + (2\Delta z D_{L_{i+1/2}}^{j-1/2} / K \psi_{i+1/2}^j) (E_i - K_{i-1/2}^{j-1/2}) \\
- c_{L_i}^{j-1/2} q_w^{j-1/2} \Delta z / 2 (T_{i+1}^{j-1} - T_{i-1}^{j-1}) \\
+ (\lambda_{i+1/2}^{j-1/2} - D_{L_{i-1/2}}^{j-1/2} D_{T_{i-1/2}}^{j-1/2} / K \psi_{i-1/2}^j + c_{L_i}^{j-1/2} q_w^{j-1/2} \Delta z / 2) T_{i-1}^{j-1} \quad (D-14)
\end{aligned}$$

where  $T_{i-1}^j = T_2^j$  is the specified surface temperature, or using (4-4c) to (4-4p).

$$[B_3^j - (\bar{A}_3^j \bar{A}_3^j) T_3^j - C_3^j T_2^j + (\bar{B}_3^j - \bar{A}_3^j) \psi_3^j - \bar{C}_3^j \psi_4^j = H^j \quad (3) \quad (D-15)$$

where  $H^j(3)$  is the right-hand-side of (D-14).

With regard to the bottom boundary conditions, the water flux equation (2-38) -- after discretization using forward differences -- becomes

$$-K_L (\psi_{L+1} - \psi_L) / \Delta z - D_{T_L} (T_{L+1} - T_L) / \Delta z + K_L = w \quad (D-16)$$

where  $w$  is the specified bottom boundary water flux. Solving (D-16) for  $\psi_{L+1}$  results in

$$\psi_{L+1} = \psi_L - \Delta z (1 - w / K_L) - (D_{T_L} / K_L) (T_{L+1} - T_L) \quad (D-17)$$

while from the bottom boundary condition (D-18) for the heat flow equation

$$(\partial T / \partial z) |_{z=L} = (T_{L+\Delta z} - T_L) / \Delta z = 0$$

(D-18)

one obtains

$$T_{L+\Delta z} = T_L$$

(D-19)

## APPENDIX E

### DOCUMENTED COMPUTER PROGRAMS

#### E1 Introduction

The present computer program simulates the one-dimensional simultaneous flow of water and heat in the subsurface (4-1). It consists of a main program and 21 subroutines or function routines. Most transport parameters and coefficients are written in separate subroutines in order to facilitate changes by simply inserting the appropriate program segment. The program was initially run in WATFIV for debugging purposes and subsequently in FORTRAN G for shorter execution time. Double precision arithmetic was used throughout for the various calculations involved in the model. The amount of computer storage required was dependent on the size of the finite difference scheme to be solved. The present program is set up for 50 nodes. In order to alter the size of the system, the dimension statements must be changed.

The main program is the control program which directs the sequence of operations for solving the system of coupled partial differential equations (4-1). It calls all appropriate subroutines; it controls the input and output

data, and boundary and initial conditions; it checks the time increments, the number of iterations and convergence constraints.

E2 Subroutines

Subroutine DTCOEF calculates the thermal diffusion coefficients  $D_{TL}$  and  $D_T$ ; the non-isothermal water flux  $q_w/\rho$ ; the heat flux due to the movement of water  $q_{cv}$  and the total heat flux  $q_h$ .

Subroutine DPSICF calculates the total water conductivity  $K_\psi$ .

Subroutine HYCOND adjusts the measured saturated hydraulic conductivity for temperature using (4-15). It also provides for the calculation of the unsaturated hydraulic conductivity function from the non-isothermal water flux equation (4-1d).

Subroutine EVAPO calculates the evaporation rate from a water conservation equation; that is, from the time change of the water content of the top finite difference mesh element and the known water flux at the bottom of that element. This water flux is estimated from the non-isothermal flux equation (4-1d) employing the specified hydraulic conductivity function ( $K$  vs  $\theta$ ) for the top element.

Subroutine HCAPT calculates the volumetric heat

capacity of the subsurface layers as functions of their mineral matter, organic matter and water fractions (3-15).

Subroutine HFLUX calculates the water vapor conductivity  $K_{\psi v}$ ; the conductive  $q_{cd}$  and latent  $q_{lh}$  heat fluxes; the vapor thermal diffusion coefficient  $D_{Tv}$  and the vapor flux  $q_v/\rho$ .

Subroutine FCOEF calculates the specific water capacity (2-47).

Subroutine DLCOEF calculates the coupling coefficient for heat transfer  $D_L$  (4-1c).

Subroutine TRIDAG (Carnahan et al., 1969) solves a system of linear simultaneous equations with a tridiagonal matrix; such a system results from the implicit finite difference scheme used here. The equations are numbered from IF through L and their subdiagonal, diagonal and superdiagonal coefficients are stored in the arrays AZ, BZ and CZ. The computed solution vector is stored in the array VZ.

Subroutines SPLINE and CALCCF and function PCUBIC form the piecewise-cubic interpolation program (Conte and de Boor, 1972). This cubic spline program is called extensively to interpolate input data for a number of parameters required in the program. Subroutine SPLINE uses Gauss elimination adapted to take advantage of the tridiagonal character of the resulting coefficient matrix (Conte and de

Boor, 1972) to calculate the spline coefficients  $C(2,i)$ ,  $i = 2, \dots, N$ , given the numbers  $C(1,i) = f(x_i)$ ,  $i = 1, \dots, N+1$ ,  $C(2,1) = f'(x_1)$  and  $C(2, N+1) = f'(x_{N+1})$ , where  $f(x_i)$  comprises the input data corresponding to  $x_i$  and  $C(2,1)$  and  $C(2, N+1)$  are reasonable approximations to the end slopes of  $f(x_i)$ . Subroutine CALCCF calculates the spline coefficients  $C(3,i)$  and  $C(4,i)$ , where  $i = 1, \dots, N$ . Function PCUBIC evaluates the cubic spline equation (E-1)

$$f(x_i) - C(1,i) + C(2,i)(x-x_i) + C(3,i)(x-x_i)^2 + C(4,i)(x-x_i)^3 \quad (E-1)$$

for any particular point once the spline coefficients  $C(j,i)$ ,  $j=1, \dots, 4$ ,  $i=1, \dots, N$  are known.

Subroutine KSPLN interpolates the specified hydraulic conductivity function ( $K$  vs  $\theta$ ) data using cubic splines and adjusts the conductivity values for temperature.

Subroutines DENS, VISCO, VAPSPL, CLQCF and DAWCF calculate water density  $\rho$ , viscosity  $\mu$ , latent heat of vaporization of water  $L'$ , saturated vapor pressure  $p_v^s$ , specific heat of liquid water  $c_l$ , and molecular diffusion coefficient of water vapor in air  $D_a$ , respectively, as functions of temperature. All the above subroutines call the cubic spline interpolation program to interpolate the input data.

Subroutines THESP2 and THCOND calculate the volumetric water content and thermal conductivity as functions of the negative pressure head and water content, respectively. Both subroutines interpolate the input data using the cubic

spline interpolation program mentioned above.

E3 List of Variables<sup>1</sup>

CC, CCO	volumetric heat capacity of porous material (C) at current and previous time steps
CLQ, CLQO	specific heat of liquid water ( $c_l$ ) at current and previous time steps
CSAT <sub>i</sub> , i=1, ..., 4	saturated hydraulic conductivity ( $K_{sat}$ ) of layer i
DAW	molecular diffusion coefficient of water vapor in air ( $D_a$ )
DELT	time increment ( $\Delta t$ )
DELZ	depth increment ( $\Delta z$ )
DPSI, DPSIO	total water conductivity ( $K_\psi$ ) of current and previous time steps
DPSIV, DPSIVO	vapor conductivity ( $K_{\psi_v}$ ) of current and previous time steps
DT, DTO	thermal water diffusivity ( $D_T$ ) of current and previous time steps
DTHETA	water diffusivity ( $D_g$ )
DTHV	vapor diffusivity ( $D_v$ )
DTL	liquid thermal diffusivity ( $D_{Tl}$ )
DTV, DTVO	thermal vapor diffusivity ( $D_{Tv}$ ) of current, and previous time steps
EPS	a small positive number ( $\epsilon$ )
FF, FO	specific water capacity ( $\partial\theta/\partial\psi$ ) or

<sup>1</sup>Units: [length] = cm; [time] = hr; [mass] = gm;  
[temperature] = C; [heat] = cal.

GR specific storage ( $S_s$ )  
 HVAP acceleration of gravity (g)  
 latent heat of vaporization of water  
 ( $L'$ )  
 J time step index  
 K, KO hydraulic conductivity (K) of  
 current and previous time steps  
 KMAX maximum number of iterations per  
 time step  
 KODE1 specifies the top boundary condition  
 of evaporation or infiltration  
 KODE2 specifies after how many time steps  
 the output is to be printed  
 KODE4 specifies if the coupled or  
 uncoupled equations are to be used  
 KODE5 specifies the bottom boundary  
 condition of recharge or discharge  
 KOUNT count index  
 KSAT saturated hydraulic conductivity  
 ( $K_{sat}$ )  
 L total number of space nodes  
 LAMDA, LAMDAO apparent thermal conductivity ( $\lambda$ ) of  
 current and previous time steps  
 MI dynamic viscosity of water ( $\mu$ )  
 MITREF dynamic viscosity of water at  
 reference temperature ( $\mu(T_0)$ )  
 MO node below which the mineral and

organic matter fractions remain constant

MW molecular weight of water vapor (M)

Ni number of specified input data of various parameters

N1 number of  $\rho(T)$  input data

N2 " "  $\mu(T)$  " "

N3 " "  $L'(T)$  " "

N5 " "  $K(\theta)$  " "

N7 " "  $p_v^s(T)$  " "

N8 " "  $c_p(T)$  " "

N9 " "  $D_a(T)$  " "

N11 " "  $\lambda(\theta)$  " "

N66 " "  $\psi(\theta)$  " "

NJ number of time increments

NR, NI, NII depths at which the saturated hydraulic conductivity changes

NSTOP upper limit on the number of time increments

Pi, i=1,2,3,5,7,8,9,11,66 end slope of input data  $f(x_i)$

Pi(1,I), I=1, Ni input data corresponding to Ni (see Ni)

PSIO, PSI, PSII pressure head ( $\psi$ ) of previous, current and next time steps

PSI66 input pressure head data in the water characteristic function

QH	total heat flux ( $q_h$ )
QCD	conductive heat flux ( $q_{cd}$ )
QCV	convective heat flux ( $q_{cv}$ )
QS	latent heat flux ( $q_{lh}$ )
QW, QWO	water flux ( $q_w/\rho$ ) of current and previous time steps
QVAP	vapor flux ( $q_v/\rho$ )
R	universal gas constant (R)
RO	liquid water density ( $\rho$ )
ROIREF	liquid water density at the reference temperature $\{\rho(T_0)\}$
SL	total length of subsurface profile studied (L)
SRH	soil relative humidity (h)
SS	specific storage ( $S_s$ )
SVP	saturated vapor pressure ( $p_v^s$ )
TO, T, TI	porous medium temperature (T) of previous current and next time steps
Ti (I), I=1, Ni	input temperature data corresponding to Ni (see Ni)
THETA0, THETA, THETA1	moisture content ( $\theta$ ) of previous, current and next time steps
THETA5	input moisture content data in the $K(\theta)$ relationship
THET11	input moisture content data in the $\lambda(\theta)$ relationship
TINCR	incremental time step

TREF reference temperature ( $T_0$ )  
TS ground surface temperature  
W specified water flux at bottom  
boundary  
XM volumetric mineral matter fraction  
( $x_{mm}$ )  
XMAXST maximum simulation time  
XO volumetric organic matter fraction  
( $x_o$ )  
Z incremental depth (z).

## E4 Program Listing

```

1      IMPLICIT REAL*8(A-H,O-Z)
2      COMMON/DSWHE/ PSI(50),THETA(50),T(50),QW(50),QH(50),DELTAT(50),
3      LAMDA(50),CLQ(50),SVP(50),RO(50),MI(50),P2(4,50),T2(50),
4      T1(50),P1(4,50),T3(50),P3(4,50),THET11(50),P11(4,50),HVAR(50),
5      3THETA5(50),P5(4,50),T9(50),P9(4,50),PF(50),
6      4PSI66(50),P66(4,50),T7(50),P7(4,50),T8(50),
7      5PH(4,50),SRH(50),K(50),QWO(50),DAW(50),DT(50),
8      6THETA0(50),NJ,L,L1,KL,M,DELZ
9
10     C
11     COMMON/MN/ M1,M2,M3,M5,M7,M8,M9,M11,M66
12     DIMENSION PSIO(50),TO(50),LAMBDA0(50),APR(50),DTL(50),
13     ICPR(50),BPR(50),CC(50),CCO(50),DL(50),DLO(50),QVAP(50),
14     2CBARPR(50),BBARPR(50),DIO(50),ABAR(50),CBAR(50),
15     3A(50),C(50),B(50),DPSI(50),DPSIO(50),KPLUS(50),DTHETA(50),
16     4KO(50),KSAT(50),DTV(50),DTVO(50),DTHV(50),DPSIV(50),
17     5D(50,3),E(50,3),F(50,3),G(50,3),CTT(50),PTT(50),
18     6H(50),HPR(50),U(50),V(50),TS(600),QS(50),II(50),
19     7DELTRP(50),KMINUS(50),TI(50),PSII(50),THETA1(50),
20     8XM(50),XO(50),ABARPR(50),BBAR(50),QCD(50),P(4,50),
21     9DPSIVO(50),PO(50),CQ(50),QW(50),CLQ0(50),
22     >DI(50),DII(50),DIII(50),GI(50),GII(50),GIII(50)
23
24     C
25     REAL*8 K,MV,LAMDA,KSAT,MI,MITREP,HVAR,KMINUS,KPLUS,LAMBDA0,KO
26     C---READ IN AND PRINT PHYSICAL PARAMETERS FOR THE SYSTEM
27     READ(5,501) B,MV,SS,SL,GR,TREP,ROTREP,MITREP
28     WRITE(6,200) B,MV,SS,SL,GR,TREP,ROTREP,MITREP
29     200 FORMAT(1H1,'LIST OF PHYSICAL PARAMETERS FOR THE SYSTEM',//
30     1'1HO,'GAS CONSTANT (ERG/DEG.C-MOL)
31     2',F10.1,/1HO,'MOLECULAR WT. OF WATER (GM/MOL) ',F10.1,/
32     3'1HO,'SPECIFIC STORAGE(CN**=1) ',5X,E15.7,/
33     4'1HO,'SECTION LENGTH ( CM ) ',14X,F10.1,/
34     5'1HO,'ACCELERATION OF GRAVITY(CN/SEC**2) ',F10.3,/
35     6'1HO,'REFERENCE TEMP. (DEG.C) ',12X,F10.3,/
36     7'1HO,'WATER DENSITY AT REF.TEMP. (GM/CC) ',F11.5,/
37     8'1HO,'WATER VISCOSITY AT REF.TEMP. (GM/CN-HR) ',F6.3/////
38     501 FORMAT(2F10.1,D10.5,F10.1,2F10.3,/2F10.5)
39     C---READ IN AND PRINT NUMERICAL INFORMATION
40     READ(5,502) NSTOP,L,NJ,XMAXST,EPS,KMAX,DELZ
41     502 FORMAT(3I6,F8.2,F7.5,I4,F10.3)
42     XNJ=NJ
43     L1=L-1
44     DELT=XMAXST/XNJ
45     RATIO=DELT/DELZ
46     RATIOR=RATIO/DELZ
47     WRITE(6,230) XMAXST,DELT,NJ,L,DELZ,EPS,KMAX
48     230 FORMAT(1H1,'NUMERICAL INFORMATION',//1HO,'MAXIMUM SIMULATION TIME
49     1(HR) ',1X,G15.7,/1HO,'SIZE OF TIME INCREMENT(HR) ',3X,G15.7,/1HO,
50     2'NUMBER OF TIME INCREMENTS',I15,/1HO,
51     3'NUMBER OF SPACE NODES',I19,/1HO,
52     4'SIZE OF SPACE INCREMENTS( CM ) ',F10.3,/1HO,'EPSILON',23X,F10.4,
53     5/1HO,'MAXIMUM NUMBER OF ITERATIONS',2X,I10/////
54     C---READ IN AND PRINT BOUNDARY CONDITIONS
55     TINCR=0.000
56     DO 81 I=1,NJ
57     TS(I)=24.400+7.700*DSIN(6.28300*TINCR/24.000+0.392700)
58     81 TINCR=TINCR+DELT
59     IF(NJ.LE.1000) GO TO 93
60     C--- PICEWISE LINEAR SURFACE TEMPERATURE DISTRIBUTION
61     TS(1)=32.500
62     DO 82 I=2,7

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61      82 TS(I)=TS(I-1)+0.13666D0
62      DO 83 I=8,14
63      83 TS(I)=TS(I-1)+0.05571D0
64      DO 84 I=15,21
65      84 TS(I)=TS(I-1)-0.53D0
66      DO 85 I=22,28
67      85 TS(I)=TS(I-1)-0.59286D0
68      DO 86 I=29,35
69      86 TS(I)=TS(I-1)-0.49571D0
70      DO 88 I=36,42
71      88 TS(I)=TS(I-1)-0.13143D0
72      DO 89 I=43,56
73      89 TS(I)=TS(I-1)-0.19692D0
74      DO 90 I=57,63
75      90 TS(I)=TS(I-1)-0.13333D0
76      DO 91 I=64,70
77      91 TS(I)=TS(I-1)+0.22833D0
78      DO 92 I=71,77
79      92 TS(I)=TS(I-1)+0.755D0
80      93 READ(5,121) KODE1,KODE2,KODE3,KODE5
81      121 FORMAT(4I3)
82      C---BOTTOM BOUNDARY WATER FLUX
83      IF(KODE1) 5,5,10
84      5 QW(L)=0.0D0
85      GO TO 122
86      10 QW(L)=0.07D0
87      122 IJK=NI/2
88      DO 94 J=1,IJK
89      JJ=J+IJK
90      94 WRITE(6,141) J,TS(J),TS(JJ),JJ
91      141 FORMAT(1H,13,3X,'SURFACE TEMPERATURE( DEG. C)',G15.7,3X,G15.7,
92      12X,I3)
93      W=QW(L)
94      C---READ IN AND PRINT OUT INITIAL CONDITIONS
95      READ(5,503) (PSI(I),I=2,L)
96      READ(5,503) (T(I),I=2,L)
97      503 FORMAT(6F10.3)
98      T(2)=TS(1)
99      241 WRITE(6,240)
100     240 FORMAT(1H1,'LISTING OF INITIAL CONDITIONS',//1H0,10X,'INCREMENT',
101     118X,'POSITION',17X,'PSI',5X,'MOISTURE CONTENT(THETA)',5X,
102     2' TEMPERATURE',//1H,41X,'(CH)',12X,'(CH H2O)',18X,'(DIN.)',
103     313X,'(DEG.C)',//)
104     C
105     KL=L+1
106     READ(5,281) N1,N2,N3,N5,N7,N8,N9,M11
107     281 FORMAT(8I5)
108     READ(5,2222) (T1(I),P1(1,I),I=1,N1),P1(2,1),P1(2,N1)
109     READ(5,2222) (THET11(I),P11(1,I),I=1,N11),P11(2,1),P11(2,N11)
110     READ(5,282) N66,NO
111     282 FORMAT(2I5)
112     C---CHARACTERISTIC CURVES
113     READ(5,3333) (PSI66(I),P66(1,I),I=1,N66),P66(2,1),P66(2,N66)
114     3333 FORMAT(D15.7,F10.4)
115     READ(5,154) NR,NI,MI,CSAT1,CSAT2,CSAT3,CSAT4
116     154 FORMAT(3I5,4F10.5)
117     DO 1 I=2,NR
118     1 KSAT(I)=CSAT1
119     NM1=NR+1
120     DO 2 I=NM1,NI

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121      2 KSAT(I)=CSAT2
122      NM2=NI+1
123      DO 3 I=NM2,L1
124      3 KSAT(I)=CSAT3
125      4 KSAT(L)=CSAT4
126      CALL THESP2 (PSI,KL,THETA,N66,PSI66,P66,L)
127      C---
128      DO 6 I=2,L
129      IF (I.GT.N0) GO TO 7
130      READ(5,1111) XM(I),XO(I)
131      GO TO 6
132      7 XM(I)=XM(N0)
133      XO(I)=XO(N0)
134      6 CONTINUE
135      1111 FORMAT(F10.3,F10.5)
136      READ(5,2222) (T9(I),P9(1,I),I=1,N9),P9(2,1),P9(2,N9)
137      READ(5,2222) (T8(I),P8(1,I),I=1,N8),P8(2,1),P8(2,N8)
138      READ(5,2222) (T7(I),P7(1,I),I=1,N7),P7(2,1),P7(2,N7)
139      READ(5,2222) (T3(I),P3(1,I),I=1,N3),P3(2,1),P3(2,N3)
140      2222 FORMAT(2F10.5)
141      READ(5,2222) (T2(I),P2(1,I),I=1,N2),P2(2,1),P2(2,N2)
142      READ(5,2225) (THETA5(I),P5(1,I),I=1,N5),P5(2,1),P5(2,N5)
143      2225 FORMAT(F10.5,D10.6)
144      DO 250 I=2,L
145      Z=I-2
146      Z=DELZ*Z
147      211 WRITE(6,260) I,Z,PSI(I),THETA(I),T(I)
148      250 CONTINUE
149      260 FORMAT(I20.6X,F20.8,4X,JF20.8)
150      T(KL)=T(L)
151      PSI(KL)=PSI(L)-DELZ*(1.000*W/KSAT(L))
152      KODE4=KODE2
153      C---BEGIN TIME ITERATIONS
154      40 DO 270 J=1,NJ
155      IF (NJ.GT.NSTOP) GO TO 999
156      KOUNT=0
157      IF (J.EQ.1) GO TO 6981
158      GO TO 699
159      6981 DO 697 I=2,L
160      THETA0(I)=THETA(I)
161      T0(I)=T(I)
162      PSIO(I)=PSI(I)
163      697 CONTINUE
164      C---CALCULATE TRANSPORT COEFFICIENTS
165      699 CALL UCAPT(XM,XO,L,THETA,CC,KL)
166      IF (J.GE.43) GO TO 999
167      CALL THESP2 (PSI,KL,THETA,N66,PSI66,P66,L)
168      DO 5325 I=2,L
169      IF (J.EQ.1) CCO(I)=CC(I)
170      DELTAT(I)=DABS(T(I+1)-T(I))
171      CTT(I)=(CC(I)+CCO(I))/2.000
172      DELTRF(I)=DABS(T(I)-TREF)
173      IF (KODE3.EQ.0) DL(I)=0.000
174      IF (KODE3.EQ.0) CLQ(I)=0.000
175      359 IF (RSI(I).GE.0.000) GO TO 361
176      EM=HW*GR*PSI(I)
177      ED=R*(T(I)+273.1600)
178      EE=EM/ED
179      SRH(I)=DEXP(EE)
180      GO TO 5325

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181 361 SRH(I)=1.000
182 5325 CONTINUE
183 698 CALL VAPSP(L,T,L,HVAP,N3,T3,P3,KL)
184 CALL DEMS(T,L,RO,N1,T1,P1,KL)
185 CALL THCOND(L,LAMDA,PSI,THETA,KL,THET11,F11,N11)
186 CALL VISCO(T,L,N1,N2,T2,P2,KL)
187 CALL SVSP(L,T,L,SVP,N7,T7,P7,KL)
188 CALL DAWCP(T,L,DAW,N9,T9,P9,KL)
189 CALL PCOEF(L,PSI,THETA,SS,PP,KL)
190 IF(KODE3.EQ.0) GO TO 605
191 CALL CLQCP(T,L,CLQ,N8,T8,P8,KL)
192 605 CALL KSPLN(THETA,K,N5,THETA5,P5,L,PSI,T,HI,RO,
193 IT1,T2,P1,P2,N1,N2,KL,KSAT)
194 CALL HFLUX(DTHV,DTV,QVAP,DPSIV,QS,QCD,KODE3)
195 CALL EVAPO(EV,DELT,DTV,DPSIV,DTL,J,KOUNT,KODE3,KODE5)
196 606 CALL HYCOND(J,KSAT,MITREF,ROTREF,DTHV,DPSIV,
197 IDELTRF,DTV,EV)
198 CALL DPSICP(DTHV,DPSI,KSAT,DTHETA,DPSIV)
199 CALL DTCOEF(DTV,DTL,DPSI,EV,NR,NT,QCD,QS,KODE3)
200 IF(KODE3.EQ.0) GO TO 696
201 CALL DLCOEF(DTHV,DL,DPSIV)
202 696 IF(KOUNT.EQ.0) GO TO 777
203 778 KOUNT=KOUNT+1
204 IF(KODE2.EQ.1) GO TO 6011
205 IF(J-KODE4.NE.0) GO TO 341.
206 6011 WRITE(6,6768)
207 6768 FORMAT(1H,'0X','THETA',14X,'K',12X,'QH',11X,'CC',13X,'QW',
208 112X,'DTL',12X,'PSI',12X,'T')
209 DO 6769 I=2,L
210 6769 WRITE(6,6770) I,THETA(I),K(I),QH(I),CC(I),QW(I),DTL(I),PSI(I),
211 IT(I)
212 6770 FORMAT(1H,I2,2X,8G15.6)
213 WRITE(6,6767)
214 6767 FORMAT(1H,'0X','THETA',12X,'DT',12X,'DTV',12X,'DL',10X,
215 'LAMDA',11X,'DPSIV',11X,'DPSI',10X,'QVAP')
216 DO 5163 I=2,30
217 5163 WRITE(6,5164) I,THETA(I),DT(I),DTV(I),DL(I),LAMDA(I),DPSIV(I),
218 IDPSI(I),QVAP(I)
219 5164 FORMAT(1H,I2,2X,8G15.6)
220 341 DO 340 I=2,L
221 FTT(I)=(FF(I)+FO(I))/2.000
222 CQ(I)=(CLQ(I)+CLQO(I))/2.000
223 QW(I)=(QW(I)+QWO(I))/2.000
224 340 CONTINUE
225 DO 720 I=3,L1
226 APR(I)=(LAMDA(I)+LAMDA(I-1)+LAMDAO(I-1)+LAMDAO(I))/4.000
227 1+CQ(I)*RO(I)*QW(I)*DELZ/2.000
228 718 CPR(I)=(LAMDAO(I)+LAMDAO(I+1)+LAMDA(I+1)+LAMDA(I))/4.000
229 1-CQ(I)*RO(I)*QW(I)*DELZ/2.000
230 716 BPR(I)=((CC(I)+CCO(I))/RATIOR)+APR(I)+CPR(I)
231 720 CONTINUE
232 APR(2)=(LAMDA(2)+LAMDAO(2))/2.000+CQ(2)*RO(2)*QW(2)*DELZ/2.000
233 CPR(2)=(LAMDAO(2)+LAMDA(2)+LAMDAO(3)+LAMDA(3))/4.000
234 1-CQ(2)*RO(2)*QW(2)*DELZ/2.000
235 BPR(2)=((CC(2)+CCO(2))/RATIOR)+APR(2)+CPR(2)
236 APR(L)=(LAMDA(L)+LAMDA(L1)+LAMDAO(L1)+LAMDAO(L))/4.000
237 1+CQ(L)*RO(L)*QW(L)*DELZ/2.000
238 CPR(L)=(LAMDA(L)+LAMDAO(L))/2.000-CQ(L)*RO(L)*QW(L)*DELZ/2.000
239 BPR(L)=((CC(L)+CCO(L))/RATIOR)+APR(L)+CPR(L)
240 DO 780 I=3,L1

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241 ABARPR (I) = (DL (I) + DL (I-1) + DLO (I-1) + DLO (I)) / 4.000
242 738 CBARPR (I) = (DLO (I) + DLO (I+1) + DL (I+1) + DL (I)) / 4.000
243 736 BBARPR (I) = ABARPR (I) + CBARPR (I)
244 740 CONTINUE
245 ABARPR (2) = (DLO (2) + DL (2)) / 2.000
246 CBARPR (2) = (DLO (2) + DL (2) + DLO (3) + DL (3)) / 4.000
247 BBARPR (2) = ABARPR (2) + CBARPR (2)
248 ABARPR (L) = (DL (L) + DL (L-1) + DLO (L-1) + DLO (L)) / 4.000
249 CBARPR (L) = (DLO (L) + DL (L)) / 2.000
250 BBARPR (L) = ABARPR (L) + CBARPR (L)
251 782 DO 760 I=3, L1
252 ABAR (I) = (DT (I) + DT (I-1) + DTO (I-1) + DTO (I)) / 4.000
253 758 CBAR (I) = (DTO (I) + DTO (I+1) + DT (I+1) + DT (I)) / 4.000
254 756 BBAR (I) = ABAR (I) + CBAR (I)
255 760 CONTINUE
256 ABAR (2) = (DT (2) + DTO (2)) / 2.000
257 CBAR (2) = (DTO (2) + DT (2) + DTO (3) + DT (3)) / 4.000
258 BBAR (2) = ABAR (2) + CBAR (2)
259 ABAR (L) = (DT (L) + DT (L-1) + DTO (L-1) + DTO (L)) / 4.000
260 CBAR (L) = (DTO (L) + DT (L)) / 2.000
261 BBAR (L) = ABAR (L) + CBAR (L)
262 DO 780 I=3, L1
263 A (I) = (DPSI (I) + DPSI (I-1) + DPSIO (I-1) + DPSIO (I)) / 4.000
264 768 C (I) = (DPSIO (I) + DPSIO (I+1) + DPSI (I+1) + DPSI (I)) / 4.000
265 766 B (I) = ((FP (I) + PO (I)) / RATIO) + A (I) + C (I)
266 780 CONTINUE
267 A (2) = (DPSI (2) + DPSIO (2)) / 2.000
268 C (2) = (DPSIO (2) + DPSI (2) + DPSIO (3) + DPSI (3)) / 4.000
269 B (2) = ((FP (2) + PO (2)) / RATIO) + A (2) + C (2)
270 A (L) = (DPSI (L) + DPSI (L-1) + DPSIO (L-1) + DPSIO (L)) / 4.000
271 C (L) = (DPSIO (L) + DPSI (L)) / 2.000
272 B (L) = ((FP (L) + PO (L)) / RATIO) + A (L) + C (L)
273 DO 800 I=3, L1
274 IF (I.GE.NR) GO TO 775
275 KHINUS (I) = (K (I) + K (I-1) + KO (I-1) + KO (I)) / 4.000
276 788 KPLUS (I) = (KO (I) + KO (I+1) + K (I+1) + K (I)) / 4.000
277 GO TO 800
278 775 KHINUS (I) = 4.000 / (1.000 / K (I) + 1.000 / K (I-1) + 1.000 / KO (I-1) + 1.000 /
279 1KO (I))
280 KPLUS (I) = 4.000 / (1.000 / KO (I) + 1.000 / KO (I+1) + 1.000 / K (I+1) + 1.000 /
281 1K (I))
282 800 CONTINUE
283 KHINUS (2) = (K (2) + KO (2)) / 2.000
284 KPLUS (2) = (KO (2) + K (2) + KO (3) + K (3)) / 4.000
285 KHINUS (L) = 4.000 / (1.000 / K (L) + 1.000 / K (L-1) + 1.000 / KO (L-1) + 1.000 /
286 1KO (L))
287 KPLUS (L) = 2.000 / (1.000 / K (L) + 1.000 / KO (L))
288 C---FORMULATE SUBMATRICES D, E, F, G
289 811 D (3, 1) = 0.000
290 D (3, 2) = BPR (3) - ABARPR (3) + ABAR (3) / A (3)
291 D (3, 3) = -CPR (3)
292 DO 300 I=4, L1
293 D (I, 1) = -APR (I)
294 D (I, 2) = BPR (I)
295 D (I, 3) = -CPR (I)
296 300 CONTINUE
297 D (L, 1) = -APR (L)
298 D (L, 2) = BPR (L)
299 D (L, 3) = 0.000
300 G (2, 1) = 0.000

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301      G(2,2)=B(2)-A(2)
302      G(2,3)=-C(2)
303      DO 330 I=3,L1
304      G(I,1)=-A(I)
305      G(I,2)=B(I)
306      G(I,3)=-C(I)
307      330 CONTINUE
308      G(L,1)=-A(L)
309      G(L,2)=B(L)
310      G(L,3)=0.000
311      E(3,1)=0.000
312      E(3,2)=CBARPR(3)
313      E(3,3)=-CBARPR(3)
314      DO 310 I=4,L1
315      E(I,1)=-ABARPR(I)
316      E(I,2)=BBARPR(I)
317      E(I,3)=-CBARPR(I)
318      310 CONTINUE
319      E(L,1)=-ABARPR(L)
320      E(L,2)=BBARPR(L)
321      F(L,3)=0.000
322      F(2,1)=0.000
323      F(2,2)=CBAR(2)
324      F(2,3)=-CBAR(2)
325      DO 320 I=3,L1
326      F(I,1)=-ABAR(I)
327      F(I,2)=BBAR(I)
328      F(I,3)=-CBAR(I)
329      320 CONTINUE
330      F(L,1)=-ABAR(L)
331      F(L,2)=BBAR(L)
332      F(L,3)=0.000
333      C---APPLY TOP B.C.
334      TI(2)=TS(J)
335      C---APPLY BOTTOM B.C.
336      322 TI(KL)=T(L)
337      30 PSI(KL)=PSI(L)-DELZ*(1.000+W/K(L))-DT(L)*(T(KL)-T(L))/K(L)
338      PSII(KL)=PSI(KL)
339      IF(PSI(L)-LT.0.000) GO TO 887
340      C
341      35 DO 350 I=3,L
342      H(I)=- (C(I) * (PSI(I) - PSI(I+1)) + A(I) * (PSI(I) - PSI(I-1)))
343      1 + CBAR(I) * (T(I) - T(I+1)) + ABAR(I) * (T(I) - T(I-1))
344      2 - (KMINUS(I) - KPLUS(I)) * 2.000 * DELZ - (2.000 * PTT(I) / RATIO) * PSI(I)
345      C
346      HPR(I) = - (CPR(I) * (T(I) - T(I+1)) + APR(I) * (T(I) - T(I-1)) +
347      1CBARPR(I) * (PSI(I) - PSI(I+1)) + ABARPR(I) * (PSI(I) - PSI(I-1))
348      2 + CQ(I) * RO(I) * QWW(I) * DELZ * (T(I+1) - T(I-1)) / 2.000
349      3 - (2.000 * CTT(I) / RATIO) * T(I))
350      350 CONTINUE
351      H(2) = ((2.000 * PTT(2) / RATIO) - C(2)) * PSI(2) + C(2) * PSI(3) + 2.000 *
352      1DELZ * (EV - KPLUS(2)) + CBAR(2) * (T(3) - T(2))
353      HPR(3) = 2.000 * CTT(3) * T(3) / RATIO + (APR(3) + CQ(3) * RO(3) * QWW(3) *
354      1DELZ / 2.000 - (ABARPR(3) * ABAR(3))
355      2 / A(3)) * TI(2) + CPR(3) * (T(4) - T(3)) + APR(3) * (T(2) - T(3)) + ABARPR(3) *
356      3ABAR(3) / A(3) * (T(3) - T(2)) + CBARPR(3) * (PSI(4) - PSI(3)) + 2.000 *
357      4DELZ * ABARPR(3) / A(3) * (EV - KMINUS(3)) + CQ(3) * RO(3) * QWW(3) * DELZ *
358      5(T(4) - T(2)) / 2.000
359      I=L
360      352 H(I) = H(I) + C(I) * PSI(I+1) + CBAR(I) * T(I+1)

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361 HPR(I)=HPR(I)+CPR(I)*T(I+1)+CBARPR(I)*PSI(I+1)
362 C---FORM RHS : HPR-(E)*(PSI)=U : H-(F)*(T)=V
363 DO 9875 I=2,L
364 IF(I.EQ.2) GO TO 9874
365 V(I)=H(I)-F(I,1)*T(I-1)-F(I,2)*T(I)-F(I,3)*T(I+1)
366 GO TO 9873
367 9874 V(2)=H(2)-F(2,2)*T(2)-F(2,3)*T(3)
368 9873 GI(I)=G(I,1)
369 GII(I)=G(I,2)
370 GIII(I)=G(I,3)
371 9875 CONTINUE
372 CALL TRIDAG(2,L,GI,GII,GIII,V,PSII)
373 DO 9870 I=3,L
374 U(I)=HPR(I)-E(I,1)*PSII(I-1)-E(I,2)*PSII(I)-E(I,3)*PSII(I+1)
375 DI(I)=D(I,1)
376 DII(I)=D(I,2)
377 DIII(I)=D(I,3)
378 9870 CONTINUE
379 CALL TRIDAG(3,L,DI,DII,DIII,U,TI)
380 CALL THESP2(PSII,KL,THETA1,M66,PSI66,P66,L)
381 IF(KOUNT.GT.KMAX) GO TO 888
382 DO 77 I=3,L
383 IF(DABS(TI(I)-T(I))-LE.EPS) GO TO 77
384 GO TO 9
385 77 CONTINUE
386 DO 710 I=2,L
387 TO(I)=T(I)
388 T(I)=TI(I)
389 IF(I.EQ.1) GO TO 710
390 PSIO(I)=PSI(I)
391 PSI(I)=PSII(I)
392 THETAO(I)=THETA(I)
393 THETA(I)=THETA1(I)
394 CCO(I)=CC(I)
395 710 CONTINUE
396 GO TO 271
397 9 DO 711 I=2,L
398 TO(I)=T(I)
399 T(I)=(TI(I)+TO(I))/2.0D0
400 IF(I.EQ.1) GO TO 711
401 PSIO(I)=PSI(I)
402 PSI(I)=(PSII(I)+PSIO(I))/2.0D0
403 THETAO(I)=THETA(I)
404 THETA(I)=(THETA1(I)+THETAO(I))/2.0D0
405 CCO(I)=CC(I)
406 711 CONTINUE
407 GO TO 699
408 777 DO 17 I=2,L
409 CCO(I)=CC(I)
410 DPSIO(I)=DPSI(I)
411 FO(I)=FF(I)
412 LAMDAO(I)=LAMDA(I)
413 KO(I)=K(I)
414 CLQO(I)=CLQ(I)
415 QWO(I)=QW(I)
416 DLO(I)=DL(I)
417 DTO(I)=DT(I)
418 17 CONTINUE
419 GO TO 778
420 C---PRINT OUT CALCULATED VALUES

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421      271 IF(KODE2.EQ.1) GO TO 6016
422          IF(J-KODE4.NE.0) GO TO 270
423          KODE4=KODE2+J
424      6016 WRITE(6,5019) J,KOUNT,(TI(I),I=2,L)
425          WRITE(6,5020) J,(PSII(I),I=2,L)
426      5019 FORMAT(1H0,'J=',I3,2X,'KOUNT=',I3,/(1H0,'T',6G15.7))
427      5020 FORMAT(1H0,'J=',I3,/(1H0,'PSI',6G15.7))
428      6015 WRITE(6,700)
429      700 FORMAT(1H0,'=====')
430      270 CONTINUE
431          WRITE(6,702) J
432      702 FORMAT(1H0,'NORMAL TERMINATION,J=',I5,2X,'ITERATIONS')
433          GO TO 999
434      887 WRITE(6,887)
435      87 FORMAT(1H0,'WARNING--PROFILE DRIED TO THE BOTTOM')
436          GO TO 999
437      888 WRITE(6,889)
438      889 FORMAT(1H0,'LIMITS EXCEEDED; NO CONVERGENCE')
439      999 STOP
440      END
441
C
442 C---SUBROUT
443 C
444 C      SUBROUTINE DTCDZ(DTV,DTL,DPSI,EV,NI,NI,QCD,QS,KODE3)
445 C
446      IMPLICIT REAL*8(A-H,O-Z)
447      COMMON/DSWHE/ PSI(50),THETA(50),T(50),QW(50),QH(50),DELTAT(50),
448      1LAMBDA(50),CLQ(50),SVP(50),RO(50),SI(50),P2(4,50),T2(50),
449      2T1(50),P1(4,50),T3(50),P3(4,50),THET11(50),P11(4,50),HVAP(50),
450      3THETA5(50),P5(4,50),T9(50),P9(4,50),FF(50),
451      4PSI66(50),P66(4,50),T7(50),P7(4,50),T8(50),
452      5P8(4,50),SRH(50),K(50),QWO(50),DAW(50),DT(50),
453      6THETA0(50),NJ,L,I,K,M,NW,DELZ
454      COMMON/NM/ N1,N2,N3,N5,N7,N8,N9,N11,N66
455 C
456      DIMENSION DTV(L),DTL(L),DPSI(L),
457      1QCV(50),QCD(L),QS(L)
458      REAL*8 K,NW,LAMBDA,KSAT,NI,NITREF,HVAP
459      DATA R/8.31432,OD*2/,GR/980.665D0/
460      DO 333 I=2,L
461      33 IF(PSI(I)-GE.0.0D0) GO TO 303
462          DTL(I)=K(I)*R*DLOG(SRH(I))/(NW*GR)
463      30 DTL(I)=DABS(DTL(I))
464          IF(KODE3.EQ.0) DTL(I)=0.0D0
465          DT(I)=DTL(I)+DTV(I)
466          IF(KODE3.EQ.0) DT(I)=0.0D0
467          IF(I.LE.3) GO TO 331
468          QW(I)=-DPSI(I)*(PSI(I+1)-PSI(I-1))/(2.0D0*DELZ)-DT(I)*
469          1(T(I+1)-T(I-1))/(2.0D0*DELZ)*K(I)
470          GO TO 333
471      303 DT(I)=0.0D0
472          DTL(I)=DT(I)
473          IF(I.LE.3) GO TO 331
474          IF(I.EQ.L) GO TO 333
475      298 QW(I)=- (2.0D0/(1.0D0/K(I-1)+1.0D0/K(I+1)))* (PSI(I+1)-PSI(I-1))
476          1/(2.0D0*DELZ)-1.0D0)
477          GO TO 333
478      331 QW(2)=EV
479      333 CONTINUE
480      DO 100 I=2,L

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481      QCV(I)=RO(I)*CLQ(I)*DELTAT(I)*QH(I)
482      IF(KODE3.EQ.0) QCV(I)=0.0D0
483      QH(I)=QCD(I)*QS(I)+QCV(I)
484      100 CONTINUE
485      440 RETURN
486      END
487
C
488      SUBROUTINE DPSICP(DTHV,DPSI,KSAT,DTHETA,DPSIV)
489
C
490      IMPLICIT REAL*8(A-H,O-Z)
491      COMMON/DSWHE/ PSI(50),THETA(50),T(50),QH(50),QH(50),DELTAT(50),
492      1LAMBDA(50),CLQ(50),SVP(50),RO(50),NI(50),P2(4,50),T2(50),
493      2T1(50),P1(4,50),T3(50),P3(4,50),THET11(50),P11(4,50),HVAP(50),
494      3THETA5(50),P5(4,50),T9(50),P9(4,50),PF(50),
495      4PSI66(50),P66(4,50),T7(50),P7(4,50),T8(50),
496      5P8(4,50),SRH(50),K(50),QWO(50),DAW(50),DT(50),
497      6THETA0(50),NJ,L,L1,KL,M,DELZ
498      COMMON/NN/ N1,N2,N3,N5,N7,N8,N9,N11,N66
499
C
500      DIMENSION DTHV(L),DPSI(L),KSAT(L),DTHETA(L),DPSIV(L)
501      REAL*8 K,M,LAMBDA,KSAT,NI,NITREF,HVAP
502      DATA R/831432.0D+2/,GR/980.665D0/
503      DO 455 I=2,L
504      IF (PSI(I).GE.0.0D0) GO TO 45
505      DPSI(I)=K(I)+DPSIV(I)
506      IF (PF(I).EQ.0.0D0) GO TO 453
507      DTHETA(I)=DPSI(I)/PF(I)
508      GO TO 454
509      45 DPSI(I)=K(I)
510      453 DTHETA(I)=0.0D0
511      454 DPSI(I)=DABS(DPSI(I))
512      455 CONTINUE
513      RETURN
514      END
515
C
516      SUBROUTINE HYCOND(J,KSAT,NITREF,ROTREF,DTHV,DPSIV,
517      1DELTRF,DTV,EV)
518
C
519      IMPLICIT REAL*8(A-H,O-Z)
520      COMMON/DSWHE/ PSI(50),THETA(50),T(50),QH(50),QH(50),DELTAT(50),
521      1LAMBDA(50),CLQ(50),SVP(50),RO(50),NI(50),P2(4,50),T2(50),
522      2T1(50),P1(4,50),T3(50),P3(4,50),THET11(50),P11(4,50),HVAP(50),
523      3THETA5(50),P5(4,50),T9(50),P9(4,50),PF(50),
524      4PSI66(50),P66(4,50),T7(50),P7(4,50),T8(50),
525      5P8(4,50),SRH(50),K(50),QWO(50),DAW(50),DT(50),
526      6THETA0(50),NJ,L,L1,KL,M,DELZ
527      COMMON/NN/ N1,N2,N3,N5,N7,N8,N9,N11,N66
528
C
529      DIMENSION DTHV(L),DPSIV(L),
530      1DELTRF(L),KSAT(L),DTV(L),BL(50)
531      REAL*8 NI,NITREF,K,KSAT,M,LAMBDA,HVAP
532      DATA R/831432.0D+2/,GR/980.665D0/
533      DO 111 I=2,L
534      IF (PSI(I).LT.0.0D0) GO TO 111
535      PF(DELTRF(I).GE.1.0D0) GO TO 102
536      101 K(I)=KSAT(I)
537      GO TO 111
538      102 K(I)=KSAT(I)*(NITREF/ROTREF)*RO(I)/NI(I)
539      111 CONTINUE
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541      IF (J.LE.1000) GO TO 113
542      CALCULATION OF UNSAT K USING NON-ISOTHERMAL WATER FLUX EQN
543      DO 112 I=2,L1
544      IF (PSI(I).LT.0.000) GO TO 103
545      GO TO 112
546      IF (I.EQ.3) GO TO 112
547      BL(I)=R*DLOG(SRH(I))/(NW*GR)
548      IF (I.EQ.2) GO TO 99
549      K(I)=(-QW(I)-DPSIV(I)*(PSI(I+1)-PSI(I-1)))/(2.000*DELZ)
550      1-DTV(I)*(T(I+1)-T(I-1))/(2.000*DELZ))
551      2/(BL(I)*(T(I+1)-T(I-1))/(2.000*DELZ)+
552      3(PSI(I+1)-PSI(I-1))/(2.000*DELZ)-1.000)
553      GO TO 98
554      99 K(I)=(-QW(I)-DPSIV(I)*(PSI(I+1)-
555      PSI(I))/DELZ-DTV(I)*(T(I+1)-T(I))/DELZ)/(
556      2DELZ+(PSI(I+1)-PSI(I))/DELZ-1.000)
557      98 K(I)=DABS(K(I))
558      112 CONTINUE
559      113 RETJRN
560      END
561      C
562      SUBROUTINE EVAP0 (EV, DELT, DTV, DPSIV, DTL, J, KOUNT, KODE3, KODE5)
563      C
564      IMPLICIT REAL*8 (A-H, O-Z)
565      COMMON/D5WHE/ PSI (50), THETA (50), T (50), QW (50), QH (50), DELTAT (50),
566      1LAMBDA (50), CLQ (50), SVP (50), RH (50), HI (50), P2 (4, 50), T2 (50),
567      2T1 (50), P1 (4, 50), T3 (50), P3 (4, 50), THETA1 (50), P11 (4, 50), HVAP (50),
568      3THETA5 (50), P5 (4, 50), T9 (50), P9 (4, 50), PF (50),
569      4PSI66 (50), P66 (4, 50), T7 (50), P7 (4, 50), T8 (50),
570      5PB (4, 50), SRH (50), K (50), QW0 (50), DAW (50), DT (50),
571      6THETA0 (50), NJ, L, L1, KL, HW, DELZ
572      COMMON/NM/ N1, N2, N3, N5, N7, N8, N9, N11, N66
573      C
574      DIMENSION DTV (L), DPSIV (L), DEL (L)
575      REAL*8 NW, K, LAMBDA, HVAP, HI
576      DATA R/831432.0D+2/, GR/980.665D0/
577      DT (3)=DTV (3)+DABS (K (3)+R*DLOG (SRH (3)))/(NW*GR)
578      IF (KODE3.EQ.0) DT (3)=0.000
579      48 QW (3)=- (K (3)+DPSIV (3)) * (PSI (4)-PSI (2))/(2.000*DELZ)
580      1-DT (3)*(T (4)-T (2))/(2.000*DELZ)+K (3)
581      IF (KODE5.GT.0) GO TO 40
582      444 EV=DABS (QW (3)) - (THETA (2)-THETA0 (2)+THETA (3)-THETA0 (3))/2.000
583      1*DELZ/DELT
584      IF (QW (3).GT.0.000) EV=-QW (3) - (THETA (2)-THETA0 (2)+THETA (3)
585      1-THETA0 (3))/2.000*DELZ/DELT
586      45 WRITE (6, 47) J, KOUNT, EV, QW (3), K (3), THETA (2), THETA (3)
587      47 FORMAT (1H0, 'J=', I3, 2X, 'KOUNT', I3, 2X, 'EV=', G15.7, 2X, 'QW (3)='
588      1G15.7, 2X, 'K (3)=' , G15.7, 2X, 'THETA (2, 3)', 2G15.7)
589      EV=-EV
590      GO TO 41
591      40 EV=0.09D0
592      41 RETURN
593      END
594      C
595      SUBROUTINE HCAPT (XH, XO, L, THETA, CC, KL)
596      IMPLICIT REAL*8 (A-H, O-Z)
597      DIMENSION XH (KL), XO (KL), THETA (KL), CC (KL)
598      DO 213 I=2, L
599      CC (I)=0.46D0*XH (I)+0.60D0*XO (I)+THETA (I)
600      213 CONTINUE

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601 RETURN
602 END
603
604 C
605 SUBROUTINE HFLUX(DTHV,DTV,QVAP,DPSIV,QS,QCD,KODE3)
606 IMPLICIT REAL*8(A-H,O-Z)
607 COMMON/DS#HE/ PSI(50),THETA(50),T(50),QW(50),QH(50),DELTAT(50),
608 1LAMD(50),CLQ(50),SVP(50),RO(50),MI(50),P2(4,50),T2(50),
609 2T1(50),P1(4,50),T1(50),P3(4,50),THET11(50),P11(4,50),HVAP(50),
610 3THETA5(50),P5(4,50),T9(50),P9(4,50),PF(50),
611 4PSI66(50),P66(4,50),T7(50),P7(4,50),T8(50),
612 5PB(4,50),SRH(50),K(50),QWO(50),DAW(50),DT(50),
613 6THETA0(50),NJ,L,L1,KL,MW,DELZ
614 C
615 COMMON/NN/ N1,N2,N3,N5,N7,N8,N9,N11,N66
616 DIMENSION DTHV(L),DTV(L),QVAP(L),QCD(L),QS(L),QCV(50),
617 1DPSIV(L)
618 REAL*8 LAMDA,HVAP,MW,K,MI
619 DATA R/831432.0D+2/,GR/980.665D0/
620 POR=0.41D0
621 DO 100 I=2,L
622 IF (PSI(I).GE.0.0D0) GO TO 99
623 ZETA=1.8D0
624 IF (THETA(I).LE.0.09D0) GO TO 95
625 RK=(POR-THETA(I))/(POR-0.09D0)
626 PF=(2.0D0/3.0D0)*(POR-THETA(I)+RK*THETA(I))
627 GO TO 96
628 95 PF=2.0D0*POR/3.0D0
629 RT=M2*GR/(R*(T(I)+273.16D0))
630 RTS=RT*RT
631 DPSIV(I)=PF*DAW(I)*SVP(I)*RTS*SRH(I)
632 IF (KODE3.EQ.0) DPSIV(I)=0.0D0
633 GO TO 98
634 99 DPSIV(I)=0.0D0
635 QS(I)=0.0D0
636 98 IF (I.EQ.2) GO TO 30
637 QCD(I)=-LAMDA(I)*(T(I+1)-T(I))/(2.0D0*DELZ)
638 QS(I)=-DPSIV(I)*RO(I)*HVAP(I)*(PSI(I+1)-PSI(I))/(2.0D0*DELZ)
639 SP=(SVP(I+1)-SVP(I))/(T(I+1)-T(I))
640 GO TO 40
641 30 QCD(2)=-LAMDA(I)*(T(I+1)-T(I))/DELZ
642 QS(2)=-DPSIV(I)*RO(I)*HVAP(I)*(PSI(I+1)-PSI(I))/DELZ
643 SP=(SVP(I+1)-SVP(I))/(T(I+1)-T(I))
644 40 IF (PSI(I).GE.0.0D0) GO TO 331
645 IF (PF(I).EQ.0.0D0) GO TO 45
646 DTHV(I)=DPSIV(I)/PF(I)
647 45 IF (T(I).GE.25.0D0) ZETA=1.3D0
648 DTV(I)=ZETA*PF*RT*DAW(I)*SRH(I)*SP
649 IF (KODE3.EQ.0) DTV(I)=0.0D0
650 IF (I.EQ.2) GO TO 300
651 QVAP(I)=-DPSIV(I)*(PSI(I+1)-PSI(I))/(2.0D0*DELZ)
652 1-DTV(I)*(T(I+1)-T(I))/(2.0D0*DELZ)
653 GO TO 100
654 300 QVAP(2)=-DPSIV(2)*(PSI(3)-PSI(2))/DELZ-DTV(2)*(T(3)-T(2))/DELZ
655 GO TO 100
656 331 DTV(I)=0.0D0
657 DTHV(I)=0.0D0
658 QVAP(I)=0.0D0
659 100 CONTINUE
660 321 RETURN
661 END

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SUBROUTINE PCOEF(L,PSI,THETA,SS,FF,KL)
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION PSI(KL),THETA(KL),FF(L)
DO 45 I=2,L
IF (PSI(I).GE.0.000) GO TO 35
IF (I.EQ.2) GO TO 33
IF (PSI(I+1).GE.0.000) GO TO 34
IF (PSI(I+1).EQ.PSI(I-1)) GO TO 32
FF(I)=(THETA(I+1)-THETA(I-1))/(PSI(I+1)-PSI(I-1))
GO TO 45
33 IF (PSI(2).EQ.PSI(3)) GO TO 32
FF(I)=(THETA(I+1)-THETA(I))/(PSI(I+1)-PSI(I))
GO TO 45
34 FF(I)=(THETA(I+1)-THETA(I))/(-PSI(I))
GO TO 45
32 FF(I)=0.000
GO TO 45
35 FF(I)=SS
45 CONTINUE
RETURN
END

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C

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SUBROUTINE DLCOEF(DTHV,DL,DPSIV)
IMPLICIT REAL*8(A-H,O-Z)
COMMON/D5WHE/ PSI(50),THETA(50),T(50),QW(50),QH(50),DELTAT(50),
1LANDA(50),CLQ(50),SVP(50),RO(50),MI(50),P2(4,50),T2(50),
2T1(50),P1(4,50),T3(50),P3(4,50),THET11(50),P11(4,50),HVAP(50),
3THETA5(50),P5(4,50),T9(50),P9(4,50),FF(50),
4PSI66(50),P66(4,50),T7(50),P7(4,50),T8(50),
5P8(4,50),SRH(50),K(50),QRO(50),DAW(50),DT(50),
6THETA0(50),NJ,L,L1,KL,MW,DELZ
COMMON/NM/ N1,N2,N3,N5,N7,N8,N9,N11,N66

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C

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DIMENSION DTHV(L),DL(L),DPSIV(L)
REAL*8 MW,HVAP,KSAT,K,LANDA,MI,MITREF
DATA R/831432.00+2/,GR/980.66500/
DO 65 I=2,L
IF (PSI(I).GE.0.000) GO TO 75
DL(I)=RO(I)*HVAP(I)*DPSIV(I)
GO TO 65
75 DL(I)=0.000
65 CONTINUE
RETURN
END

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C

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SUBROUTINE DENS(T,L,RO,N1,T1,P1,KL)
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION RO(KL),T(KL),T1(N1),P1(4,N1)
NR=N1-1
CALL SPLINE(NR,T1,P1,N1)
CALL CALCCP(NR,T1,P1,N1)
DO 63 I=2,L
X=T(I)
63 RO(I)=PCUBIC(X,NR,T1,P1,N1)
RETURN
END

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SUBROUTINE VISCO(T,L,MI,N2,T2,P2,KL)

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721      IMPLICIT REAL*8 (A-H,O-Z)
722      DIMENSION T2(N2),P2(4,N2),NI(KL),T(KL)
723      REAL*8 NI
724      NR=N2-1
725      CALL SPLINE(NR,T2,P2,N2)
726      CALL CALCCF(NR,T2,P2,N2)
727      DO 63 I=2,L
728      X=T(I)
729      63 NI(I)=PCUBIC(X,NR,T2,P2,N2)
730      RETURN
731      END
732
733      C
734      SUBROUTINE VAPSPL(T,L,HVAP,N3,T3,P3,KL)
735      IMPLICIT REAL*8(A-H,O-Z)
736      DIMENSION T3(N3),P3(4,N3),HVAP(KL),T(KL)
737      REAL*8 HVAP
738      NR=N3-1
739      CALL SPLINE(NR,T3,P3,N3)
740      CALL CALCCF(NR,T3,P3,N3)
741      DO 63 I=2,L
742      X=T(I)
743      63 HVAP(I)=PCUBIC(X,NR,T3,P3,N3)
744      RETURN
745      END
746
747      C
748      SUBROUTINE THESP2(PSI,KL,THETA,N66,PSI66,P66,L)
749      IMPLICIT REAL*8(A-H,O-Z)
750      DIMENSION THETA(KL),PSI(KL),P66(4,N66),PSI66(N66)
751      NR=N66-1
752      CALL SPLINE(NR,PSI66,P66,N66)
753      CALL CALCCF(NR,PSI66,P66,N66)
754      DO 64 I=2,L
755      IF(PSI(I).GE.0.000) GO TO 62
756      IF(PSI(I).LE.-1.005) GO TO 63
757      X=PSI(I)
758      62 THETA(I)=0.4100
759      GO TO 64
760      63 THETA(I)=0.03700
761      64 CONTINUE
762      RETURN
763      END
764
765      C
766      SUBROUTINE SVPSPL(T,L,SVP,N7,T7,P7,KL)
767      IMPLICIT REAL*8(A-H,O-Z)
768      DIMENSION T7(N7),P7(4,N7),SVP(KL),T(KL)
769      NR=N7-1
770      CALL SPLINE(NR,T7,P7,N7)
771      CALL CALCCF(NR,T7,P7,N7)
772      DO 63 I=2,KL
773      X=T(I)
774      63 SVP(I)=PCUBIC(X,NR,T7,P7,N7)
775      RETURN
776      END
777
778      C
779      SUBROUTINE CLOCF(T,L,CLQ,N8,T8,P8,KL)
780      IMPLICIT REAL*8(A-H,O-Z)
781      DIMENSION T8(N8),P8(4,N8),CLQ(KL),T(KL)
782      NR=N8-1

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781      CALL SPLINE(NR,T8,P8,N8)
782      CALL CALCCF(NR,T8,P8,N8)
783      DO 63 I=2,L
784      X=T(I)
785      63 CLQ(I)=PCUBIC(X,NR,T8,P8,N8)
786      RETURN
787      END
788
789      C
790      SUBROUTINE SPLINE(NR,XI,P,NSIZE)
791      IMPLICIT REAL*8(A-H,O-Z)
792      DIMENSION XI(NSIZE),P(4,NSIZE),D(50),DIAG(50)
793      DIAG(1)=1.0D0
794      D(1)=0.0D0
795      NP1=NR+1
796      DO 10 M=2,NP1
797      D(M)=XI(M)-XI(M-1)
798      10 DIAG(M)=(P(1,M)-P(1,M-1))/D(M)
799      DO 20 M=2,NR
800      P(2,M)=3.0D0*(D(M)*DIAG(M+1)+D(M+1)*DIAG(M))
801      20 DIAG(M)=2.0D0*(D(M)+D(M+1))
802      DO 30 M=2,NR
803      G=-D(M+1)/DIAG(M-1)
804      DIAG(M)=DIAG(M)+G*D(M-1)
805      30 P(2,M)=P(2,M)+G*P(2,M-1)
806      NJ=NP1
807      DO 40 M=2,NR
808      NJ=NJ-1
809      40 P(2,NJ)=(P(2,NJ)-D(NJ)*P(2,NJ+1))/DIAG(NJ)
810      RETURN
811      END
812
813      C
814      SUBROUTINE CALCCF(NR,XI,P,NSIZE)
815      IMPLICIT REAL*8(A-H,O-Z)
816      DIMENSION XI(NSIZE),P(4,NSIZE)
817      DO 10 I=1,NR
818      DX=XI(I+1)-XI(I)
819      DIVDF1=(P(1,I+1)-P(1,I))/DX
820      DIVDF3=P(2,I)+P(2,I+1)-2.0D0*DIVDF1
821      P(3,I)=(DIVDF1-P(2,I)-DIVDF3)/DX
822      P(4,I)=DIVDF3/DI/DX
823      10 CONTINUE
824      RETURN
825      END
826
827      C
828      FUNCTION PCUBIC(XBAR,NR,XI,P,NSIZE)
829      IMPLICIT REAL*8(A-H,O-Z)
830      DIMENSION XI(NSIZE),P(4,NSIZE)
831      I=1
832      DX=XBAR-XI(I)
833      IF (DX) 10,30,20
834      10 IF (I.EQ.1) GO TO 30
835      I=I-1
836      DX=XBAR-XI(I)
837      IF (DX) 10,30,30
838      19 I=I+1
839      DX=DDX
840      20 IF (I.EQ.NR) GO TO 30
841      DDX=XBAR-XI(I+1)
842      IF (DDX) 30,19,19
843      30 PCUBIC=P(1,I)+DX*(P(2,I)+DX*(P(3,I)+DX*P(4,I)))

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841      RETURN
842      END
843
844      C
845      SUBROUTINE TRIDAG(I1,L,AZ,BZ,CZ,DR,VZ)
846      IMPLICIT REAL*8(A-H,O-Z)
847      DIMENSION AZ(50),BZ(50),CZ(50),DR(50),VZ(50),BETA(50),GAMMA(50)
848      BETA(I1)=BZ(I1)
849      GAMMA(I1)=DR(I1)/BETA(I1)
850      I1P1=I1+1
851      DO 1 I=I1P1,L
852      BETA(I)=BZ(I)-AZ(I)*CZ(I-1)/BETA(I-1)
853      1 GAMMA(I)=(DR(I)-AZ(I)*GAMMA(I-1))/BETA(I)
854      VZ(L)=GAMMA(L)
855      LAST=L-1
856      DO 2 K=1,LAST
857      I=L-K
858      VZ(I)=GAMMA(I)-CZ(I)*VZ(I+1)/BETA(I)
859      2 CONTINUE
860      RETURN
861      END
862
863      C
864      SUBROUTINE THCOND(L,LAMDA,PSI,THETA,KL,THET11,P11,N11)
865      IMPLICIT REAL*8(A-H,O-Z)
866      DIMENSION LAMDA(KL),PSI(KL),THETA(KL),THET11(N11),P11(4,N11)
867      REAL*8 LAMDA
868      NR=N11-1
869      CALL SPLINE(NR,THET11,P11,N11)
870      CALL CALCCF(NR,THET11,P11,N11)
871      DO 63 I=2,L
872      X=THETA(I)
873      63 LAMDA(I)=PCUBIC(X,NR,THET11,P11,N11)
874      RETURN
875      END
876
877      C
878      SUBROUTINE DAWCF(T,L,DAW,N9,T9,P9,KL)
879      IMPLICIT REAL*8(A-H,O-Z)
880      DIMENSION T9(N9),P9(4,N9),DAW(KL),T(KL)
881      NR=N9-1
882      CALL SPLINE(NR,T9,P9,N9)
883      CALL CALCCF(NR,T9,P9,N9)
884      DO 63 I=2,L
885      X=T(I)
886      63 DAW(I)=PCUBIC(X,NR,T9,P9,N9)
887      RETURN
888      END
889
890      C
891      SUBROUTINE KSPLN(THETA,K,N5,THETAS,P5,L,PSI,T,MI,RO)
892      T1,T2,P1,P2,N1,N2,KL,KSAT)
893      IMPLICIT REAL*8(A-H,O-Z)
894      DIMENSION THETAS(N5),P5(4,N5),THETA(KL),K(KL),PSI(KL),MI(KL)
895      T1(N1),T2(N2),P1(4,N1),P2(4,N2),T(KL),RO(KL),KSAT(KL)
896      REAL*8 K,MI,KSAT
897      NR=N5-1
898      CALL DENS(T,L,RO,N1,T1,P1,KL)
899      CALL VISCO(T,L,MI,N2,T2,P2,KL)
900      59 CALL SPLINE(NR,THETAS,P5,N5)
901      CALL CALCCF(NR,THETAS,P5,N5)
902      DO 63 I=2,L
903      62 IF (PSI(I).GE.0.000) GO TO 64
904      X=THETA(I)
905      K(I)=PCUBIC(X,NR,THETAS,P5,N5)
906      C--- TEMPERATURE ADJUSTMENT OF K-UNSAT BASED ON TREF=20C
907      60 IF (DABS(T(I)-20.000).GE.1.000) K(I)=K(I)*36.1367D0*RO(I)/MI(I)
908      GO TO 63
909      64 K(I)=KSAT(I)
910      63 CONTINUE
911      65 RETURN
912      END

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#### E5 Sample Input Data and Output Results

A sample input data to the present simulation program follows; also a sample output data using these input data.





121	0.	1-00738
122	5.	1-00768
123	10.	1-001-3
124	15.	-99776
125	20.	-99803
126	25.	-99828
127	30.	-99852
128	35.	-99795
129	40.	-99808
130	45.	-99826
131	0.	0
132	5.	6-22841
133	10.	0-59140
134	15.	12-51863
135	20.	17-30036
136	25.	23-63451
137	30.	32-29627
138	35.	43-26825
139	40.	57-38710
140	45.	75-22936
141	0.	97-74119
142	5.	5-03
143	10.	597-3
144	15.	598-5
145	20.	591-7
146	25.	508-9
147	30.	546-0
148	35.	503-2
149	40.	540-4
150	45.	577-6
151	0.	574-7
152	5.	571-9
153	10.	-0-57
154	15.	68-312
155	20.	58-684
156	25.	87-852
157	30.	81-008
158	35.	36-872
159	40.	32-040
160	45.	28-892
161	0.	25-884
162	5.	23-512
163	10.	21-467
164	15.	-0-383
165	20.	-03567
166	25.	3-000-12
167	30.	-03190
168	35.	5-100-12
169	40.	-04000
170	45.	2-510-11
171	0.	-04200
172	5.	6-710-11
173	10.	-04800
174	15.	2-010-10
175	20.	-04510
176	25.	3-100-10
177	30.	-04600
178	35.	6-170-10
179	40.	-04800
180	45.	1-680-09
181	0.	-04961
182	5.	3-600-04
183	10.	-05200
184	15.	1-260-04
185	20.	-05171
186	25.	3-400-04
187	30.	-05600
188	35.	0-220-06
189	40.	-04824
190	45.	2-520-07
191	0.	-04008
192	5.	4-200-07
193	10.	-04200
194	15.	1-260-04
195	20.	-08200
196	25.	3-080-06
197	30.	-05061
198	35.	4-300-06
199	40.	-05061
200	45.	1-980-05
201	0.	-11193
202	5.	0-130-05
203	10.	-12751
204	15.	1-920-04
205	20.	-13981
206	25.	3-480-04
207	30.	-18924
208	35.	5-400-04
209	40.	-17507
210	45.	1-560-03
211	0.	-19065
212	5.	3-000-03
213	10.	-21771
214	15.	7-590-03
215	20.	-23206
216	25.	1-740-02
217	30.	-25707
218	35.	3-300-02
219	40.	-27798
220	45.	7-400-02
221	0.	-29520
222	5.	1-650-01
223	10.	-31857
224	15.	5-250-01
225	20.	-22400
226	25.	0-420-01
227	30.	-33784
228	35.	1-200-00
229	40.	-35400
230	45.	1-510-00
231	0.	-36941
232	5.	1-800-00
233	10.	-39186
234	15.	2-200-00
235	20.	-40467
236	25.	4-500-00
237	30.	-41040
238	35.	4-000-00
239	40.	0.
240	45.	0.

--Line 0137: WZAO(5,2222) (T0(1),P0(1),I1,I=1,M0),P0(2,1),P6(2,26)

--Line 0138: WZAO(5,2222) (T7(1),P7(1),I1,I=1,M7),P7(2,1),P7(2,M7)

--Line 0139: WZAO(5,2222) (T3(1),P3(1),I1,I=1,M3),P3(2,1),P3(2,M3)

--Line 0141: WZAO(5,2222) (T2(1),P2(1),I1,I=1,M2),P2(2,1),P2(2,M2)

--Line 0142: WZAO(5,2225) (T0(1),P0(1),I=1,M5),P0(2,1),P5(2,M5)

Sample Output Data

- 1 SURFACE TEMPERATURE(DEG.C) 27.34667
- 2 SURFACE TEMPERATURE(DMG.C) 27.87003
- 3 SURFACE TEMPERATURE(DEG.C) 28.37800
- 4 SURFACE TEMPERATURE(DEG.C) 28.85573
- 5 SURFACE TEMPERATURE(DEG.C) 29.31255
- 6 SURFACE TEMPERATURE(DEG.C) 29.78150
- 7 SURFACE TEMPERATURE(DEG.C) 30.18138

LISTING OF FBI: 11 CONDITIONS

INCORRECT	POSITION (CM)	PSE (CM H2O)	MOISTURE CONVERT(VNSTA) (DM.)	TEMPERATURE (DEG.C)
1	0.000000	-3000.000000	0.05623918	27.3466698
2	17.000000	-6000.000000	0.07581000	28.7000000
3	36.000000	-2000.000000	0.07832848	27.8000000
4	50.000000	-2000.000000	0.08071805	21.0000000
5	68.000000	-1800.000000	0.08354627	20.0000000
6	84.000000	-1400.000000	0.08709940	19.5000000
7	104.000000	-1200.000000	0.09117115	19.5000000
8	120.000000	-1000.000000	0.09585952	17.7000000
9	140.000000	-800.000000	0.10177344	16.7000000
10	160.000000	-600.000000	0.11522544	16.1000000
11	180.000000	-400.000000	0.12174000	15.5000000
12	200.000000	-300.000000	0.12800000	15.0000000
13	220.000000	-200.000000	0.13200000	14.5000000
14	240.000000	-150.000000	0.14218191	14.2000000
15	260.000000	-100.000000	0.15252167	13.8000000
16	280.000000	-50.000000	0.16497803	13.4000000
17	300.000000	0.000000	0.18000000	13.0000000
18	320.000000	200.000000	0.20000000	12.5000000
19	340.000000	400.000000	0.22000000	12.0000000
20	360.000000	600.000000	0.24000000	11.5000000
21	380.000000	800.000000	0.26000000	11.0000000
22	400.000000	1000.000000	0.28000000	10.5000000
23	420.000000	1200.000000	0.30000000	10.0000000
24	440.000000	1400.000000	0.32000000	9.5000000
25	460.000000	1600.000000	0.34000000	9.0000000
26	480.000000	1800.000000	0.36000000	8.5000000
27	500.000000	2000.000000	0.38000000	8.0000000
28	520.000000	2200.000000	0.40000000	7.5000000
29	540.000000	2400.000000	0.42000000	7.0000000
30	560.000000	2600.000000	0.44000000	6.5000000
31	580.000000	2800.000000	0.46000000	6.0000000
32	600.000000	3000.000000	0.48000000	5.5000000
33	620.000000	3200.000000	0.50000000	5.0000000
34	640.000000	3400.000000	0.52000000	4.5000000
35	660.000000	3600.000000	0.54000000	4.0000000
36	680.000000	3800.000000	0.56000000	3.5000000
37	700.000000	4000.000000	0.58000000	3.0000000
38	720.000000	4200.000000	0.60000000	2.5000000
39	740.000000	4400.000000	0.62000000	2.0000000
40	760.000000	4600.000000	0.64000000	1.5000000
41	780.000000	4800.000000	0.66000000	1.0000000
42	800.000000	5000.000000	0.68000000	0.5000000
43	820.000000	5200.000000	0.70000000	0.0000000
44	840.000000	5400.000000	0.72000000	-0.5000000
45	860.000000	5600.000000	0.74000000	-1.0000000
46	880.000000	5800.000000	0.76000000	-1.5000000
47	900.000000	6000.000000	0.78000000	-2.0000000
48	920.000000	6200.000000	0.80000000	-2.5000000
49	940.000000	6400.000000	0.82000000	-3.0000000
50	960.000000	6600.000000	0.84000000	-3.5000000



DT	DTF	D	LARGA	DRSEV	DPSI	OTAP
2	0-5568710-01	0-5251540-03	0-3154030-05	0-8657410-09	0-1151740-04	0-1965690-23
3	0-7516550-01	0-4940450-03	0-2440360-05	0-4176710-08	0-6917540-05	0-1304540-03
4	0-7723390-01	0-6619140-03	0-2040600-05	0-1733710-08	0-7901190-05	0-2076540-03
5	0-7930110-01	0-5394960-03	0-2050040-05	0-1512970-08	0-8037720-05	0-5070700-04
6	0-8019100-01	0-5070040-03	0-1928640-05	0-1304540-08	0-8630600-05	0-2273200-04
7	0-8151200-01	0-4814240-03	0-1420840-05	0-3112110-08	0-1196710-04	0-3581300-04
8	0-8611800-01	0-4530710-03	0-1734440-05	0-2542680-08	0-1494530-04	0-2924690-24
9	0-9140100-01	0-4340830-03	0-1538940-05	0-2101420-08	0-1797710-04	0-2718120-04
10	0-9596340-01	0-5231140-03	0-1379180-05	0-2292150-08	0-2740210-04	0-2412690-04
11	0-101393	0-5308230-03	0-4035600-05	0-2041500-08	0-3049560-04	0-1645870-04
12	0-107800	0-6002160-03	0-1460090-05	0-2846150-08	0-3049560-04	0-1645870-04
13	0-115261	0-4612120-03	0-3751300-05	0-2141110-08	0-1335060-03	0-1604700-04
14	0-120991	0-6617200-03	0-1444430-05	0-2141110-08	0-1335060-03	0-1604700-04
15	0-122359	0-8675230-03	0-1194570-05	0-2141110-08	0-1335060-03	0-1604700-04
16	0-122730	0-1019410-03	0-1206860-05	0-2070440-08	0-1693480-04	0-1304540-08
17	0-165314	0-1224570-03	0-1109120-05	0-2101420-08	0-1693480-04	0-1304540-08
18	0-181015	0-1711860-03	0-1109120-05	0-1914440-08	0-1693480-04	0-1304540-08
19	0-206684	0-2080120-03	0-1067500-05	0-1811240-08	0-1693480-04	0-1304540-08
20	0-274008	0-2040870-03	0-9708450-06	0-1181940-08	0-1693480-04	0-1304540-08
21	0-277725	0-197407	0-1276970-03	0-1181940-08	0-1693480-04	0-1304540-08
22	0-360003	0-312446	0-1276970-03	0-775370-09	0-663789	0-6740500-05
23	0-372470	0-296695	0-7807410-08	0-8914360-09	1-28429	0-9767700-06
24	0-394693	0-258816	0-5914030-04	0-170740-09	1-53580	0-9877200-06
25	0-404767	0-172771	0-4145170-04	0-2598160-09	1-79228	0-6660880-06
26	0-409997	0-2424420-04	0-1514150-04	0-1520240-09	1-79136	0-4871160-06
27	0-410000	0-8101740-05	0-3045480-07	0-5185330-10	2-01504	0-1582920-04
28	0-410000	0-8128740-06	0-1524130-10	0-2579390-13	2-37324	0-7601920-10
29	0-410000	0-000000	0-000000	0-000000	1-25640	0-600000
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32	0-410000	0-000000	0-000000	0-000000	1-25640	0-600000
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7 LOWT...