1 Identifying non-invasible habitats for marine copepods using temperature-

2 dependent **R**₀

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8

9 Abstract

10 If a non-indigenous species is to thrive and become invasive it must first 11 persist under its new set of environmental conditions. Net reproductive rate (R_0) 12 represents the average number of female offspring produced by a female over its 13 lifetime, and has been used as a metric of population persistence. We modeled R_0 as a 14 function of ambient water temperature (T) for the invasive marine calanoid copepod 15 Pseudodiaptomus marinus, which was introduced to west coast of North America 16 from East Asia by ship ballast water. The model was based on temperature-dependent 17 stage-structured population dynamics given by a system of ordinary differential 18 equations. We proposed a methodology to identify habitats that are non-invasible for 19 *P. marinus* using the threshold of $R_0(T) < 1$ to identify potentially invasible habitats. 20 We parameterized the model using published data on P. marinus and applied $R_0(T)$ to 21 identify the range of non-invasible habitats in a global scale based on sea surface 22 temperature data. Model predictions matched field evidence of species occurrence 23 well.

24 Keywords

Net reproductive rate, invasive species, marine copepods, *Pseudodiaptomus marinus*, temperature, stage-structured population models, ordinary differential
 equations, ecological modeling, habitat invasibility, habitat suitability

1 Introduction

2

3 Assessment of habitat invasibility often relies on statistical matching of the 4 external environmental variables in native and novel habitats via methods such as 5 ecological niche modeling (ENM) (Jeschke and Strayer 2008; Mercado-Silva et al. 6 2006). However, it is often the case that invasive species can tolerate environmental 7 conditions in novel habitats that are outside those found in their native habitats 8 (Broennimann et al. 2007; Elith and Leathwick 2009). This indicates that the absence 9 of a species in particular environments may not necessarily mean such environments 10 are unsuitable for the species. As an alternative to ENM, we can determine the 11 response of potential invaders to specific environmental conditions under controlled 12 laboratory settings. For example, we can measure the rates of mortality, offspring 13 production, and stage durations under different environmental conditions. However, 14 we must still translate these measures into a habitat invasibility indicator or metric. 15 Will a population persist and grow under a given set of environmental conditions? 16 To answer this question we can use the net reproductive rate R_0 of a population as a 17 metric. R_0 is a measure of a population's reproductive success (Ackleha and de-18 Leenheerb 2008), and therefore, is a population fitness trait, which represents the 19 average number of offspring produced by a female over its lifetime (de-Camino-Beck 20 and Lewis 2008). It has been used in evolutionary invasion analysis to predict long 21 term evolutionary outcomes (Hurford et al. 2010). When $R_0>1$, a population grows, 22 and when $R_0 < 1$, a population tends to decrease to extinction (Boldin 2006). Thus, we 23 can use R_0 to decide which habitats are suitable or unsuitable for a species by 24 determining whether environmental parameters result in $R_0 > 1$ or $R_0 < 1$. We derived R_0 25 from a mechanistic state-structured population model given by a system of ordinary 26 differential equations and parameterized by data from laboratory experiments. This 27 method allows us to predict the range of habitats that are non-invasible or potentially 28 invasible for a species or strain.

29 Our model species, *Pseudodiaptomus marinus*, is an invasive marine calanoid 30 copepod that was introduced to the Pacific coast of North America (Fleminger and

1 Kramer 1998) and coastal waters in Southern Chile from its native habitat in East 2 Asia via ballast water (Bollens et al. 2002). It is a perennial egg-carrying calanoid 3 copepod, spawns continuously throughout the year, and has multiple overlapping 4 generations (Uye et al. 1983). Its life-history traits such as fertility, mortality and 5 maturation rates are known to be functions of temperature (Liang and Uye 1997a; Uye 6 et al. 1983). P. marinus has also been reported in many other oceanic habitats around 7 the world (Marine Planktonic Database) and has been expanding its range (Jiménez-8 Pérez and Castro-Longoria 2006). Despite high propagule pressure, P. marinus has 9 not been reported in the coastal ecosystems of Oregon and Washington (Cordell et al. 10 2009), or Vancouver Harbour (Piercey et al. 2000), indicating that it may be a 11 successful invader only in selected habitats. It has not been clear what environmental 12 factors limit its geographical distribution in terms of its physiological tolerance.

Here we modeled R_0 of *P. marinus* as a function of temperature assuming continuous time stage-structured population dynamics of the species based on a system of linear first order ordinary differential equations (ODEs). ODE transmission models in epidemiology literature are commonly evaluated using R_0 , although it is less commonly used in stage-structured life-history dynamics. We parameterized the model using previously published data from laboratory experiments and field surveys (Liang and Uye 1997a; Uye et al. 1983).

20 The R_0 -based approach to determining habitat invasibility, while appealing, is 21 necessarily limited by the range of environmental conditions under which the 22 laboratory experiments can produce parameters. When R_0 is calculated using model 23 parameters that were estimated for a limited range of primary environmental variables 24 (e.g. temperature only), with other secondary environmental variables (e.g. salinity, 25 daylight levels) held at optimal levels in the laboratory, results are not likely to be 26 representative of what the species experiences in the field. In these cases, however, it 27 is possible to use the R_0 -based approach to identify which habitats are non-invasible. 28 If $R_0 < 1$ when secondary variables are optimal it also should remain below one when 29 secondary variables are suboptimal. In this way we can identify temperature (T)30 thresholds for invasibility of the marine copepod P. marinus using $R_0(T)$.

1 The method we develop yields $R_0(T)$ as a function of temperature, allowing us 2 to predict the range of temperatures that inhibit the growth of *P. marinus*, and thereby 3 to predict the range of habitats that are potentially invasible to *P. marinus*. This 4 method can be generally applied to model R_0 for other similar species. The results is 5 complimentary to ENM and has a further advantage over ENM in terms of predicting 6 species' potential spread over habitats that differ from their native habitats.

7

8 Methods

9

10 We modeled stage-structured population dynamics of P. marinus using a 11 system of first order linear ODEs assuming continuous year-round growth and 12 overlapping generations (Uye et al. 1983). We followed the methods in van den 13 Driessche and Watmough (2002) to model the net reproductive rate R_0 based on the 14 ODE model. Our model contains fertility, maturation, and mortality rate parameters. 15 Because stage based fertility, mortality, and maturation rates are temperature-16 dependent (Uye et al. 1983; Liang and Uye 1997a.), we modeled the rate parameters 17 as functions of temperature. This allowed us to calculate the temperature-dependent 18 R_0 .

19

20 Model

P. marinus has 12 life stages, consisting of eggs, five naupliar stages, five copepodid stages, and one adult stage. We do not include naupliar stage 1 in the model as data corresponding to this stage are not available due to difficulty in measurement as it lasts only few minutes (Uye et al. 1983). However, the data on naupliar stage 2 can be considered as an approximation, combining stage 1 and stage 2 into a single stage.

We define n(t) to be a vector representing the stage composition of the population at time *t*, and A(T) be a matrix of parameter space of vital rates (fertility, maturation, and mortality) that depend on temperature (*T*). Thus, we can write the rate of change of stage composition as follows:

$$\frac{dn(t)}{dt} = A(T)n(t) \tag{1}$$

3 Where,

4 $n(t) = [n_1(t), n_2(t), ..., n_{12}(t)]^T$

5

$$6 \quad A(T) = \begin{pmatrix} -\mu_1(T) - \gamma_1(T) & 0 & \vdots & 0 & q\beta(T) \\ \gamma_1(T) & -\mu_2(T) - \gamma_2(T) & \vdots & 0 & 0 \\ 0 & \gamma_2(T) & \vdots & \vdots & \vdots \\ \vdots & \vdots & & -\mu_{11}(T) - \gamma_{11}(T) & 0 \\ 0 & 0 & \vdots & \gamma_{11}(T) & -\mu_{12}(T) \end{pmatrix}$$

where, $\mu_i(T)$ and $\gamma_i(T)$, $\beta(T)$ are stage-dependent mortality, maturation, and 8 9 fertility rates respectively, which are functions of temperature. Here, n_1 represents the number of eggs, $n_2...n_6$ represents the number of individuals in the five naupliar 10 stages (excluding stage 1), $n_7...n_{12}$ represents the number of individuals in the five 11 copepodid stages, $\beta(T)$ is the fertility rate (rate of egg production) in adult females as a 12 13 functions of temperature. The constant q is the average proportion of ovigerous 14 females in the adult population, which is estimated to be 0.61 (Liang and Uye 1997b). 15 See Table 1 for all notations. We derived the net reproductive rate R_0 for *P. marinus* 16 based on the above model as described below.

17

18 R_0 as a function of temperature

19 First, we wrote the matrix *A* as A = F - V where *F* is the matrix of fertility 20 coefficients (non-negative and non-zero), and *V* is the matrix of transition coefficients 21 (i.e. net maturation and mortality rates). R_0 can then be written as $R_0 = \rho[FV^{-1}]$, 22 where ρ is the spectral radius of the matrix FV^{-1} (van den Driessche and Watmough 23 2002). That is $\rho[FV^{-1}] = \max_{1 \le i \le n} |\lambda_i|$ where $\lambda_1, \lambda_2, ..., \lambda_n$ are eigenvalues of the square 1 matrix *FV*⁻¹. Note that the intrinsic growth rate defined as the maximum real

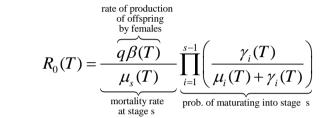
2 eigenvalue of the square matrix A has a non-linear relationship with net reproductive

3 rate R_0 (Wallinga and Lipsitch M 2007). However, the intrinsic growth rate is positive

4 if and only if $R_0 > 1$.

5 We modified the model to express R_0 as a function of temperature, such 6 that $R_0(T) = \rho[F(T)V(T)^{-1}]$. Using the graph reduction method (de-Camino-Beck

7 and Lewis 2007) (see derivation in Appendix A), we can also write R_0 as,



9 where *s* is the final stage (stage 12) for *P. marinus*. We modeled temperature
10 dependent parameters in the model as described in the next section.

11

8

12 Fertility rates $\beta(T)$

13 Eggs are produced by adult females in stage 1 (n_{11}). Fertility rate, $\beta(T)$, can be 14 written as $\beta(T) = f(T) / \Delta t$, where f(T) is the number of eggs produced by an adult 15 female over time Δt at average temperature T. Uye et al. (1983) fitted a linear model to parameterize $\beta(T)$. The linear model takes the form $\beta(T) = 0.771T - 4.48$, with 16 R^2 =0.84. Residual analyses of Uye's data, however, show that residuals are not 17 randomly distributed along the fitted line indicating that linearity may not be the 18 19 appropriate assumption. There is a depression in fertility rates at low temperatures. 20 Furthermore, the linear model assumes that fertility is unbounded with increasing 21 temperature, which is not a biologically valid assumption. We therefore refitted the 22 data with a sigmoidal curve, assuming log normally distributed errors. We 23 incorporated a lag parameter (b) to relax the assumption that the curve must otherwise 24 intercept the y-axis at the origin. The sigmoidal curve allows us to assume that 25 fertility rate has a maximum value. Biologically it is more appropriate to assume that

1 fertility rate is a bell-shaped curve, however we did not have the data to extend our

2 curve to the point were $\beta(T)$ begins to decrease at high temperatures. Hence, our

3 model for fertility rate can be written as,

4

$$\beta(T) = f_m f_l e^{w(T-b)} / [f_m + f_l (e^{w(T-b)} - 1)]$$

5 Where, f_m is the maximum rate of fertility, f_l is fertility rate at the lowest temperature, 6 and w is a shape parameter that accounts for the depression in fertility at lower 7 temperatures. We compared the regression fit of linear model used in Uye et al. (1983) 8 with our sigmoidal model using residual sum of squares.

9

10 *Maturation rates* $\gamma_i(T)$

11 We solved the system of ODE's represented by Eq.1 analytically for initial 12 values corresponding to a single individual in stage 1, $n_1(0) = 1$, and $n_i(0) = 0$ for 13 i=2,...,12. This allowed us to follow a single cohort over time with no additional 14 individuals being added to the system (Appendix B).

15 In experimental studies, maturation rates are commonly calculated using 16 median development times, or the time it takes for 50% of the cohort to mature from 17 eggs past a given stage (e.g. Uye et al. 1983, Breteler et al 1994, Lee et al. 2003.) An 18 assumption underlying such conventional calculation of maturation rate using 19 'proportions not yet past given stage' is that daily mortality rates of copepods are the 20 same across all stages for a cohort. It excludes the mortality rate parameter from the 21 equation and assumes that daily stage proportions are the result of individuals 22 maturing from one stage to another. We made the same assumption here in the 23 estimation of maturation rates from our model as P. marinus data are available only as 24 proportions of a cohort remains in each stage over time with the same assumption. 25 Thus, we normalized the stage size data $n_a(t)$ for each time step (t) dividing it by total 26 remaining population of the cohort at that time step to give the proportion at each stage $z_a(t)$. This assumption made the proportion at each stage $z_a(t)$ to be 27 28 independent from the mortality rates (Appendix C).

Using Eq.3 in Appendix C we can describe the proportion of individuals not

2 having past stage *a*, i.e.
$$\sum_{i=1}^{a} z_i(t)$$
, as,

3
$$\sum_{i=1}^{a} z_{i}(t) = 1 - \sum_{i=1}^{a} \left[\prod_{\substack{j=1\\j\neq i}}^{a} \frac{\gamma_{j}}{\gamma_{j} - \gamma_{i}} (1 - e^{-\gamma_{i}t}) \right].$$
(4)

4 As shown by Cox (1967), this equation can also be derived from assuming the 5 length of time that a copepod takes in a stage (stage duration time) as an exponentially 6 distributed random variable, d_a , such that the probability density function of d_a is $\gamma_a e^{-\gamma_a t}$ and cumulative density function of d_a is $(1 - e^{-\gamma_a t})$, where γ_a is the stage 7 maturation rate, and $\mu_a = 0$ for all stages a. The length of mean time taken to exit stage 8 *a*, i.e. stage development time, D_a , becomes a random variable defined as $D_a = \sum_{i=1}^{a} d_i$ of 9 which the cumulative density function of is $\left[1 - \sum_{i=1}^{a} z_i(t)\right]$. The quantity $\sum_{i=1}^{a} z_i(t)$, thus 10 11 yields the proportion of individuals not having past stage a. 12 We fitted stage proportion data from Uye et al. (1983) to Eq.4 using nonlinear 13 least squares regression to estimate γ_a . The data used were collected for *P. marinus* at 20[°]C. We calculated the mean stage duration times d_a as $\overline{d}_a = \frac{1}{\gamma_a}$ at 20[°]C. This 14 yielded from the fact that d_a is an exponentially distributed random variable. We then 15 used d_a calculated for 20⁰C to estimate the relationship between D_a and temperature 16 (*T*). We assumed the relationship given by Belehradek's function, $\overline{D}_a = \alpha_a (T-1)^{-1.8}$ 17 (as used by Uye et al. (1983) for *P. marinus*), where *T* is temperature in centigrade 18 and α_a is a constant that varies with stage a. Using calculated α_a , we estimated the 19 parameters for $\gamma_a(T)$ from the following equation derived from the above, 20 $\gamma_a(T) = (T-1)^{1.8} / (\alpha_a - \alpha_{a-1})$ for each stage *a* at temperatures (*T*). Here, $\alpha_0 = 0$. 21 22 As an advancement to the above model, we modified Eq.1 to assume that stage 23 duration times are gamma distributed (Breteler et al. 1994; Lee et al. 2003) to replace

1 the earlier assumption on exponentially distributed times. That is, probability density

2 function of
$$d_a$$
 now becomes $\frac{\gamma^k}{\Gamma(k)} t^{k-1} e^{-\gamma_a t}$ where, $\Gamma(k) = (k-1)!, \gamma_a > 0, k > 0$

Mathematically this can be achieved by assuming that there are sub-stages (k_a) within 3 4 each stage a in Eq.1 given that duration times of sub-stages are exponentially distributed (see MacDonald 1978 for a full description). Here we assumed that 5 6 mortality and maturation rates of sub-stages were the same for each stage. Thus the 7 number of sub-stages, k, in Eq.1 is equivalent to assuming the shape parameter k in 8 the gamma distributed stage duration times. Here we assumed k_a to be the same for 9 all stages a as previous studies suggested for copepods (e.g., Breteler et al. 1994; Lee 10 et al. 2003). The method for fitting the model with multiple sub-stages is outlined in 11 Appendix D.

12

The mean stage duration times
$$d_a$$
 become $\overline{d}_a = \frac{k_a}{\gamma_a}$ for the modified model for

13 gamma distributed d_a . We assumed k_a to be the same for all stages *a* (Breteler et al. 14 1994). Therefore

15

$$\gamma_a(T) = k(T-1)^{1.8} / (\alpha_a - \alpha_{a-1})$$
(5)

16 where $\alpha_0 = 0$. Note that the advanced model (see Appendix D through Eq.5) reduces 17 to simple model when k=1 and $\varepsilon = 0$. We compared the model fits for k=1, and k=2,318 using AIC and chi-squares test to determine which model assumption was the best to 19 estimate $\gamma_a(T)$. We used the estimated stage duration times to calculate mortality rates 20 as shown in the next section.

21

22 Mortality rates $\mu(T)$

Liang and Uye (1997a) estimated the percent survival of nine generations of
the population for *P. marinus* from the west coast of Japan under different mean
temperatures. We used these data to estimate survival curves at different temperatures.
Because of their estimation procedure, Liang and Uye reported percent
survival >100% in some cases; these values were reduced to 100%. We fitted the

1 function $Sv = \exp(-\phi a^{\chi})$ for the proportion surviving from eggs to stage *a*, where ϕ is 2 a scale parameter and χ is a shape parameter. We estimated ϕ and χ using non-3 linear least squares regression. We calculated the proportion of individuals that died 4 in each stage with respect to the proportion of individuals that matured into the 5 current stage from the previous stage using *Sv*. We refer to *Sv* as a modified Wiebull 6 function because (1-*Sv*) is the cumulative density function of the Wiebull distribution 7 (1951).

8 To obtain estimates of mortality rates $\mu_a(T)$ for each stage *a*, we divided the 9 estimated proportions that died in each stage by the stage duration times, given by $d_a = \frac{1}{\nu}$ for the exponential distributions (simple model), and $d_a = \frac{k}{\nu_a}$ for gamma 10 11 distributions (advanced model) at the same temperatures. We pooled mortality rates 12 across stages so as to be consistent with our earlier assumption (in modeling stage 13 maturation rates using experimental data) that mortality rates across all stages are the same. We fitted a quadratic function $\mu(T) = \kappa_2 T^2 + \kappa_1 T + \kappa_0$ for the pooled data 14 using nonlinear least squares regression. We did not use the survey measurement data 15 at 27.4°C in Uye et al. (1983) for above calculations as it yielded near zero daily 16 17 mortality rates at such a comparatively high temperature which resulted in a 18 biologically inexplainable pattern that contradicted the general trend, suggesting that 19 those data may be outliers.

We tested whether the assumption behind pooling data, i.e. mortality rates are the same across all stages for a given temperature (as in Breteler et al. 1994; Uye et al. 1983) is a valid assumption for this species. To do this, we used the method of positioning means within confidence intervals (Venables and Repley 2002).

24 Now we had $\beta(T)$, $\gamma_a(T)$ and $\mu(T)$ modeled exclusively as functions of 25 temperature to finally fit into $R_0(T)$ model.

26

27

$$R_0(T) = \frac{q\beta(T)}{\mu_s(T)} \prod_{i=1}^{s-1} \left(\frac{\gamma_i(T)}{\mu_i(T) + \gamma_i(T)}\right)^k$$

The model for $R_0(T)$ for any k is as follows

(6)

1 (see derivation in Appendix A). 2 3 Application and validation 4 We used the parameterized $R_0(T)$ to predict the range of habitats that are non-5 invasible to P. marinus on a global scale, based on sea surface temperature data from 6 NOAA Optimum Interpolation (OI) SST V2. The range of habitat temperatures where 7 $R_0(T) < 1$ is considered to be non-suitable for population persistence and hence non-8 invasible. We compared predictions with the known distribution of *P. marinus*. 9 10 Results 11 12 Fertility rates 13 We found that the sigmoidal model for fertility rates fits the data better than 14 the linear model (Fig.1). The residual sum of squares (RSS) for the sigmoidal model 15 was 97.37, compared to 126.08 for the linear model. Parameters for the sigmoidal 16 model were $f_m = 13.89$, $f_1 = 0.61$, w=0.35, b=6.01°C. Using the sigmoidal model, fertility 17 rates started at zero near or slightly above 0°C, and tended to reach a maximum at 18 temperatures above 25°C. Intuitively, fertility rate should peak at some optimal 19 temperature, then decrease with increasing temperatures, which our sigmoidal model 20 does not recreate. However, we are more interested in predicting dynamics at lower 21 temperatures, so the sigmoidal model is sufficient. The results indicate that sigmoidal 22 model is a better statistical approximation as well as having a theoretically better 23 rationale than the linear model. 24 25 Maturation rates 26 We estimated stage development times for cases k=1,2 and 3 in Eq.5 by fitting

27 data from Uye et al. (1983) (Fig.2). We compared the fits using AIC and found that

28 k=3 is the better statistical model than k=1,2 (Table 2). The model with k=3 gives the

29 lowest AIC (Table 2). Note that *p*-values for chi-squares goodness of fit test for k=1

30 and k=2 with respect to k=3 was <0.001. This suggests that model with k=3 is

1 significantly different from models with k=1 and k=2. Hence, we concluded that the 2 model with k=3 is the most reasonable.

3

4 *Mortality rates*

5 We estimated values of λ and α for Wiebull model for different generations at 6 different temperature regimes (Table 4). We also plotted mortality rates against temperatures based on the Wiebull model (Fig. 4) and in relation to $d_a = \frac{k}{\gamma(T)}$ at 7 8 different temperature regimes. The parameters estimated for mortality rate were $\kappa_2 = 0.0022 / \text{day}, \kappa_1 = -0.0563 / C \text{day}, \kappa_0 = 0.4211 / C^2 \text{day}$. The assumption that 9 10 mortality rates are the same across all stages was tested by examining confidence 11 intervals. The mean values of the model coefficients fall within the confidence 12 intervals of every other stage, indicating that the data can be pooled. Hence, our 13 assumption that mortality rates are the same across all stages for a given temperature 14 is valid for P. marinus. 15 16 *Net reproductive rate*

We plotted R₀(T) after incorporating the parameterized submodels β(T), γ_a(T) and μ(T) (Fig. 5). R₀(T) tends to curve downwards at high
temperatures due to increasing mortality rate (Fig.4) that suppresses the positive effect
of increasing fertility rates at higher temperatures (Fig.1).

We plotted $R_0(T)$ for the cases where k=1 and k=3 (Fig. 5). Relatively higher 21 22 values of $R_0(T)$ for higher k suggest that the fitness of the population is reduced when 23 k is low regardless of the temperature. The model $R_0(T)$ that best fits data was the one 24 with parameter k=3. The uncertainty associated with the estimates of $R_0(T)$ can not be 25 calculated because parameters taken from the literature did not have confidence estimates (Uye et al (1983) and Liang and Uye (1997a)). We found that $R_0 > 1$ 26 between 11° C and 23° C, and this is therefore the range within which the habitats are 27 28 potentially invasible. If other conditions in a habitat are ideal and temperature falls within this range, species could grow. At temperatures $<11^{\circ}$ C and $>23^{\circ}$ C, $R_{0}<1$ and 29

1 habitats with these mean temperatures are non-invasible. If a habitat's temperature

- 2 fluctuates seasonally between these two limits, it is tolerable to *P. marinus*.
- 3

4 Application and validation

5 We mapped the range of habitats where yearly averaged sea surface 6 temperatures is between 11° C and 23° C (colored contours in Fig 6) where they are 7 potentially invasible to *P. marinus*. Hence, the area where there are no contour lines 8 (23° C <T<11^{\circ}C) indicate the habitats where *P. marinus* is non-invasible. Field 9 sampling evidence depicted in Fig (6) suggests that our predictions fit well into 10 potentially invasible habitat range except for marginal deviations of few occurrences.

11

12 **Discussion**

13

14 Here we proposed a novel methodology to model net reproductive rate R_0 , 15 which is a population persistence metric, as a function of temperature (T) for invasive 16 marine copepod P. marinus based on the data from experiments. This approach can be 17 generally applied to model R_{θ} for aquatic copepods that respond to environmental 18 parameters markedly, reproduce year-round, and have multiple overlapping 19 generations (species for e.g. as in Bonnet et al. 2009; Chen et al. 2006). Temperatures 20 giving $R_0(T) > 1$ indicate habitats where the species can physiologically persist, 21 assuming that other environmental factors are suitable for its growth. Temperatures 22 resulting $R_0(T) < 1$ indicate habitats where that the species cannot physiologically 23 persist regardless of the other environmental factors. Thus, our approach can 24 conservatively predict habitats which are non-invasible, and thereby habitats which 25 are potentially invasible. Note that we have not incorporated confidence intervals in 26 the estimates due to unavailability of primary data to incorporate that.

The habitats that are potentially invasible to *P. marinus* as predicted by our model matched well with field evidence of species occurrences on a global scale except for few marginal deviations (miss-matches) on the borders limiting $R_0(T)=1$. In particular, we note that from Fig 6, Elliot bay, Puget Sound is on the border of non-

1 invasibility range limiting $R_0(T)$. It has been recorded in U.S Geological Surveys that 2 P. marinus has been sampled in that location by Cohen (2004). However, up to now, 3 there has been any indication that it has established in that location. Further 4 northwards, Piercey et al. (2000) found that there was a large propagule pressure of P. marinus on Vancouver harbor (in 25.4% ships sampled, and occurring in densities 5 6 from $2 \sim 54 \text{m}^{-3}$). Our model predicts that Vancouver harbor is also located on the 7 border where $R_0(T)=1$. We note that on the above locations, temperatures fluctuate 8 seasonally throughout the year (Lighthouse sea surface temperature data, DFO 9 Canada). To better predict non-invasibility in such habitats we need a model that 10 incorporates the effect of seasonal variation of temperatures.

Furthermore, had we incorporated the survival data at 27 0 C, then the upper bound of R₀(T)=1 would have shifted towards higher temperatures moving the potentially invasible range towards the tropics. We did not incorporate those data as they were inconsistent with the general trend in mortality rates with respect to increasing temperatures and did not make sense biologically, as outlined in the methods section.

17 The methodological basis adopted here in determining non-invasible habitats 18 is in contrast to that of ENM (Peterson 2003). ENM predicts habitat-suitability based 19 on a snapshot of environmental conditions and species occurrences (Herborg et al. 20 2007a; Peterson et al. 2007) by matching the range of environmental variables in 21 native habitats with that in novel habitats (Jeschke and Strayer 2008; Mercado-Silva 22 et al. 2006). For e.g. Genetic Algorithm for Rule-set Prediction (GARP) (Stockwell 23 and Peters 1999) in ENM has been commonly used to predict habitat suitability for 24 both terrestrial and aquatic invasive species (e.g. Herborg et al. 2007a; 2007b; 25 Peterson 2003; Peterson et al. 2007). The above methodology implicitly assumes that 26 the limit to phenotypic plasticity of population fitness traits is exhaustively 27 represented in the observed environmental set in their native habitats. This, in turn, 28 assumes that a species may only survive and reproduce in habitats those having 29 environmental sets similar to that in their native ranges. Often, species tolerate 30 environmental set beyond that is found in native habitats (Lockwood et al. 2006). For 1 example, a species distribution may be confined to a certain native range due to 2 natural barriers rather than environmental parameters (Lonhart 2009) suggesting that 3 absence is not necessarily indicative of a habitat's suitability. In such cases, ENM 4 may not be able to fully capture the potential range of the environmental set that a 5 species may tolerate. For this reason, ENM can overlook habitats where a species can 6 potentially survive and reproduce, especially in cases where human-mediated 7 transport may facilitate jump dispersal (e.g. Broennimann et al. 2007). Our approach 8 avoids this particular limitation of ENM.

9 Our model is designed to quantify R_0 at low introductory populations to 10 determine the species establishment potential. Hence, we did not explicitly account 11 for density dependence of the population considering high population levels. Further, 12 we disregarded Allee effects (Taylor and Hasting 2005; Courchamp et al. 2008; 13 Kramer et al. 2008) although it may be a factor that acts against species establishment 14 at low population levels (Lockwood et al. 2005; Whitmann et al., accepted). In such 15 cases it is possible to have a *backward bifurcation*, where a species can persist even 16 when $R_0 < 1$, and hence a different approach would be needed to analyze populations 17 with Allee effects. Biologically, inclusion of the Allee effect may further filter out a 18 subset of non-invasible habitats from potentially invasible habitats. This will 19 complement our predictions which were made without the case of Allee effect.

20 Sea surface temperature has been rising over the last few decades (Cane et al. 21 1997). Our model can be used as a tool to determine how climate change may affect 22 species range expansion. For *P. marinus*, the shape of $R_0(T)$ curve suggests that with 23 increases in sea temperature, ranges may tend to shift towards currently cooler waters. 24 However, the effect of climate change on seasonal changes in sea surface temperature 25 may also be a critical factor in determining long term effects on niche shifts. For 26 example, temperature data from Racerock, B.C., spanning the years 1921-2008, 27 indicates that annual low temperatures have not increased as much as annual high 28 temperatures. The impact of such non-linear increases in temperatures may have non-29 linear effects on R_0 . Hence, we may not be able to rescale the range of R_0 by simply 30 adding the expected increment to mean sea surface temperature.

1 A proxy of using mean temperatures to characterize a habitat is appropriate in 2 cases where temperature forces R_0 to be either strictly less than 1 or greater than 1. 3 Hence, our result is only applicable to habitats where all seasonal temperatures, were 4 they held constant or averaged, would force $R_0(T)$ to be greater than 1 or less than 1 5 throughout years. However, in habitats where temperatures fluctuate seasonally, or 6 daily, forcing $R_0(T) > 1$ in one period, and $R_0(T) < 1$ in another period, we cannot make 7 clear predictions on habitat invasibility by metric $R_0(T)$ alone. Yet, we could presume 8 that a habitat to be more unfavorable to a species when the seasonal fluctuations of a 9 factor forces $R_0 < 1$ in longer period of the year, and *vice-versa*. It may be useful to 10 incorporate the effects of short term and seasonal temperature fluctuations on R_0 (see 11 Bacaeer 2009; Bacaeer and Ouifki 2007, Wesley and Allen 2009).

12 An extension to our model would be to incorporate vital rates as functions of 13 other environmental factors such as salinity. We can then calculate R_0 in a two-14 dimensional environmental space. It may increase the non-invasible habitat set for the 15 species reducing the potentially invasible habitat set. Recent work towards modeling 16 the combined effect of temperature and salinity on population persistence is found in 17 Strasser et al. (in press).

18

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20

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28 29

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Appendix A: Deriving R₀ from graph theoretic method

2

3 Following the method given in de-Camino-Beck et al. (2008), here we have a real 12x12 matrix $(F\lambda^{-1} - V) = a_{ii}$ after decomposing matrix A from Eq.1 into matrices 4 F, fertility, and V, transition. Hence, for matrix $(F\lambda^{-1} - V)$, there corresponds a 5 labeled directed graph, $D(F\lambda^{-1} - V)$, with nodes 1,2,...,12, and a directed edge (arc) 6 j→i. The weight of this arc is a_{ij} , and $D(F\lambda^{-1} - V)$ has a loop at node i of weight a_{ij} if 7 $a_{ii} \neq 0$. Thus, we can draw the diagraph, $D(F\lambda^{-1} - V)$, as follows. 8 9 10 -γ₁ -γ11 11 $-(\gamma_1 + \mu_1)$ n_1 n₁₀ n₁₁ n₁₂ n_2 n₃ $-\mu_{12}$ 12 13 $(\gamma_{10} + \mu_{10})$ $-(\gamma_2 + \mu_2)$ $(\gamma_3 + \mu_3)$ $-(\gamma_{11}+\mu_{11})$ 14 $q\beta\lambda^{-1}$ 15

16 We created trivial nodes using graph reduction Rule 1 in de-Camino-Beck et al. (2008) 17 by reducing the loops $-a_{ii} < 0$ to -1 at node i's, for every arc entering i divided by 18 weight a_{ii}. Thus the diagraph will be reduced to the following.

 $-\gamma_{10}$

 $-\gamma_{11}$

19

20

21

22

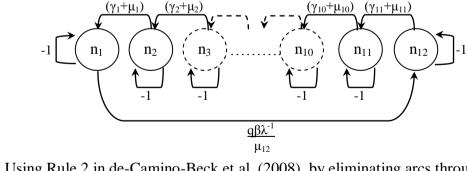
23

24

25



-γ₁



26 Using Rule 2 in de-Camino-Beck et al. (2008), by eliminating arcs through trivial nodes, here we replaced two arcs at a time by $j \rightarrow k$ with weights equal to the product 27 28 of weights on arc $j \rightarrow i$ and $i \rightarrow k$, for trivial nodes i on a path $j \rightarrow i \rightarrow k$. Thus, it finally 29 yields the following diagraph with a single node.

$$-1 + \frac{q\beta}{\mu_{12}} \prod_{i=1}^{11} \left(\frac{\gamma_i}{\gamma_i + \mu_i}\right) \lambda^{-1} (n_{12})$$

6

4 Finally, we set the weight of this loop to zero giving and equation of lambda. The

5 smallest positive roots of this equation yielded R₀.

$$R_0 = \frac{q\beta}{\mu_{12}} \prod_{i=1}^{11} \left(\frac{\gamma_i}{\gamma_i + \mu_i} \right)$$

Furthermore, when there are 2 sub stages in each stage (that is k=2), the initial graph 7 8 is given as follows:

-γ11

-γ₁₁

 n_{12}

-1

 $(\gamma_{11}+\mu_{11}) (\gamma_{11}+\mu_{11})$

¥

 n_{11}

-1

9



-γ1 $-\gamma_{12}$ -γ₁ - Y11 11 n_1 n₁₂ n₁₂ n_1 n₁₁ n_2 $-\mu_{12}$ $-(\gamma_1 + \mu_1)$ 12 13 $(\gamma_2 + \mu_2)$ $-(\gamma_1 \overline{+\mu_1})$ $_{12}+\mu_{12})$ $-(\gamma_1 + \mu_1)$ 14 $q\beta\lambda^{-1}$ 15 $q\beta\lambda^{-1}$ 16

17 Using Rule 1, this can be reduced as follows.

-γ1

 $(\gamma_1 + \mu_1)$

 n_1

-γ1

 $(\gamma_1 + \mu_1)$

 n_2

 $(\gamma_2 + \mu_2)$

18

19

20

21

22

23

24

24
25
26

$$\left(\frac{q\beta\lambda^{-1}\gamma_{12}}{\mu_{12}} + q\beta\lambda^{-1}\right)\frac{1}{(\gamma_{12} + \mu_{12})} = \frac{q\beta\lambda^{-1}}{\mu_{12}}$$

 n_1

-1

It finally yields, 27

1
$$-1 + \frac{q\beta}{\mu_{12}} \prod_{i=1}^{11} \left(\frac{\gamma_i}{\gamma_i + \mu_i}\right)^2 \lambda^{-1} \quad \boxed{\mathbf{n}_{12}}$$

2 Thus,
$$R_0 = \frac{q\beta}{\mu_{12}} \prod_{i=1}^{11} \left(\frac{\gamma_i}{\gamma_i + \mu_i}\right)^2$$

3 Similarly, for any k sub stages, it yields, $R_0 = \frac{q\beta}{\mu_{12}} \prod_{i=1}^{11} \left(\frac{\gamma_i}{\gamma_i + \mu_i}\right)^k$

4 The same result can be easily derived from $R_0 = \rho [FV^{-1}]$ also.

5

6 Appendix B: General solution for $n_a(t)$

7

8

9

We obtained the following general solution for $n_a(t)$, the proportion of individuals in a given stage *a* at time *t* in Eq.1:

10
$$n_{a}(t) = \left(\prod_{i=1}^{a-1} \gamma_{i}\right) (\underline{b}_{a} \cdot \underline{v}_{a}) \quad \text{for a>1};$$
(2)
11
$$n_{1}(t) = e^{-\sigma_{1}t} \gamma_{1} \quad \text{for a=1} ;$$

12 where, $\sigma_i = (\gamma_i + \mu_i)$ such that $\gamma_i > 0$ and $\mu_i > 0$ for any stage *i* and $\sigma_{ij} = (\sigma_i - \sigma_j)$, and

13 \underline{b}_a is a row vector of dimension 1x(*a*-1) of the form $\underline{b}_a = \prod_{j=1}^{a} B_j$, j=1,...,*a*, where, B_j

14 matrices are non-square matrices such that, $B_1 = 1$, $B_2 = \sigma_{21}^{-1}$, $B_3 = \begin{bmatrix} \sigma_{31}^{-1} & -\sigma_{32}^{-1} \end{bmatrix}$,

15
$$B_4 = \begin{bmatrix} \sigma_{41}^{-1} & 0 & \sigma_{43}^{-1} \\ 0 & \sigma_{42}^{-1} & \sigma_{43}^{-1} \end{bmatrix}$$
, $B_5 = \begin{bmatrix} \sigma_{51}^{-1} & 0 & 0 & \sigma_{54}^{-1} \\ 0 & \sigma_{52}^{-1} & 0 & \sigma_{54}^{-1} \\ 0 & 0 & \sigma_{53}^{-1} & \sigma_{54}^{-1} \end{bmatrix}$, and so on. The general formula for B_k

16 $(k \ge 3)$ can be written as,

17
$$B_{k} = \begin{bmatrix} \sigma_{k1}^{-1} & 0 & : & 0 & 0 & \sigma_{kk-1}^{-1} \\ 0 & \sigma_{k2}^{-1} & : & 0 & 0 & \sigma_{kk-1}^{-1} \\ : & : & : & : & : & : \\ 0 & 0 & : & \sigma_{kk-3}^{-1} & 0 & \sigma_{kk-1}^{-1} \\ 0 & 0 & : & 0 & \sigma_{kk-2}^{-1} & \sigma_{kk-1}^{-1} \end{bmatrix}_{(k-2)\times(k-1)}$$

- 1 Note that due to the dimensions of the B_j matrices, the product $\underline{b}_a = \prod_{j=1}^{a} B_j$ is a vector.
- 2 We define the vector \underline{v}_a to be a column vector of the form,
- 3 $\underline{\nu}_{a} = \begin{bmatrix} e^{-\sigma_{1}t} e^{-\sigma_{a}t} \\ e^{-\sigma_{2}t} e^{-\sigma_{a}t} \\ e^{-\sigma_{3}t} e^{-\sigma_{a}t} \\ \vdots \\ e^{-\sigma_{a-1}t} e^{-\sigma_{a}t} \end{bmatrix}_{(a-1)x1}$
- 4

5 Appendix C: Analysis of the case with constant mortality amongst stages

6

7 To see that the assumption of equal mortality at each stage cased the mortality 8 rates in Eq. 2 to cancel out mathematically, consider the case where each μ_i is a 9 constant μ in our solution Eq.2. Then note that in Eq.2, σ_{ii} becomes independent of μ , and as a result \underline{b}_a also becomes independent of μ . Further, in \underline{v}_a , $(e^{-\sigma_i t} - e^{-\sigma_a t})$ 10 can be written as $e^{-\mu t} (e^{-\gamma_i t} - e^{-\gamma_a t})$ for each element *i*. Thus, in the dot product 11 $(\underline{b}_a.\underline{v}_a)$ in the Eq.2, the term $e^{-\mu t}$ can be separated out as a multiplier, and after 12 redefining, $n_a(t) = e^{-\mu t} \left(\prod_{i=1}^{a-1} \gamma_i \right) (\underline{\bar{b}}_a . \underline{\bar{\nu}}_a)$, such that term $\left(\prod_{i=1}^{a-1} \gamma_i \right) (\underline{\bar{b}}_a . \underline{\bar{\nu}}_a)$ becomes 13 independent of μ . i.e. $\underline{b}_a = \underline{b}_a$ and $\underline{v}_a = \underline{v}_a$ for the special case where $\mu_i = 0$ for all 14 15 stages *i*. Now, we can write the proportion of each stage *a* that remains at time *t*, $z_a(t)$, with respect to the total population at t: 16 $z_a(t) = n_a(t) / \sum_{i=1}^{s} n_i(t) = \left(\prod_{i=1}^{a-1} \gamma_i\right) (\underline{\bar{b}}_a \cdot \underline{\bar{\nu}}_a) / \sum_{i=1}^{s} \left(\prod_{i=1}^{j-1} \gamma_i\right) (\underline{\bar{b}}_j \cdot \underline{\bar{\nu}}_j)$ 17

18 where, *s* is number of stages. Thus, this equation is independent of μ . The numerator 19 of this equation is $n_a(t)$ for the case where $\mu_i = 0$ for all stages for any *t*. The

20 denominator is the solution to
$$\sum_{i=1}^{s} n_i(t)$$
 for the special case where $\mu_i = 0$ for all stages

at any *t* if the population starts from 1 egg, thus remains 1 at any *t*. Hence, this can be
simplified, so that,

$$z_a(t) = \left(\prod_{i=1}^{a-1} \gamma_i\right) \underline{\bar{b}}_a \cdot \underline{\bar{\nu}}_a$$
(3)

which, is equivalent to z_a(t) = n_a(t) when μ_i = 0 for all stages at any t. Therefore,
z_a(t) can be equated with the stage sizes normalized at each time step t in
experimental data found in the literature which makes the assumption that μ_i = μ for
all *i*=1 to s.

8

3

9 Appendix D: Fitting Eq. 4 data using multiple substages

10

11 To derive solution to the modified system of equations in Eq.1 by adding k12 sub-stages to each stage required using Laplace transformations. It yielded a 13 complicated analytical result. Instead, we modified Eq. 4 to include sub-stages within 14 stages, by assuming small differences in maturation rates among sub-stages. However, 15 the solution in Eq.4 cannot be simply transformed into a general case for the system to 16 have multiple sub-stages, because in such case the denominator of the solution in Eq.4 17 becomes zero, mathematically, as $\sigma_{ij} = 0$ when *i* and *j* were redefined for sub-stages in each stage, such that $\sigma_i = \sigma_i$. Therefore, we implemented the sub-stages for a 18 given stage *a* by adding and subtracting a small constant (ε) to γ_a such that $\varepsilon \ll \gamma_a$. 19 20 For example, separating γ_a into three sub-stages would involve splitting γ_a among the 21 three sub-stages, such that maturation rates were $\gamma_a => [\gamma_a - \varepsilon, \gamma_a, \gamma_a + \varepsilon]$. Then we estimated γ_a using the modified Eq.4 fitting to data from Uye et al. (1983) for small 22 23 values of ε . 24 25 References 26 Ackleha AS, de Leenheerb P (2008) Discrete three-stage population model: 27

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1 <u>Tables</u>

Table 1 Meaning of mathematical notations

Notation Description

n ₁	number of eggs
n_2n_6	number of individuals in the five naupliar stages
$n_7 n_{12}$	number of individuals in the five copepodid stages
$\beta(T)$	Fertility rate (rate of egg production) in adult females as a function of
	temperature
q	average proportion of ovigerous females in the adult population, assumed
	to be a constant value of 0.61 (Liang and Uye 1997b)
$\mu_i(T)$	rate of mortality in stage <i>i</i> as a function of temperature
$\gamma_i(T)$	rate of maturation of individuals surviving to stage i as a function of
	temperature
A	12x12 linear matrix composed of maturation, mortality and fertility rates,
	such that $dn(t)/dt = An(t)$, where <i>n</i> are vectors of stage classes
Т	temperature
R_0	net reproductive rate
f_m	maximum rate of fertility
f_l	fertility at the lowest temperature
W	shape parameter that accounts for the depression in fertility rate at low
	temperatures
b	lag parameter to relax the assumption that the fertility rate curve
	otherwise intercepts y-axis at the origin
$z_a(t)$	proportion of individuals at each stage a
d_a	stage (a) duration times random variable
\overline{d}_{a}	mean stage (a) duration times

D_a	stage (a) development time distribution
\overline{D}_a	mean stage (a) development times
$lpha_{_a}$	constant that varies with stage a in maturation function of temperature
	$\gamma_a(T) = (T-1)^{1.8} / (\alpha_a - \alpha_{a-1})$ where $\alpha_0 = 0$ derived from Belehradek's function
ϕ	scale parameter in $Sv = \exp(-\phi a^{\chi})$
χ	shape parameter in $Sv = \exp(-\phi a^{\chi})$
K	are parameters from mortality as a quadratic function of temperature
	$\mu(T) = \kappa_2 T^2 + \kappa_1 T + \kappa_0$

Table 2 Model comparisons for cases k=1, 2 and 3 in Eq.4.

	Model	RSS	LL	(LL/LLmax)	Chi ²	Deg	AIC	ΔΑΙϹ	<i>p</i> -of Chi ²
	k=3	0.57	120.56	0.00	0.00	14	-213.12	0.00	
	k=2	1.04	108.83	-11.73	23.45	13	-191.67	21.45	1.28E-06
	k=1	1.88	97.29	-23.27	46.54	12	-170.58	42.54	7.83E-11
4	**LL-Log likelihood, LLmax-Maximum Log likelihood								

Stage	$\gamma_a(20^0C)$	Stage duration time	Stage Development time	α_{a}
		$\overline{d}_a(20^0C)$	$\overline{D}_a(20^0 C)$	
		(days)	(days)	
e	3.64	0.27	-	55.01
n2	2.53	0.40	0.67	134.21
n3	1.05	0.96	1.63	325.81
n4	0.87	1.16	2.78	557.40
n5	0.65	1.53	4.31	864.01
n6	0.81	1.23	5.54	1110.77
c 1	0.54	1.84	7.39	1479.68
c2	0.58	1.73	9.12	1827.22
c3	0.60	1.66	10.78	2159.64
c4	0.40	2.48	13.26	2656.81
c5	0.29	3.48	16.74	3353.02
сб	_	4.84	21.57	4321.76

Table 3 Stage maturation, duration, and development rates at 20⁰C, and coefficient 2 α_a calculated for each stage *a* for *k*=1.

Table 4 Estimation of ϕ and χ in $Sv = \exp(-\phi a^{\chi})$ at different temperatures

Temp								
(⁰ C)	10.60	14.30	16.70	20.20	21.50	22.30	25.60	27.40
ϕ	0.02	0.01	0.00	0.00	0.13	0.53	0.00	0.10
χ	2.69	2.26	7.87	2.93	1.43	0.94	29.24	1.56
RSS	0.05	0.11	0.09	0.02	0.06	0.01	0.09	0.03

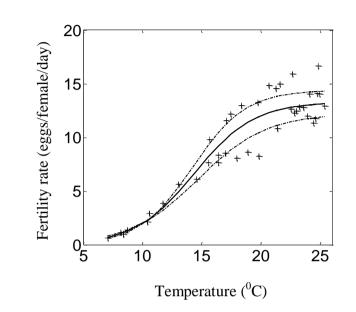
^{6 **}RSS-Residual sum of squares

1 Figures

a) Sigmoidal model

2

3



4 5

b) Linear model

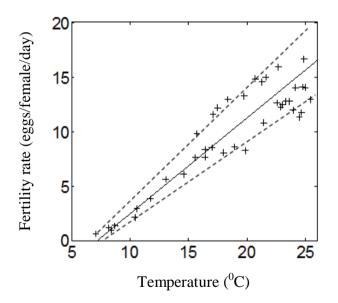


Fig. 1 Rate of fertility of adult females at different temperatures comparing sigmoidal
model with linear model by Uye et al. (1983). Dashed lines indicate 95% confidence
intervals.

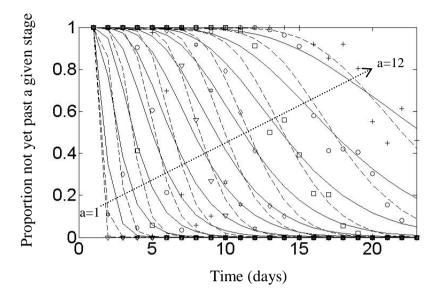
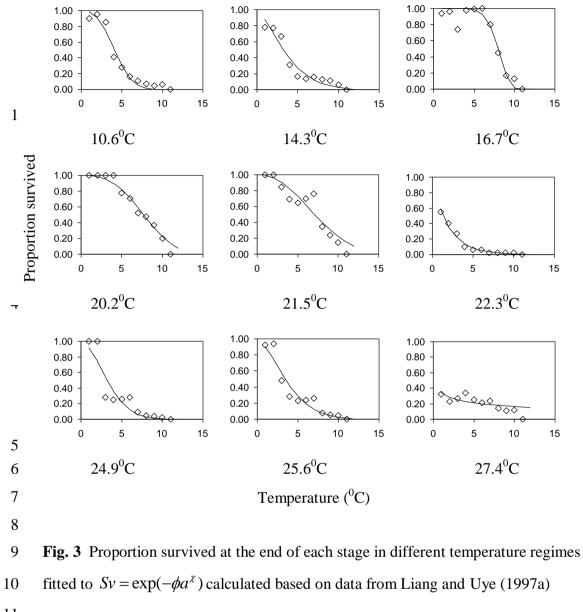
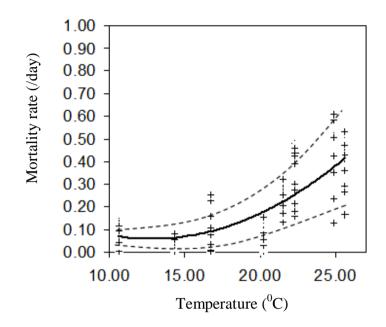


Fig. 2 Proportion of individuals in the population not yet past a given stage *a*

- 4 obtained by fitting Eq.4 to data from Fig.2 in Uye et al (1983). Solid lines are the fits
- 5 for k=1, dashed lines are the fits for k=3.





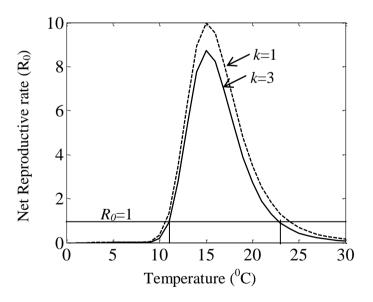


2 Fig. 4 Quadratic model of daily mortality rates as a function of temperature,

3 estimated for data where all stages are pooled. Parameter values for mortality rate

4 model are
$$\kappa_2 = 0.0022$$
 /day, $\kappa_1 = -0.0563$ /⁰C day, $\kappa_0 = 0.4211$ /⁰C² day

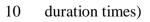






8 Fig. 5 R_0 plotted as a function of temperature (T) for the cases where k=1

9 (exponentially distributed stage duration times), and k=3 (gamma distributed stage



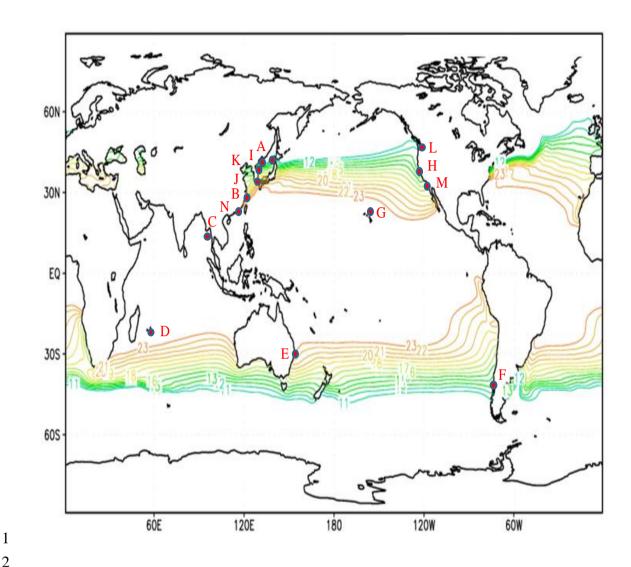


Fig. 6 Range of potentially invasible habitats [from 11° C to 23° C] by *P. marinus* as 3 predicted by our model based on $R_0(T)>1$ for sea surface temperature (T) data 4 5 averaged from year 1971-2000 through NOAA interactive database. Dots are the 6 habitats where P. marinus was collected or has established.

7

8 [References are from Fleminger and Kramer (1988) except *: (A) West coast 9 of Hokkaido, Japan, Sato (1913), Sato Anraku (1953), Walter (1986b); (B) Qing-Chao 10 and Shu-Zhen (1965); (C) Andaman Islands (Pillai 1980); (D) Mauritius (Grindley and Grice 1969); (E) Moreton Bay, Queensland (Greenwood 1977); (F)* Patagonian 11 12 Waters, Southern Chile (Jones, 1966; Grindley and Grice, 1969) from Hirakawa (1986); (G) Oahu, Hawaii (Jones 1966) (Carlton 1985)*; (H)* San Francisco Bay, 13 14 California (Ruiz et al. 2000); (I) Peter the Great Bay (Brodsky 1948, 1950); (J) Chiba 15 (1956), Tanaka (1966), Tanaka and Huee (1966), Walter (1986b); (K) Brodsky (1948, 16 1950); (L)* Elliot Bay, Puget Sound, Washington (Cohen 2004), USGS; (M) USGS;

17 (N) Shen and Lee (1963).]