

## Motivation

For robots to collaborate with humans and react to unwanted situations in production environment. To prevent damage and injury with machines using optical text recognition (OCR) programming.



Figure 1: Robot working alongside humans in manufacturing setup (Universal Robots).



Figure 2: Assessing the VF 2TR\* in the LIMDA lab (University of Alberta).

## Objective

- To assess different machine learning algorithms for text recognition used in manufacturing. Implement and test a neural network against a dataset of
- handwritten examples of characters in the English alphabet.

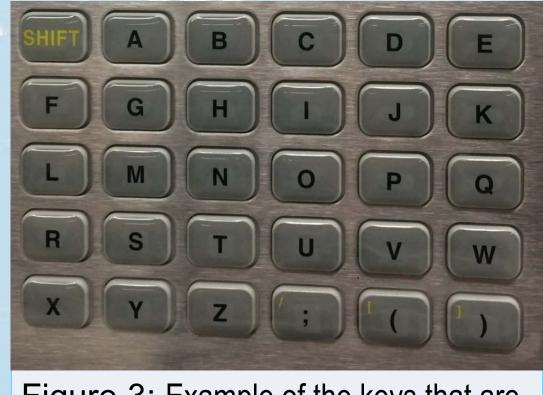
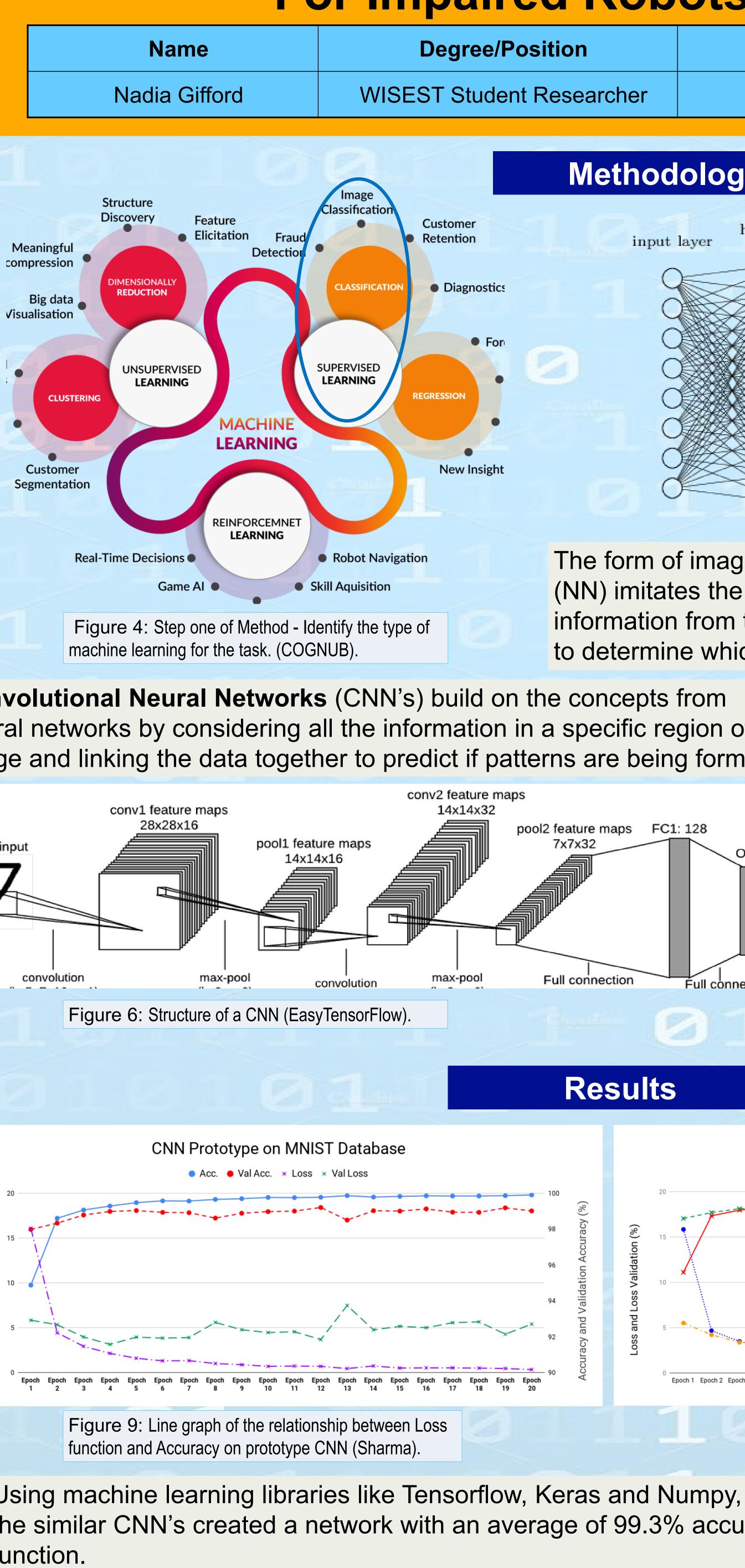
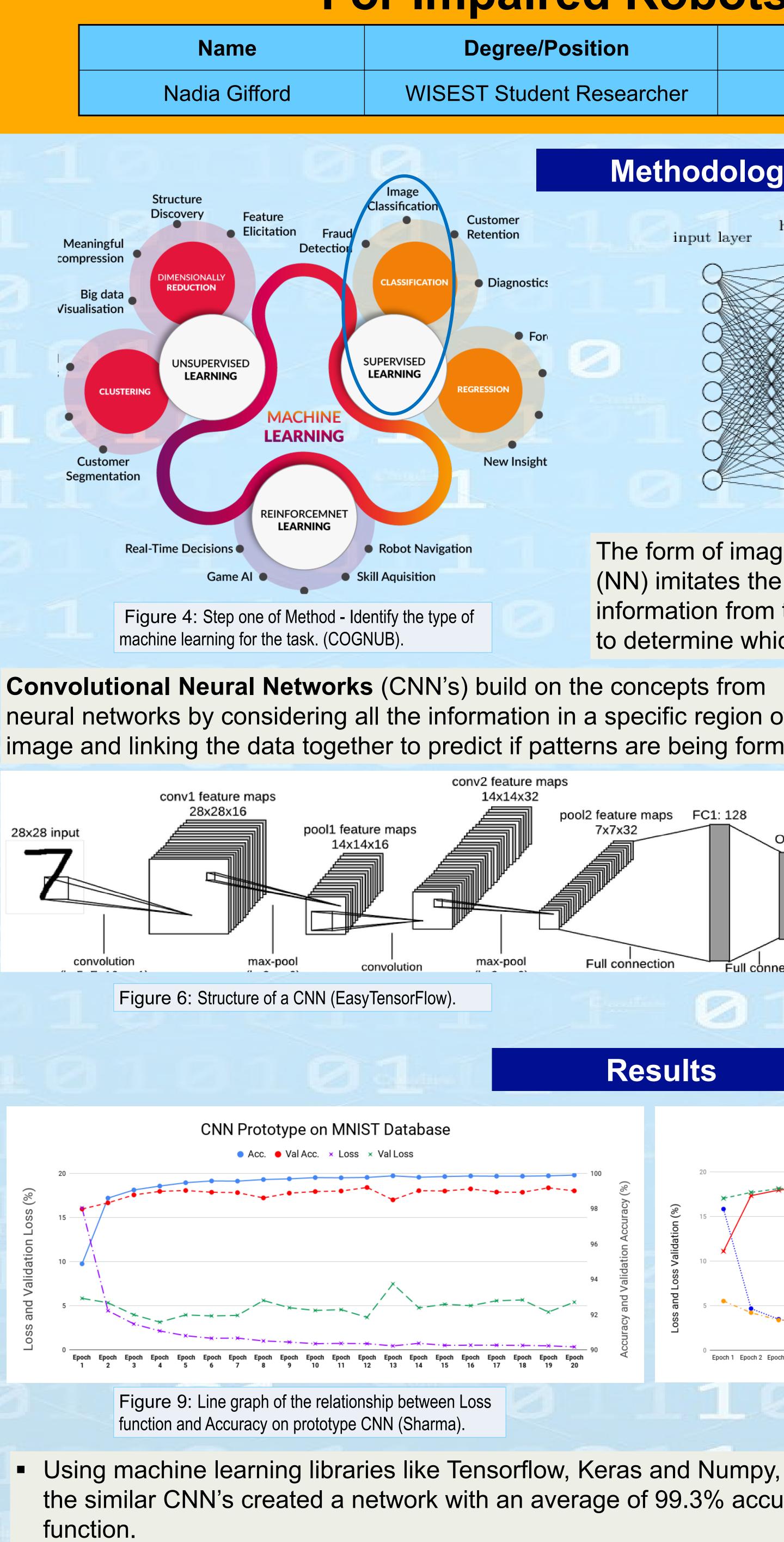


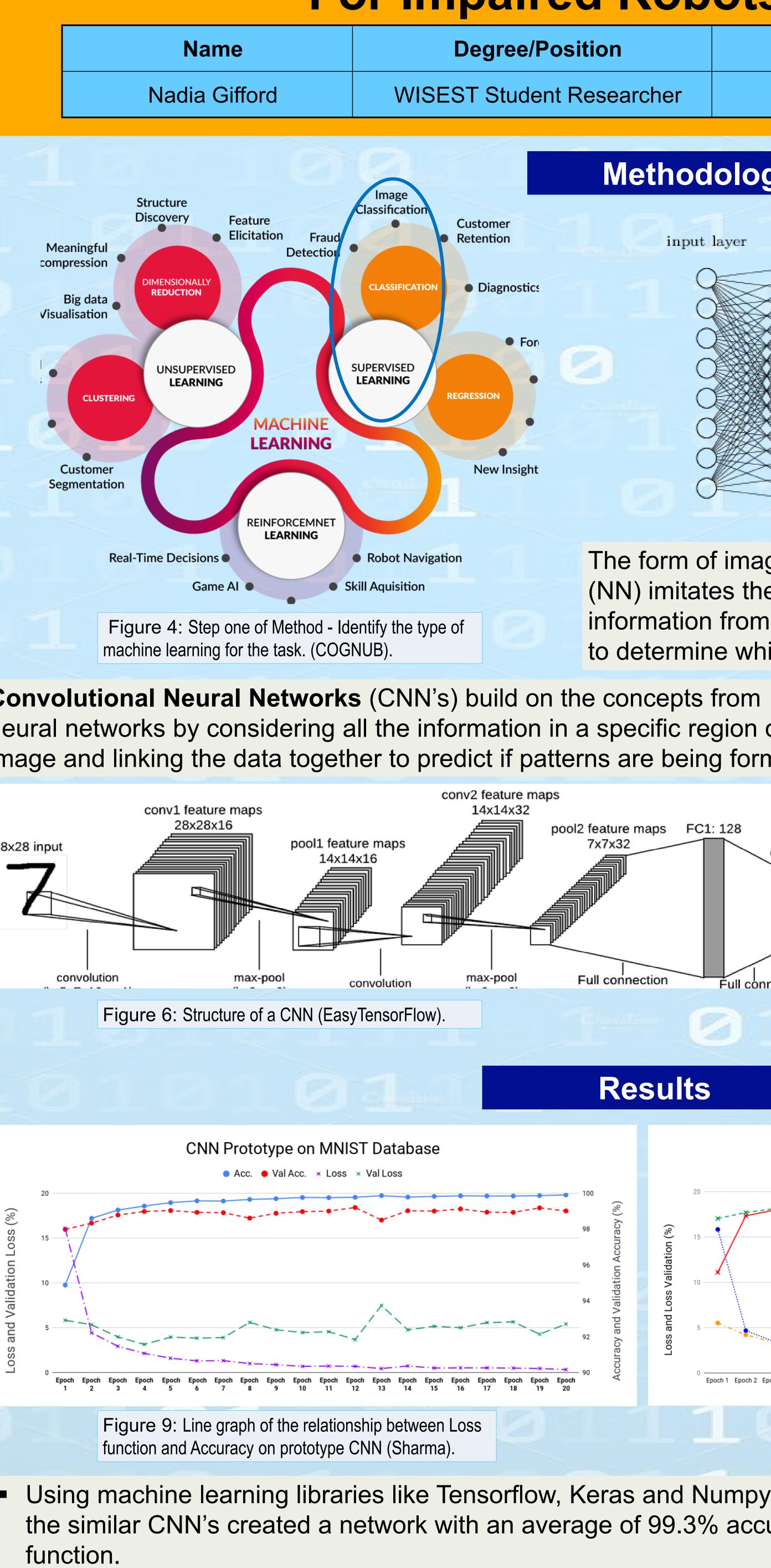
Figure 3: Example of the keys that are desired to be recognized.

\*The VF 2TR is a subtractive manufacturing machine with Computer Numerical control (CNC).











## **Text Recognition and Machine Learning: For Impaired Robots and Humans**

The learning curve of the networks both prove that improvement lev less epochs needed for adequate results means less time wasted r



Laboratory of **Design and Automation** 

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nection MNIST dig	its used to test networks.	the dataset used on final network (Patel).	
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<ul> <li>Final CNN Results</li> <li>Loss          <ul> <li>Val Loss × Acc. × Val Acc.</li> </ul> </li> </ul>			
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Figure 10: Line graph of the relationship between Loss function and Accuracy on final CNN (Patel).			
<ul> <li>, the slight variations in layer variables between</li> <li>, the slight variations in layer variables between</li> <li>, Park. S. ( stick/ . Patel. S. Retrieved . Sharma, J DataCarr</li> </ul>			
vels out between 10-15 epochs (training tests), running tests.			
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